ottobock.

The new C-Brace®

A physiotherapy training guideline



"The C-Brace[®] restores a feeling of safety so I can walk on uneven terrain again."

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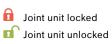
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Risk of falling!

New horizons in orthotics

The microprocessor-controlled C-Brace[®] leg orthosis opens up entirely new possibilities for freedom of movement. The new C-Brace[®] is the world's first mechatronic SSCO (Stance and Swing Phase Control Orthosis) system with 3D motion detection that controls both the stance and swing phase.

The functionality of conventional leg orthoses was previously limited to locking and releasing the knee joint. The C-Brace[®], however, supports the user during the entire gait cycle and adapts to any everyday situation in real time. Flexion under load, negotiating ramps, walking over uneven terrain or going down stairs step-over-step – all this defines a new level of mobility.

And the new C-Brace[®] offers additional advantages: It is lighter than its predecessor and can also be worn under clothing. Users need less effort for walking. New sensor technology makes the entire gait pattern even more dynamic and responsive. Users can also configure joint unit settings using a smartphone app, for instance to change to a mode that makes things such as riding a bike possible, or to read the status (e.g. battery charge level, maintenance) directly on the LED display. Users also benefit from a considerably simplified fitting process. O&P professionals can now fabricate the C-Brace[®] themselves with two different fabrication methods and configure individual user settings using a setup app.

The support of a physiotherapist is indispensable when fitting with the C-Brace[®]. We look forward to working with you to restore a great deal of quality of life for users!

The new C-Brace®



1 Thigh shell

Custom thigh shell made of fibre composite material

2 C-Brace[®] joint unit

The C-Brace[®] joint unit is also referred to as the orthosis joint. Hydraulics in the joint unit simulate the action of the quadriceps femoris muscle.

3 Display

Shows the system status and battery charge level

4 Microprocessor

The microprocessor receives and processes sensor signals and controls walking with the C-Brace[®] in real time

5 3D-Sensor

The 3D sensor in the joint unit measures the current position of the joint every 0.01 seconds

6 Medial support

17KF100=* in four versions

7 Lower leg shell

Custom fabricated lower leg shell made of fibre composite material

8 Ankle joint

A unilateral or bilateral fitting on the ankle is possible, depending on the situation

9 Foot component

Custom fabricated foot component made of fibre composite material

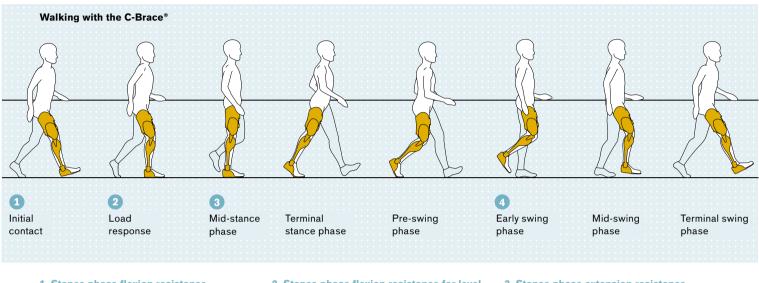
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The

setup app

Individual settings for the user on the tablet

Gait phases with the C-Brace®



1. Stance phase flexion resistance Controlled stance phase resistance supports the knee extensors during heel contact 2. Stance phase flexion resistance for level walking

Additional resistance option supports the musculature as needed upon increased load transfer; time limitation for additional stance phase resistance 3. Stance phase extension resistance Knee extension resistance in the stance phase for smooth, natural movement of the knee joint

4. Swing phase flexion angle

Controls the end of swing phase flexion for an optimised gait pattern

Training

The training takes place in three steps to help users benefit as much as possible from the C-Brace[®] orthotronic mobility system:

- Training without orthosis
 Mobility, coordination, strength
- Training with the C-Brace[®]
 Familiarisation with and use of functions
- Specific training with the C-Brace®
- Geared towards the user and everyday life

Physiotherapy training is an essential element of the fitting and varies depending on the user's physical condition and motivation. The therapy exercises performed without the orthosis are mainly intended to improve mobility and muscle strength.

New options for users

- Flexion under load is now possible for the first time, including when sitting down, descending stairs step-over-step and walking down ramps
- Controlled and stable gait characteristics on uneven terrain
- Individual operating modes can be set by the O&P professional and selected by the user according to the situation, e.g. cycling

Positive effects

- A natural body posture is developed in the course of therapy and helps reduce excessive unilateral physical strain and resulting problems
- Reduced effort required compared to locked orthoses
- Greater sense of security and newfound mobility enhance the quality of life
- Strengthening of previously little-used muscles
- Reduction of muscular atrophies
- Contractures and joint damage caused by immobilisation can be prevented
- Cardiovascular capacity is retained for everyday activities

You as the physiotherapist decide what exercises are suitable under consideration of the user's objectives. The difficulty of the exercises can be increased regularly depending on the user's performance level.

