Applanix POS AV 510

Immediate answers from airborne direct georeferencing

Applanix® POS AV® is the foremost commercial GNSS-Inertial solution for airborne direct georeferencing. Used with digital cameras, film cameras, LiDAR systems, SAR systems and digital scanners, Applanix POS AV precisely measures aerial sensor position and orientation hundreds of times each second, accounting for all motion variables at the exact moment of data capture. In real time or refined in post-processing with the highly productive Applanix POSPac™ Mobile Mapping Suite (MMS) software, data is used to accurately georeference sensor data to the Earth or local mapping frame without ground information, eliminating time-consuming aerotriangulation steps. Applanix POS AV is ideally suited to support precision mapping work, especially in inhospitable environments and in rapid response capacities where ground control data may be unavailable or physically impossible to collect.

Applanix POS AV integrated precision GNSS with inertial technology is supported by Applanix industry leading expertise and a continuous dedication to technological innovation. Offering a streamlined and automated data workflow with built-in quality control features, Applanix POS AV improves productivity in all aerial mapping applications.

As Applanix is a Trimble® Company (NASDAQ: TRMB), Applanix POS AV is unique in the marketplace with its ability to receive the Trimble CenterPoint® RTX Correction Service. Using Trimble RTX® correction service, Applanix POS AV delivers significant benefits including higher accuracy and speed, lower cost, more uptime and greater reliability.



Key Features

- High-performance, survey-grade multi-frequency GNSS receiver
- Compact, low-power, lightweight, rugged construction
- High-performance, low profile FAA certified GNSS-L Band antenna
- · Full in-air alignment support
- Embedded Trimble OmniSTAR® SBAS correction service
- Trimble CenterPoint RTX correction service available
- Simple to use and operate with auto-log and auto-start functions
- POSPac MMS post-processing software bundle includes
 Carrier Phase DGPS processing, Integrated Inertial/GNSS processing, and optional photogrammetry tools for EO generation, IMU boresight calibration and quality control



DATASHEET

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PERFORMANCE SPECIFICATIONS

APPLANIX POS AV ABSOLUTE ACCURACY SPECIFICATIONS¹ (RMS)				
APPLANIX POS AV	510 SPS	510 RTX ³	510 PP-RTX ⁴⁵	510M SMARTBASE POST-PROCESSED ⁴
Position (m)	1.5 H	0.05 H	0.03 H	0.02 H
Position (m)	3 V	0.1 V	0.06V	0.05 V
Velocity (m/s)	0.050	0.050	0.005	0.005
Roll & Pitch (deg)	0.008	800.0	0.005	0.005
True Heading ² (deg)	0.070	0.040	0.018	0.018

APPLANIX POS AV RELATIVE ACCURACY	
APPLANIX POS AV	510M
Noise (deg/sqrt(hr))	0.02
Drift (deg/hr) ⁷	0.50

SYSTEM SPECIFICATIONS

COMPUTER SYSTEM					
COMPONENT	DIMENSIONS (L × W × H) mm	WEIGHT (kg)	POWER (incl IMU)	TEMPERATURE	ALTITUDE ⁸ (m)
PCS Standard	169 × 186 × 68	2.4	18-34 Vdc, 59 W Max	-20 °C to +55 °C	0 to 7,620

INERTIAL MEASUREMENT UNIT (IMU)				
TYPE	RANGE	DIMENSIONS (L × W × H) mm	OPERATIONAL TEMPERATURE	WEIGHT (kg)
IMU-86 ⁹	+/- 10g, +/- 490 dps	116 × 116 × 108 (in tophat, provided)	-45 °C to +55 °C	0.98

GLOBAL NAVIGATION SATELLITE SYSTEM (GNSS)			
OPTION	SIGNALS	DATA RATE	
GPS-19	GPS: L1 C/A, L2C, L2E, L5 GLONASS: L1 C/A, L2 C/A, L3 CDMA ¹⁰ GALILEO: E1, E5A, E5B, E5AltBOC, E6 ¹⁰ BeiDou: B1, B2, B3 ¹¹ QZSS: L1 C/A, L1S,L1C, L2C, L5,LEX IRNSS: L5 SBAS: L1 C/A and L5 MSS L-Band: Trimble CenterPoint RTX	5 Hz (raw)	

ETHERNET INPUT/OUTPUT

Parameters	Time tag, status, position, attitude, velocity, track and speed, dynamics, performance metrics, raw IMU data (at IMU rate), raw GNSS data
Display Port	Low rate (1 Hz) UDP protocol output
Control Port	TCP/IP input for system commands
Primary Port	
Secondary PortBuffe	ered TCP/IP protocol output for data logging to external device
LOGGING	
Parameters	Time tag, status, position, attitude, velocity, track and
	speed, dynamics, performance metrics, raw IMU data
	(at IMU rate), raw GNSS data
Media	External: Removable 8 Gbyte Flash Disk (2 supplied)
	Internal: Embedded 4 Gbyte Flash Disk for redundant logging

RS232 NMEA ASCII OUTPUT Parameter

	Position (\$INGGA), Heading (\$INHDT), Track and
	Speed (\$INVTG), Statistics (\$INGST)
Rate	Up to 50 Hz (user selectable)

.....NMEA Standard ASCII messages:

RS232 HIGH RATE BINARY OUTPUT

Parameter	User selectable binary messages:
	Time, position, attitude, speed, track,
	PAV30 output, Yaw Drift Correction
Rate	Up to IMU Data Rate (user selectable)

RS232 INPUT INTERFACES

Parameter	Gimbal encoder input,
	AUX GPS Input (RTK, NavCom
	RTCM104 DGPS Corrections Input
Rate	1 to IMU Data Rate

OTHER I/O

1PPS...... 1 pulse-per-second Time Sync output, normally high, active low pulse Event Input (6) Six time mark of external events. TTL pulses > 1 ms width,

USER SUPPLIED EQUIPMENT

PC for Applanix POS Controller and Operator Client Software

- Atom 1.6 GHz or equivalent (minimum)
- · Intel Graphics media accelerator 500 or equivalent (minimum)
- · 2 GB RAM, 32 GB HDD (minimum)
- Ethernet adapter (RJ45 100 base T), USB Port
- · Windows® 7

PC for Mission Planning and optional Applanix POSPac Post-processing

- Pentium 4 (32 bits) at 2 GHz or equivalent (recommended minimum)
- · 1 GB RAM, 100 GB Free disk space (recommended minimum)
- · 2 X USB 2.0 ports for security keys
- · Internet Access (for installation, DEM download, optional SmartBase processing
- Windows 7
- Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects
- Typical mission profile, max RMS error
- Trimble RTX, typical airborne results, subject to regional coverage. Subscription sold separately
- Post-processed Trimble CenterPoint RTX, typical mission performance. Subscription sold separately
- May require local gravity model to achieve full accuracy
 Attitude will drift at this rate up to a maximum error defined by absolute accuracy in table above
- Unpressurized operation
- These IMUs are exportable worldwide subject to statutory export declarations, and standard restrictions relating to certain international destinations. Contact your Applanix representative for further information
- 10 There is no official version GLONASS L3CDMA or Galileo E6 ICD. The current tracking capability is based on publicly available information. Full receiver compatibility cannot be guaranteed. 11 The firmware of this product is designed for BeiDou B3 compatibility (trial version) and its firmware will be enhanced to fully support such new signal as soon as official ICD becomes available.

Specifications subject to change without notice.

APPLANIX

Canada:

85 Leek Crescent, Richmond Hill, ON Canada I 4B 3B3 T+1-289-695-6000



