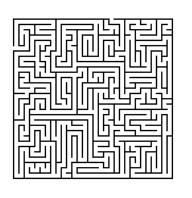
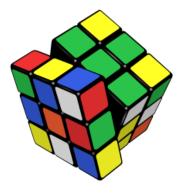
### Where are we in CSCI 450?

Now leaving: sequential, deterministic reasoning

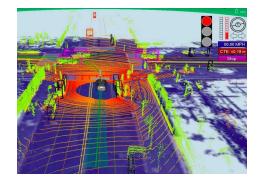




8			4		6			7
						4		
	1					6	5	
5		9		3		7	8	
				7				
	4	8		2		1		3
	5	2					9	
		1						
3			9		2			5



Entering: probabilistic reasoning and machine learning











Probability: Review of main concepts (Chapter 13)

## Making decisions under uncertainty

- Let action A<sub>t</sub> = leave for airport t minutes before flight
  - Will A<sub>t</sub> succeed, i.e., get me to the airport in time for the flight?
- Problems:
  - Partial observability (road state, other drivers' plans, etc.)
  - Noisy sensors (traffic reports)
  - Uncertainty in action outcomes (flat tire, etc.)
  - Complexity of modeling and predicting traffic
- Hence a non-probabilistic approach either
  - Risks falsehood: "A<sub>25</sub> will get me there on time," or
  - Leads to conclusions that are too weak for decision making:
    - A<sub>25</sub> will get me there on time if there's no accident on the bridge and it doesn't rain and my tires remain intact, etc., etc.
    - $A_{1440}$  will get me there on time but I'll have to stay overnight in the airport

## Making decisions under uncertainty

Suppose the agent believes the following:

```
P(A<sub>25</sub> gets me there on time) = 0.04
P(A<sub>90</sub> gets me there on time) = 0.70
P(A<sub>120</sub> gets me there on time) = 0.95
P(A<sub>1440</sub> gets me there on time) = 0.9999
```

- Which action should the agent choose?
  - Depends on preferences for missing flight vs. time spent waiting
  - Encapsulated by a utility function
- The agent should choose the action that maximizes the expected utility:

```
P(A_t \text{ succeeds}) * U(A_t \text{ succeeds}) + P(A_t \text{ fails}) * U(A_t \text{ fails})
```

## Making decisions under uncertainty

More generally: the expected utility of an action is defined as:

$$EU(a) = \sum_{\text{outcomes of a}} P(\text{outcome} | a) U(\text{outcome})$$

- Utility theory is used to represent and infer preferences
- Decision theory = probability theory + utility theory

## Monty Hall problem

 You're a contestant on a game show. You see three closed doors, and behind one of them is a prize. You choose one door, and the host opens one of the other doors and reveals that there is no prize behind it. Then he offers you a chance to switch to the remaining door. Should you take it?



http://en.wikipedia.org/wiki/Monty\_Hall\_problem

## Monty Hall problem

- With probability 1/3, you picked the correct door, and with probability 2/3, picked the wrong door.
   If you picked the correct door and then you switch, you lose. If you picked the wrong door and then you switch, you win the prize.
- Expected utility of switching:

$$EU(Switch) = (1/3) * 0 + (2/3) * Prize$$

Expected utility of not switching:

$$EU(Not switch) = (1/3) * Prize + (2/3) * 0$$

# Where do probabilities come from?

#### Frequentism

- Probabilities are relative frequencies
- For example, if we toss a coin many times, P(heads) is the proportion of the time the coin will come up heads
- But what if we're dealing with events that only happen once?
  - E.g., what is the probability that Team X will win the Superbowl this year?
  - "Reference class" problem

#### Subjectivism

- Probabilities are degrees of belief
- But then, how do we assign belief values to statements?
- What would constrain agents to hold consistent beliefs?

## Probabilities and rationality

- Why should a rational agent hold beliefs that are consistent with axioms of probability?
  - For example,  $P(A) + P(\neg A) = 1$
- If an agent has some degree of belief in proposition A, he/she should be able to decide whether or not to accept a bet for/against A (De Finetti, 1931):
  - If the agent believes that P(A) = 0.4, should he/she agree to bet \$4 that A will occur against \$6 that A will not occur?
- Theorem: An agent who holds beliefs inconsistent with axioms of probability can be convinced to accept a combination of bets that is guaranteed to lose them money

#### Random variables

- We describe the (uncertain) state of the world using random variables
  - Denoted by capital letters
  - R: Is it raining?
  - W: What's the weather?
  - D: What is the outcome of rolling two dice?
  - S: What is the speed of my car (in MPH)?
- Just like variables in CSPs, random variables take on values in a domain
  - Domain values must be mutually exclusive and exhaustive
  - R in {True, False}
  - W in {Sunny, Cloudy, Rainy, Snow}
  - **D** in  $\{(1,1), (1,2), \dots (6,6)\}$
  - **S** in [0, 200]