The exercises in this brochure are merely a training guideline and are not intended to be exhaustive.

The fitting process



User







1 Examination and fitting recommendation

Before a final recommendation can be made, you review with the user whether the C-Brace[®] is the appropriate device. The user wears the diagnostic trial orthosis (DTO) for this purpose.

2 Measuring and production

The O&P professional takes the user's measurements, fabricates the plaster negative and positive, and first produces a trial orthosis. This is followed by fabrication of the definitive orthosis using prepreg technology or with Orthopox epoxy resin.

3 Fitting and adjustment

Then comes the trial fitting of the definitive C-Brace[®] orthosis. The O&P professional uses the setup app to configure the system according to the user's needs. The O&P professional can configure a user-defined mode in addition, for example to make cycling possible. You as the therapist should be present during the final fitting and accompany the user's first steps.

4 Gait training and rehabilitation

Training with the C-Brace[®] orthotronic mobility system is an important element of the fitting process. The objectives are to teach the user how to use the system in cooperation with a trained therapist, to build confidence in the C-Brace[®] (load transfer) and to practise the functions that are new to the user (expanded ADLs).

5 Quality and continuous control

Regular service inspections by Ottobock. The medical supply company also verifies the fit and settings of the C-Brace[®] in the course of the inspection.

Medical prerequisites

In principle, a fitting with the C-Brace[®] is suitable for any neurological indication. There are, however, limitations. The functional status of the muscles is a decisive factor.

Indications

- Unilateral or bilateral lower limb paresis or flaccid paralysis, e.g. due to post-polio syndrome, traumatic paresis including paraplegia
- Physical prerequisites such as muscle status, joint mobility and possible axis deviations are crucial and proper control of the orthosis must be guaranteed
- The user must fulfil the physical and mental requirements for perceiving optical/acoustic signals and/or mechanical vibrations
- The existing muscle strength of the hip extensors and flexors must permit the controlled swing-through of the lower limb (compensation using the torso is possible). Passive flexion of the knee joint must be possible.

Contraindications

- Initiating the swing phase is not possible during the test procedure
- Insufficient trunk stability
- Moderate to severe spasticity
- Flexion contracture in the knee and/or hip joint in excess of 10°
- Knee varus/valgus malposition in excess of 10^c
- Leg length discrepancy in excess of 15 cm
- Orthoprosthesis
- Body weight over 125 kg

Definition of terms

Yielding

Yielding is unlimited knee flexion under load against hydraulic resistance (known as stance phase flexion resistance). The hydraulic stance phase flexion resistance simulates the eccentric activity of the quadriceps femoris muscle. Yielding is usually used in combination with descending slopes or stairs step-over-step. For this, the user walks over the flexed knee joint.

Swing phase release: physiological or technical?

The joint unit registers the user's current gait phase by means of sensors and automatically adapts the hydraulic resistance. The physiological swing phase is not influenced by the C-Brace[®]. During the stance phase, the resistance should be increased to give the user a safe stance phase. The hydraulic resistance has to be as low as possible at the beginning of the swing phase to obtain sufficient ground clearance. Five criteria have to be met in the joint unit to trigger the swing phase:

- Forward tilt of the lower leg
- Forward movement of the thigh
- Knee extension
- Extension moment in the knee
- Rollover movement from the heel to the forefoot

When the term "swing phase release" is used in the guideline, this means that the joint unit switches from high stance phase flexion resistance to low resistance.

Stumble recovery

In the first part of the swing phase while knee flexion is increasing, the hydraulic resistance is low. The resistance of the hydraulics automatically increases in the second part of the swing phase, when knee extension is initiated. In case of a stumble, the user is supported by this mechanism and has a chance to use the hands to avoid falling.

Putting on the orthosis



- Apply the orthosis while sitting with the orthosis joint flexed
- Start with the foot component and lower leg shell
- Apply and close the thigh shell

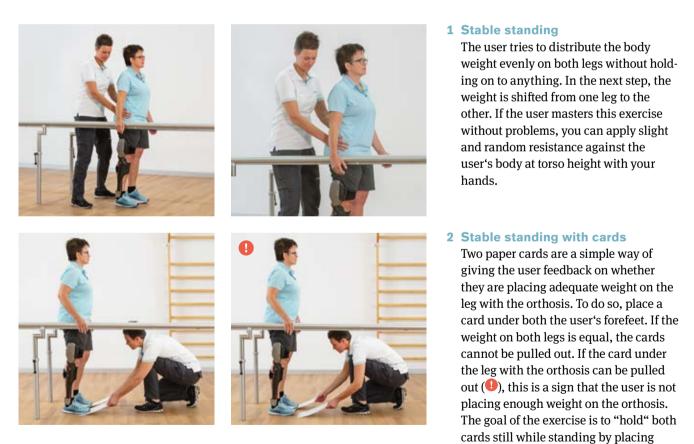


- Close the lower leg shell and foot component
- Put on the shoe (if it is not on the foot component already)
- Stand up and check all closures

Basic exercises

The goal of the initial exercises with the C-Brace[®] is for the user to achieve optimum balance and a symmetrical transfer of weight. The user has to become familiar with the C-Brace[®].

Start each exercise between parallel bars. Using the handrail for support at the outset is recommended. The more confidence the user develops in the C-Brace[®], the less you need to help.



equal weight on both feet.



3 Stable standing with dynamic arm movements

If the user can maintain their body position well, practise dynamic arm movements with them, e.g. "drumming" rapidly with the forearms ("playing percussion"), dynamic movements with two gymnastics batons or reactive exercises, e.g. throwing/ catching a ball or balloon.

Sitting down and standing up

Select a chair with arm supports. Position it so that it will not slide away. Ask the user to distribute their weight evenly on both legs before sitting down.

The configured stance phase flexion resistance brakes knee flexion while sitting down (simulates the eccentric muscular activity of the quadriceps femoris muscle).



1 Sitting down

- Both feet are in line with each other
- Put weight evenly on both legs while sitting down
- Move the upper body forward, the buttocks back towards the back of the chair ("nose towards feet")
- Move the hands to the arm supports
- The arm supports are for safety, but not intended to hold the full weight



2 Standing up

- Both feet are in line with each other
- Bend the upper body forward and stand up with the support of the arms
- The arm supports are for safety, but the user should not push up to a standing position with the arms only
- If possible, also put weight on the orthosis leg while standing up



3 Adjustment

The O&P professional can individually adapt the stance phase flexion resistance to the user using the setup app on the tablet



4 Sitting down with cards

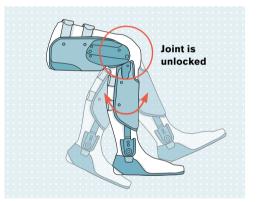
You can also use cards to check proper execution. The user should use the arm supports to help with sitting down at first. Use the cards to check whether equal weight is still being placed on both legs. Weight distribution is optimal if both cards are held securely with the feet while sitting down. If one card (1) can be pulled out easily, the weight distribution still needs to be adjusted.



5 Sitting function

The sitting function is activated automatically when the thigh is close to horizontal and there is no load on the leg with the orthosis. The resistance in the flexion and extension directions is then reduced to a minimum.

- The lower leg can be moved freely while sitting
- The sitting function is also active when sitting with the legs extended



Joint is unlocked

This function can be activated only when the joint unit is in basic mode.

A basic prerequisite is that this function was enabled in the setup app by the O&P professional and activated by the user via the Cockpit app.

Stance phase training

The user has already practised knee flexion under a load while sitting down and has felt the configured stance phase flexion resistance. In situations that normally require the muscle function of the quadriceps femoris muscle, the user will keep using this resistance. To strengthen the user's confidence in the C-Brace[®], stance phase flexion

resistance should be emphasised at the beginning of stance phase training.



1 Building trust

Initially the user stands in the stepping position while holding on to the parallel bars. The leg with the orthosis is in front. Secure and stabilise the user in the area of the knees and hips. As the next step, the user puts weight on the C-Brace[®] and pushes the knee forward into knee flexion. The user feels the resistance against knee flexion in doing so. **Important:** Knee flexion is not limited. This means the user can fully bend the knee. Therefore the knee should initially be bent only as much that it can still be kept stable while standing. Repeat this exercise several times. You can reduce the help provided as the user becomes more confident.



2 Level walking

Once the user is familiar with the basic functions such as initiating the swing phase and stance phase flexion resistance, continue practising and honing their ability to walk on level ground.

Exercise objectives:

- Stride length is appropriate and uniform
- Gait width is appropriate
- The foot, knee and hip move in the sagittal plane (avoid circumduction and raising the hip)



3 Stance phase flexion with support from the therapist

Once the motion sequence can be performed smoothly, the user should try to transfer this to walking between parallel bars. You can provide proximal support at the user's pelvis as they do so. Great emphasis should be placed on practicing the forward motion of the body's centre of gravity.

Also check whether the user is able to control the movement in view of the muscle status.



4 Stance phase flexion while walking Once the user is able to complete the motion sequence well, they have to practice alone between parallel bars with the therapist's supervision and gradually reduce the use of the arms.