#### **Events**

- Probabilistic statements are defined over events, or sets of world states
  - "It is raining"
  - "The weather is either cloudy or snowy"
  - "The sum of the two dice rolls is 11"
  - "My car is going between 30 and 50 miles per hour"
- Events are described using propositions about random variables:
  - R = True
  - W = "Cloudy" v W = "Snowy"
  - $D \in \{(5,6), (6,5)\}$
  - $30 \le S \le 50$
- Notation: P(A) is the probability of the set of world states in which proposition A holds

# Kolmogorov's axioms of probability

- For any propositions (events) A, B
  - $0 \le P(A) \le 1$
  - P(True) = 1 and P(False) = 0
  - $P(A \lor B) = P(A) + P(B) P(A \land B)$ 
    - Subtraction accounts for double-counting
- Based on these axioms, what is  $P(\neg A)$ ?
- These axioms are sufficient to completely specify probability theory for discrete random variables
  - For continuous variables, need density functions

#### Atomic events

- Atomic event: a complete specification of the state of the world, or a complete assignment of domain values to all random variables
  - Atomic events are mutually exclusive and exhaustive
- E.g., if the world consists of only two Boolean variables Cavity and Toothache, then there are four distinct atomic events:

```
Cavity = false \land Toothache = false
Cavity = false \land Toothache = true
Cavity = true \land Toothache = false
Cavity = true \land Toothache = true
```

## Joint probability distributions

 A joint distribution is an assignment of probabilities to every possible atomic event

Atomic event	Р
Cavity = false ∧ Toothache = false	0.8
Cavity = false ∧ Toothache = true	0.1
Cavity = true ∧ Toothache = false	0.05
Cavity = true ∧ Toothache = true	0.05

– Why does it follow from the axioms of probability that the probabilities of all possible atomic events must sum to 1?

## Joint probability distributions

- A joint distribution is an assignment of probabilities to every possible atomic event
- Suppose we have a joint distribution of n random variables with domain sizes d
  - What is the size of the probability table?
  - Impossible to write out completely for all but the smallest distributions

#### **Notation**

- $P(X_1 = x_1, X_2 = x_2, ..., X_n = x_n)$  refers to a single entry (atomic event) in the joint probability distribution table
  - Shorthand:  $P(x_1, x_2, ..., x_n)$
- P(X<sub>1</sub>, X<sub>2</sub>, ..., X<sub>n</sub>) refers to the entire joint probability distribution table
- P(A) can also refer to the probability of an event
  - E.g.,  $X_1 = x_1$  is an event

## Marginal probability distributions

 From the joint distribution P(X,Y) we can find the marginal distributions P(X) and P(Y)

P(Cavity, Toothache)	
Cavity = false ∧ Toothache = false	0.8
Cavity = false ∧ Toothache = true	0.1
Cavity = true ∧ Toothache = false	0.05
Cavity = true ∧ Toothache = true	0.05

P(Cavity)	
Cavity = false	?
Cavity = true	?

P(Toothache)	
Toothache = false	?
Toochache = true	?

## Marginal probability distributions

- From the joint distribution P(X,Y) we can find the marginal distributions P(X) and P(Y)
- To find P(X = x), sum the probabilities of all atomic events where X = x:

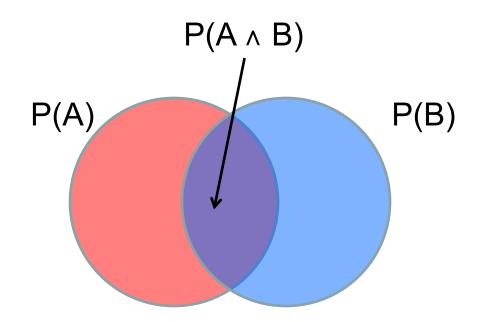
$$P(X = x) = P((X = x \land Y = y_1) \lor \dots \lor (X = x \land Y = y_n))$$
$$= P((x, y_1) \lor \dots \lor (x, y_n)) = \sum_{i=1}^{n} P(x, y_i)$$

 This is called marginalization (we are marginalizing out all the variables except X)

## Conditional probability

Probability of cavity given toothache:

• For any two events A and B, P(A | B) =



## Conditional probability

P(Cavity, Toothache)	
Cavity = false ∧ Toothache = false	0.8
Cavity = false ∧ Toothache = true	0.1
Cavity = true ∧ Toothache = false	0.05
Cavity = true ∧ Toothache = true	0.05

P(Cavity)	
Cavity = false	0.9
Cavity = true	0.1

P(Toothache)	
Toothache = false	0.85
Toothache = true	0.15

- What is P(Cavity = true | Toothache = false)?
   0.05 / 0.85 = 0.059
- What is P(Cavity = false | Toothache = true)?
   0.1 / 0.15 = 0.667

#### Conditional distributions

 A conditional distribution is a distribution over the values of one variable given fixed values of other variables