Stance phase training







5 Exercises for stride length and gait width

If the gait width is too large, have the user walk between two ropes, sticks or strips of tape on the floor. An appropriate gait width results in a better rollover motion of the foot, which forms the basis for optimal swing phase release by the joint unit. Depending on the previous fitting, the user may tend to take a very large step on the orthosis side. The disadvantage here is that the body's centre of gravity is not shifted over the foot on the orthosis side until very late. The user finds it more difficult to stabilise themselves. If the stride length varies significantly, you can use marks on the floor to provide the user with visual feedback. A metronome or music are also helpful for developing an even walking rhythm.

6 Walking on uneven ground

Once the user feels secure while walking on even surfaces, have them practise walking on uneven ground. The stance phase flexion resistance is highly advantageous for this. The user quickly gains full-surface contact with the sole of the foot, which enables them to better stabilise themselves.









Overcoming small obstacles

Overcoming small obstacles should be trained with the user in order to prepare for the challenges of daily life, such as uneven terrain or curbs. These exercises also promote trust in the orthosis. There are two ways to cross small obstacles: either with swing phase release or a yielding step.

7 Version 1: yielding step

With the user, practice crossing small obstacles with the help of stance phase flexion resistance:

- Position a flat obstacle (such as a wooden board) between the parallel bars
- Step on the obstacle with the heel, provoking knee flexion
- Cross the obstacle with the orthosis joint flexed

8 Version 2:

swing phase release

With the user, practice crossing small obstacles with swing phase release:

- Position a flat obstacle (such as a wooden board) between the parallel bars
- Step on the obstacle with the heel and leave the orthosis joint extended
- The swing phase is initiated automatically when the user crosses the obstacle

Initiating the swing phase

Five criteria have to be met so the user can initiate the swing phase of the orthosis joint:

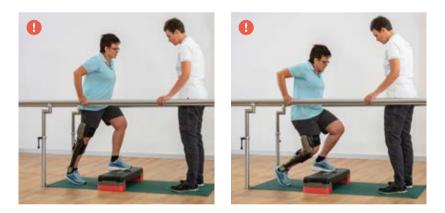
- Forward lean of the thigh
- Forward movement of the thigh
- Knee extension
- Extension moment in the knee
- Rollover movement from the heel to the forefoot



1 Exercise for initiating the swing phase Start the exercise between parallel bars and make sure the user is using their hands for only minimal support. Then place an exercise ball in front of the user. The leg without the orthosis is in front in the step position. To initiate the swing phase, the user kicks the exercise ball using the leg with the orthosis.

It is important for the user to strike the ball from the front and not from the side. The user will expend a great deal of energy at first. However, as time goes by they should learn to do the exercise with as little effort as possible. Reduce the support you give as much as possible. If the exercise goes well, the user should try to apply what they have learned when walking.

Even users who otherwise walk with circumduction can usually activate the hip flexors well during this exercise. If no other option is available, the user can tilt the pelvis to initiate the flexion movement. If the user has difficulties initiating the swing phase, the reasons can usually be found in the stance phase. Stance phase training can help to improve the swing phase.



2 Consciously initiating the swing phase

In order to prepare the user for certain everyday situations and become more familiar with the joint unit's functionality, it is important to practice initiating the swing phase consciously between parallel bars. In certain situations, for example when climbing a step with the non-orthosis leg while the leg with the orthosis remains extended, all swing phase release criteria are met and the swing phase could be initiated unintentionally.

Balance training

In the training that follows (for example on a stable or unstable surface and in motion), the user gains even more confidence while standing. Select the exercises according to dexterity and skill. Make sure the user feels secure. Start each exercise between parallel bars.

Select an unstable surface, such as a rocker board, a wobble board or a soft balance pad. Repeat the previous exercises according to the user's performance.



Exercises on the balance pad



Exercises on the MFTFit Disc



Exercises on the large balance board

Tapping with a yielding step

The following exercises are geared especially towards improving stability in the stance phase. In turn, a focused stance improves swing phase release and thus promotes a more fluid gait. Begin the training between parallel bars.



Skateboard exercises

Initially the user stands on a stable surface. The non-orthosis leg now performs the dynamic part of the exercise, first pushing the skateboard forward and back, then to the side. The user has to stabilise the orthosis leg in flexion / extension / abduction / adduction while doing so. To increase the level of difficulty, these exercises can be performed without holding on.







Reducing auxiliary devices

The goal of training is for the user to become as independent of auxiliary devices as possible, depending on their physical condition.

- The first training sessions take place between parallel bars
- Practise the four-point and two-point gait in the parallel bars
- Enhancement: walk around the outside of the bars with additional support from a crutch
- Enhancement: four and two-point gait with two crutches
- Enhancement: the same with two canes. This increases the level of difficulty as there is less

support from the wrist and forearm; alternatively, use reversed forearm crutches.

- Walking with just one cane is also an option. Be sure to keep an eye on body symmetry in this case; one-sided loads should be avoided.
- Depending on their physical constitution, the user may be able to walk without auxiliary devices



Four-point gait



Two-point gait



 Two-point gait with crutches reversed



Walking with two canes



Walking with horizontal cane



Walking with one cane



Walking without auxiliary devices

Intensive gait training

Every user has their own walking speed. When it comes to everyday situations such as crossing the street, the user should be able to change walking speeds. Start each exercise between parallel bars.

Start by practising a fluid gait at a comfortable speed. Support the user's rhythm by snapping your fingers, clapping, or using a metronome or music.

During the next exercise, you will change walking speeds. Walk next to the user and ask them to keep pace with you while you speed up or slow down. You can once again provide support through clapping or other sounds. Enhance the training by changing directions, walking in circles, doing a figure 8 or going around obstacles. Now combine changes in direction and speed. This improve's the user's flexibility.



Walking with small steps: the user should take as many steps as possible over a defined walking distance.



Walking in a figure 8

Intensive gait training



Reactive training

The goal of reaction training (as simulated in the illustration with a rolling ball) is for the user to have sufficient control to safely stop with the orthosis leg when an obstacle suddenly appears. Example: a dog suddenly runs across the sidewalk.

The user walks a given route, the therapist is positioned low to the ground and rolls a soft ball across the user's path. When the obstacle suddenly appears, the user attempts to slow their stride by means of a yielding step with the orthosis leg. For this exercise, it is advisable to learn the motion sequence in advance under the therapist's supervision.

The training becomes more demanding when you perform all of these exercises on a soft, uneven surface, such as an exercise mat.

Walking backwards

When walking backwards, the user starts the movement with the nonorthosis leg. Using the handrail is highly recommended at the start of the learning phase. No swing phase is triggered in the joint unit while waking backwards since the five initiation criteria are not met.



Walking backwards on level ground



• Walking backwards with yielding step The therapist can support the user while learning to walk backwards with a yielding step. The therapist can secure the foot of the orthosis leg to the floor using their own foot.

This is because the user needs to learn that the entire foot has ground contact during the yielding step, and that flexion in the orthosis joint is possible. Once the user is able to do this well, they practice the motion sequence alone.

Training on the stepper

You should practise descending stairs step by step to build up the necessary confidence. This training can start between parallel bars or on the stepper.

Basic exercises on the stepper

With the set stance phase flexion resistance, the C-Brace[®] helps the user descend stairs step-overstep by bending the leg with the orthosis. This is a completely new experience, which for many users has not been possible for years. Because the ankle joint in the orthosis does not permit any or only insufficient dorsal extension, only the heel should have contact with the step. This ensures fluid rollover behaviour when descending the stairs. Apply a strip of tape to the user's shoe to facilitate foot positioning. This provides the user with visual feedback; the foot is positioned so that the tape is lined up with the edge of the step. The marker is especially helpful when training on the stairs later. Once the foot is correctly positioned, the user steps down from the stepper with the non-orthosis leg. To do so, the user has to learn to permit knee flexion of the orthosis joint. Here the hydraulics of the joint unit (stance phase flexion resistance) fulfil a function similar to the quadriceps femoris muscle by permitting controlled flexion of the orthosis joint under load.

During the motion sequence, make sure

- That the user steps down vertically and does not just "fall" forward in the direction of movement,
- That the user maintains the leg axis: the foot, knee and hip remain in a line.

At first, you can support foot placement and guide the knee during the movement. However, you should gradually reduce your support. Apply a strip of tape to the floor to help the user with the stride length.





Adapting the resistance

If the user has a great deal of difficulty sinking into the orthosis knee joint when walking downhill, the O&P professional should check the stance phase flexion resistance.

If the resistance is too high or too low, this could make the user insecure.

Possible clinical indications that stance phase flexion resistance is set too high:

- The user sinks into the orthosis knee joint very poorly; the motion sequence is very halting
- The user has to allow strong exterior rotation of the leg when flexing it under a load



Possible clinical indications that stance phase flexion resistance is set too low:

- The user sinks into the orthosis joint very quickly
- The user feels very insecure and holds on to railing very tightly

The therapist and technician must set the stance phase flexion resistance to suit the user's current training condition and phase of training. With an initial fitting, the settings should be checked regularly at the outset.

Training on the stepper

Mistakes

Descending stairs with the C-Brace[®] orthotronic mobility system often requires a lot of practice and trust for the user. They are usually not able to put a load on the leg with the orthosis under flexion because of their previous fitting. The following five mistakes may be made. For all of these mistakes, repeat the exercise with the correct foot position.