P(Cavity, Toothache)	
Cavity = false ∧ Toothache = false	0.8
Cavity = false ∧ Toothache = true	0.1
Cavity = true ∧ Toothache = false	0.05
Cavity = true ∧ Toothache = true	0.05

P(Cavity   Toothache = true)	
Cavity = false	0.667
Cavity = true	0.333

P(Cavity Toothache = false)	
Cavity = false	0.941
Cavity = true	0.059

P(Toothache   Cavity = true)	
Toothache= false	0.5
Toothache = true	0.5

P(Toothache   Cavity = false)	
Toothache= false	0.889
Toothache = true	0.111

#### Normalization trick

To get the whole conditional distribution P(X | Y = y)
at once, select all entries in the joint distribution table
matching Y = y and renormalize them to sum to one

P(Cavity, Toothache)	
Cavity = false ∧ Toothache = false	0.8
Cavity = false ∧ Toothache = true	0.1
Cavity = true ∧ Toothache = false	0.05
Cavity = true ∧ Toothache = true	0.05



#### Select

Toothache, Cavity = false	
Toothache= false	0.8
Toothache = true	0.1



#### Renormalize

P(Toothache   Cavity = false)	
Toothache= false	0.889
Toothache = true	0.111

#### Normalization trick

- To get the whole conditional distribution P(X | Y = y)
  at once, select all entries in the joint distribution table
  matching Y = y and renormalize them to sum to one
- Why does it work?

$$\frac{P(x,y)}{\sum_{x'} P(x',y)} = \frac{P(x,y)}{P(y)}$$
 by marginalization

#### Product rule

- Definition of conditional probability:  $P(A | B) = \frac{P(A, B)}{P(B)}$
- Sometimes we have the conditional probability and want to obtain the joint:

$$P(A, B) = P(A | B)P(B) = P(B | A)P(A)$$

#### Chain rule

Product rule:

$$P(A,B) = P(A | B)P(B) = P(B | A)P(A)$$

Chain rule:

$$P(A_1, ..., A_n) = P(A_1)P(A_2 \mid A_1)P(A_3 \mid A_1, A_2)...P(A_n \mid A_1, ..., A_{n-1})$$

$$= \prod_{i=1}^{n} P(A_i \mid A_1, ..., A_{i-1})$$

### Independence

- Two events A and B are independent if and only if
   P(A ∧ B) = P(A, B) = P(A) P(B)
  - In other words,  $P(A \mid B) = P(A)$  and  $P(B \mid A) = P(B)$
  - This is an important simplifying assumption for modeling, e.g., *Toothache* and *Weather* can be assumed to be independent
- Are two mutually exclusive events independent?
  - No, but for mutually exclusive events we have  $P(A \lor B) = P(A) + P(B)$

### Independence

- Two events A and B are independent if and only if
   P(A ∧ B) = P(A, B) = P(A) P(B)
  - In other words,  $P(A \mid B) = P(A)$  and  $P(B \mid A) = P(B)$
  - This is an important simplifying assumption for modeling, e.g., *Toothache* and *Weather* can be assumed to be independent
- Conditional independence: A and B are conditionally independent given C iff
   P(A ∧ B | C) = P(A | C) P(B | C)
  - Equivalently:  $P(A \mid B, C) = P(A \mid C) \text{ or } P(B \mid A, C) = P(B \mid C)$

# Conditional independence: Example

- Toothache: boolean variable indicating whether the patient has a toothache
- Cavity: boolean variable indicating whether the patient has a cavity
- Catch: whether the dentist's probe catches in the cavity
- If the patient has a cavity, the probability that the probe catches in it doesn't depend on whether he/she has a toothache

```
P(Catch | Toothache, Cavity) = P(Catch | Cavity)
```

- Therefore, Catch is conditionally independent of Toothache given Cavity
- Likewise, Toothache is conditionally independent of Catch given Cavity
   P(Toothache | Catch, Cavity) = P(Toothache | Cavity)
- Equivalent statement:

```
P(Toothache, Catch | Cavity) = P(Toothache | Cavity) P(Catch | Cavity)
```

# Conditional independence: Example

- How many numbers do we need to represent the joint probability table P(Toothache, Cavity, Catch)?
  - $2^3 1 = 7$  independent entries
- Write out the joint distribution using chain rule:

```
P(Toothache, Catch, Cavity)
= P(Cavity) P(Catch | Cavity) P(Toothache | Catch, Cavity)
```

- = P(Cavity) P(Catch | Cavity) P(Toothache | Cavity)
- How many numbers do we need to represent these distributions?
  - 1 + 2 + 2 = 5 independent numbers
- In most cases, the use of conditional independence reduces the size of the representation of the joint distribution from exponential in *n* to linear in *n*

#### **Attribution**

Slides developed by Svetlana Lazebnik based on content from Stuart Russell and Peter Norvig, <u>Artificial Intelligence: A Modern Approach</u>, 3rd edition