Foot too far back

The danger with this mistake is that the swing phase may be initiated unintentionally. This is very dangerous on stairs and definitely must be avoided.



Foot too far forward When the foot is placed too far forward on the edge of the step, it may slide off the step under load, which results in a risk of falling.



"Angling"

In this example, the user does not have the confidence to put weight on the leg with the orthosis. The user attempts to reach the safety of the floor with the sound leg. Here the great risk is once again that the swing phase may be initiated unintentionally, since the orthosis joint is over-extended.



• Hip extended In this example, the user extends the hip due to fear. The swing phase release criteria are met. There is a great risk of initiating the swing phase on the stairs.



body Once again due to fear, the user simply lets herself fall forward. The criteria for the swing phase are met, so that a subsequent swing phase could be initiated unintentionally.

Training on the stairs

Continue training on the stairs. First repeat the same training steps you performed with the user between parallel bars. Then increase the number of steps. Then place special emphasis on maintaining the leg axis, the foot position, the user's safety and a fluid motion sequence.



Ascending one step at a time



Ascending step-over-step

Ascending stairs

There are two ways to ascend stairs with the C-Brace[®]: one step at a time, or step-over-step. Only users who meet certain muscular prerequisites (sufficient knee and / or hip extension) can ascend stairs step-over-step.

Training on the stairs

Descending one step at a time

When descending stairs, the user starts with the contralateral leg. The focus of the exercise is foot placement.

As with the previous exercises on the stepper, a strip of tape serves as useful visual feedback.





Foot position Assist the user with correct foot positioning.





Assistance with the foot position



Securing at the pelvis and knee



Support with flexion under load



Descending step-over-step Once the user is confident enough on the stairs, descending stairs step-over-step without assistance by the therapist is the final stage and crowning discipline. Note that users always use the handrail for safety reasons when taking the stairs.

Training on the ramp

The user can negotiate ramps of various inclination angles with the C-Brace[®]. Stance phase flexion resistance provides support so the user can bend the leg with the orthosis under load. As previously on the stairs, the user has to relearn this motion sequence.



Important: Using the handrail is mandatory for safety reasons.

Ascending a flat and steep ramp

With the C-Brace[®] orthotronic mobility system, the user can ascend a ramp using swing phase release. Walking is equivalent to walking on even ground. Depending on how strong the extensor chain in the user's leg is, either long or short steps can be taken with the orthosis leg.

Training on the ramp

Walking techniques for descending

There are two different walking techniques for descending a flat ramp: With version 1, the user initiates a normal swing phase in the orthosis joint similar to walking on level ground.

With version 2, the user has to flex the orthosis joint under load. Always check:

- That the leg axis is maintained
- That the trunk is upright
- That the line of vision is to the front
- Walking step-over-step

Users can negotiate steep ramps only using stance phase flexion resistance (version 2). Train with various walking speeds: small steps at a lower speed and larger steps at a higher speed.



Descending a flat ramp

It is important for the user to practice both walking techniques on the flat ramp. Descending with swing phase release usually occurs automatically (version 1). Descending with the yielding step (version 2) is more difficult and takes practice. In this picture, the user is practicing the yielding step.



Various kinds of support help the user gain confidence when descending.



When carrying the exercise ball, the user does not see their feet. That makes walking more difficult and the user learns to fully trust the orthosis.

Descending a steep ramp

Safely descending a steep ramp is possible only with the help of a yielding step. That means consciously sinking into stance phase flexion resistance during the stance phase.

Support from the physiotherapist for safety is very important on the steep ramp at the outset. As on the stairs, users were not able to descend a ramp step-over-step with their previous fitting and have to relearn the motion sequence.



Important: Using the handrail is mandatory for safety reasons.



One of the therapist's hands is positioned on the user's pelvis. The other hand secures and controls the flexion of the orthosis joint on the lower leg orthosis shell.



 Gradually reducing support
 Once the user has attained sufficient confidence, the support can be gradually reduced. The goal is for the user to descend the ramp independently.

Stance function

The stance function is a functional supplement to the basic mode. This makes it easier for the user to stand for a longer time. The joint is locked at a flexion angle between 5° and 65°.

- If the stance function is not enabled by the O&P professional in the setup app, users cannot activate or deactivate it independently using the Cockpit app
- This function can be executed only when the joint unit is in basic mode
- It is not activated in the sitting position

There are two different stance functions: Intuitive stance and manual stance.

Intuitive stance function on level ground

To activate intuitive stance, the user has to let the orthosis joint come to rest in the flexed position (between 5° and 65°). Then the C-Brace® is locked in the flexion direction. As soon as the user moves the orthosis joint again, the resistance immediately decreases again gradually to the stance phase flexion resistance setting and the stance function is terminated.

The joint unit activates or deactivates the stance function automatically!

Intuitive stance on the ramp

When the user stops on a steep ramp, the orthosis joint comes to a halt. The orthosis joint is slightly flexed and intuitive stance is activated automatically. The user can put weight on the orthosis side, providing relief for the non-orthosis leg.





Version 1 Taking a step with the orthosis leg immediately deactivates the stance function.



Version 2

By taking a step with the contralateral leg, stance phase flexion resistance is automatically used so a controlled yielding step forward can be taken.

Deactivating the stance function There are two ways to deactivate the stance function again. Practicing both versions with the user is highly recommended for safety reasons.





Mistakes

For a fluid motion sequence during the rollover movement, the user should avoid active hip and knee extension. The five swing phase release criteria may be met and a swing phase could be initiated. This bears a considerable safety risk and should definitely be avoided.

Stance function

Manual stance function on level ground

Activating the manual stance function requires the same procedure as for intuitive stance. Allow the leg with the orthosis to come to rest between 5° and 65° of flexion. However, the manual stance function is automatically deactivated again only through extension in the orthosis joint or by repositioning the leg (e.g. taking a step).

Manual stance function on stairs

With this execution, the user is able to deactivate manual stance correctly. Since the user starts with the orthosis leg (repositioning the leg), the manual stance function is deactivated automatically and stairs can be descended safely.









Mistakes

In this incorrectly executed and dangerous example, the user attempts to deactivate the manual stance function by taking a yielding step. **Important:** Please practice consciously with the user! To deactivate manual stance, the orthosis joint has to be extended or the entire leg must be repositioned.



Ground transfer





Kneeling

Kneeling with the C-Brace[®] is no problem. To do so, the user positions themselves in the step position with the orthosis leg in front. Using the resistance, the user goes into the half kneeling stance. Using two chairs is recommended to learn this motion sequence.

Standing-to-ground transfer

The series of images shows one way to get from standing to the floor and back with the C-Brace[®] and the leg extended using the help of a chair. This sequence can be adapted individually by the therapist or user.



The next series of photos shows a way to get from a standing position to the floor and back with the C-Brace® without using auxiliary devices. This sequence can be individually adapted, as for the standing-to-floor transfer with the leg extended and a chair.





• The sitting function is activated when sitting with the legs extended.







MyModes

Basic mode

Basic mode is intended for daily use. The parameters configured by the O&P professional describe the dynamic and safe behaviour of the C-Brace® in the gait cycle. These parameters act as basic settings for automatically adjusting the resistance behaviour to the current motion situation (e.g. walking on level ground, ramps, slow walking speed). The stance function and/or the sitting function can also be activated/deactivated.

Training mode

In training mode, the joint is locked in the stance phase and no stance phase flexion is possible. Swing phase release is possible as in basic mode. In this mode, stairs or ramps can be descended only one step at a time.

- 1) Open the Cockpit app and select training mode. A confirmation signal sounds to indicate the switch to training mode.
- 2) The joint unit is locked in the stance phase, and the leg with the orthosis can swing forward freely in the swing phase.

The support of stance phase flexion resistance for sitting down is not available in this mode.



Activating training mode using the Cockpit app



Joint unit locked in the stance phase

Freeze position

In this mode, C-Brace[®] users can freeze the joint unit in any position, which means locking the joint unit completely. Then it cannot be moved in either flexion or extension direction.

This may for instance be used for gardening, yoga or strength training, as shown in this example. It is very easy to activate. Place the C-Brace[®] in the desired position, then click the "Freeze position" menu item, confirm, and start training.

After completing the exercise, unfreeze the position with two clicks. To do so, switch to basic mode and click for final confirmation.









MyModes

User defined

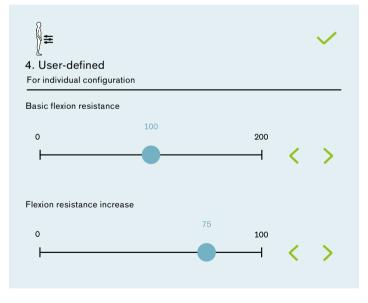
This mode is intended for specific motion patterns or postures (such as bowling or cycling). The O&P professional can configure this MyMode individually using the setup app on the tablet. Users can make minor changes directly using the Cockpit app.

With the setup app, the O&P professional can change the "Flexion resistance increase" and "Basic flexion resistance" in the 4th MyMode "User defined".



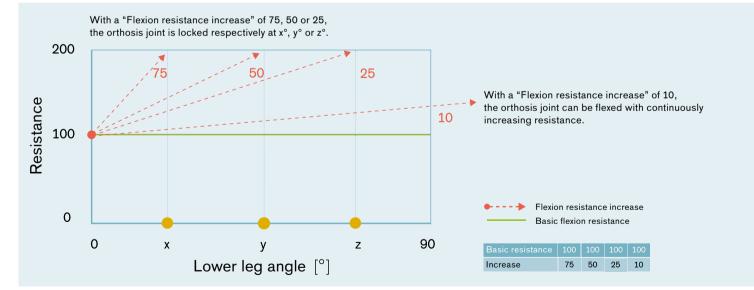
"Basic flexion resistance" parameter

This parameter is used to set the basic resistance at the start of flexing the orthosis joint. The higher the value, the greater the resistance against flexion.



"Flexion resistance increase" parameter

This parameter is used to set the increase in the flexion resistance (starting from the parameter "Basic flexion resistance") while flexing the orthosis joint. The flexion resistance increases continuously along with the flexion angle until the orthosis joint locks at a certain flexion angle. Thus the flexion angle at which the orthosis joint locks depends on the settings for the parameters "Basic flexion resistance" and "Flexion resistance increase".









Example: bowling

For bowling, the recommended configuration of the "Basic flexion resistance" and "Flexion resistance increase" is so that the flexion resistance increases continuously with increasing knee flexion, until the orthosis joint locks at the desired flexion angle.



Example: ergometer In this example of the 4th MyMode for training on the ergometer, both the "Basic flexion resistance" and "Flexion resistance increase" are zero.



Important: Directly before getting off, basic mode should be activated using the Cockpit app.





Outdoors

Training should be moved out of doors as soon as possible. Design the training according to the work and family situation, and the user's recreational activities. Initially use the same auxiliary devices during outdoor training as you did indoors. If the user requires only balance support, Nordic walking poles are a good option.

The goal is for the user to move about safely both indoors and outdoors. Everyday life offers many challenges that have a different effect on training compared with indoors. Outdoor training offers a very good indication of whether the orthosis settings are appropriate for the user.

Practise

- Walking on different surfaces
- Changes in direction
- Changing walking speed
- Overcoming obstacles
- Walking on slopes of varying inclines
- Walking up and down stairs



Ascending a ramp



Descending a ramp



Walking down a steep meadow



 Taking a walk on a gravel path while engaged in conversation



Wooden bridge

Activities of daily living

After successful training, activities of daily living should no longer constitute an obstacle for the user. Whether moving about within the office, taking a leisurely walk or attending an after-work event at a bar, the C-Brace[®] supports the user in all life situations.



Opening a door by stepping back



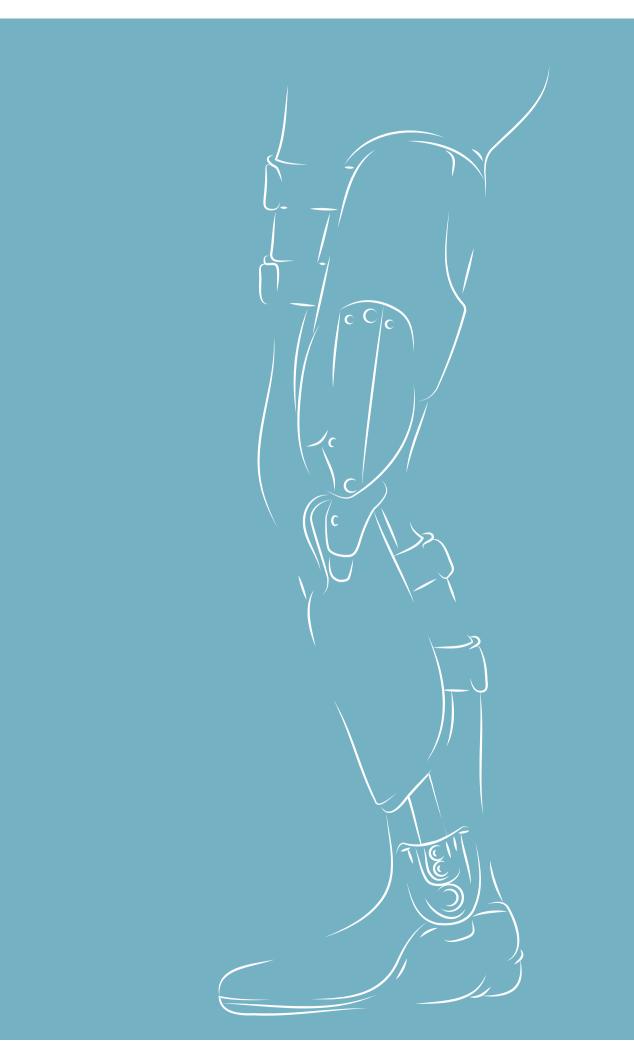




• Talking on the telephone while taking a walk on a gravel path



 Intuitive use of the stance function in conversation at the bar



Notes

Notes

Please contact us if you have any further questions or would like more information.