

# Trimble APX-20 UAV

## High Performance GNSS-Inertial Solution with Dual IMU

The Trimble® APX-20 UAV is a GNSS-Inertial OEM solution designed to reduce the cost and improve the efficiency of mapping from small Unmanned Aerial Vehicles (UAV). Comprised of small, low power, precision GNSS and inertial hardware components and Applanix® POSPac™ UAV post-mission Differential GNSS-Inertial office software, the APX-20 UAV eliminates the need to survey extensive Ground Control Points (GCP's), and reduces the amount of sidelap required to be flown per flight. The innovative APX-20 UAV features a precision, survey grade GNSS receiver and dual inertial measurement units; one embedded onto the GNSS-inertial board and one as an external unit mounted on the sensor to be georeferenced. With this feature the APX-20 UAV automatically supports integration on gimbaled platforms without requiring an external interface to an autopilot or the mount itself.

### High Accuracy, Extremely Small Package

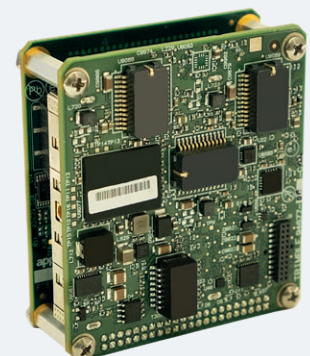
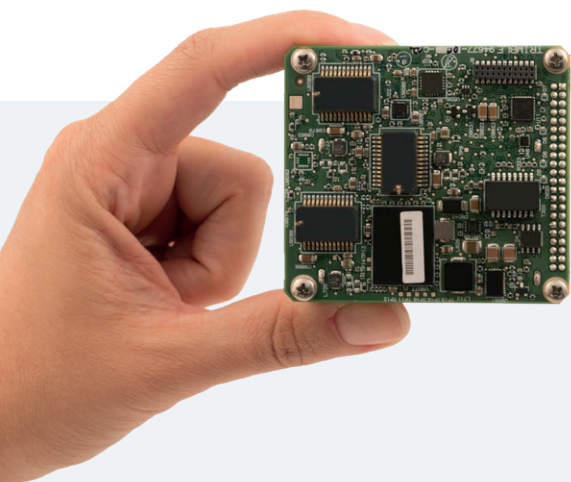
Weighing only 90 grams, and measuring just 60 × 67 × 34 mm for the GNSS-Inertial board, with different types of external IMU sensors, the APX-20 UAV provides unparalleled performance in an extremely small and lightweight package. The APX-20 UAV computes a real-time navigation solution at 100 Hz using its embedded IMU while simultaneously logging the raw IMU data from both the internal and external IMU at 200 Hz for post-processing in POSPac UAV. The highly accurate post-processed position and orientation solutions are used for direct georeferencing of cameras, LiDARs and other sensors.

### The APX-20 UAV brings all the benefits of Direct Georeferencing to UAV platforms:

- Turn your UAV into a professional mapping solution
- Ultra-fast image georeferencing for faster map production and delivery
- Reduced number of ground control points, saving time and money
- Consistent, reliable, highly accurate results
- Increased collection area per flight for greater productivity
- Redundant navigation solution to autopilot for enhanced safety

### Key Features

- High-performance Direct Georeferencing solution for improved efficiency and accuracy of mapping from small Unmanned Aerial Vehicles
  - Reduce/eliminate GCP's
  - Reduce sidelap
  - Accurate LiDAR/Camera georeferencing
  - Seamless workflow with gimbaled platforms
- Compact OEM module complete with survey-grade multi-frequency GNSS receiver and embedded and external IMU
- Applanix IN-Fusion® GNSS-Inertial and Applanix SmartCal™ compensation technology for superior position and orientation performance
- POSPac UAV Differential GNSS Inertial post-processing software for highest accuracy georeferencing
- RTK real-time position for precision landing and real-time mapping applications
- Supports all common RTK corrections such as CMR, CMR+, RTCM



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## High Performance GNSS-Inertial Solution with Dual IMU

### TECHNICAL SPECIFICATIONS

- Advanced Applanix IN-Fusion GNSS-Inertial integration technology
- Dual IMU with solid-state MEMS inertial sensors with Applanix SmartCal compensation technology
- Advanced Trimble Maxwell™ Custom GNSS survey technology
- 336 Channels
  - GPS: L1 C/A, L2C, L2E, L5
  - GLONASS: L1 C/A, L2 C/A, L3 CDMA2
  - BeiDou: B1, B2
  - Galileo: E1, E5A, E5B, E5AltBOC
  - QZSS: L1 C/A, L1S, L1C, L2C, L5, LEX
  - SBAS: L1 C/A, L5
- MSS L-band: Trimble RTX®, Trimble OmniSTAR®
- High precision multiple correlator for GNSS pseudorange measurements
- Unfiltered, unsmoothed pseudorange measurements data for low noise, low multipath error, low time domain correlation and high dynamic response
- Very low noise GNSS carrier phase measurements with <1 mm precision in a 1 Hz bandwidth
- Proven Trimble low elevation tracking technology
- 100 Hz position, roll, pitch and heading output
- IMU data rate 200 Hz for both Internal and external IMU
- Navigation output format: ASCII (NMEA-0183), Binary (Trimble GSOFF)
- Supported Reference input: CMR, CMR+, sCMR, RTCM 2.1, 2.2, 2.3, 3.0, 3.1
- Support for POSPac UAV post-processing software (included)
- No export permit required

### LAN INPUT/OUTPUT

ALL ETHERNET FUNCTIONS ARE SUPPORTED THROUGH DEDICATED IP ADDRESS (STATIC OR DNS) SIMULTANEOUSLY	
TCP/IP and UDP	ASCII and Binary data streaming (Time tag, PPS sync, status, position, attitude, velocity, track and speed, dynamics, performance metrics, GNSS data)
HTTP	Web based Control software (GUI) for easy system configuration and low rate display. Support for all common browsers (IE, Safari, Mozilla, Google Chrome, Firefox)

### SERIAL INPUT/OUTPUT

RS232 LEVEL PORT	
TTL level (3.3 V) port Parameters	ASCII and Binary data streaming (Time tag, PPS sync, status, position, attitude, velocity, track and speed, dynamics, performance metrics, GNSS data), reference input (CMR, CMR+, sCMR, RTCM), configuration messages
OTHER I/O	
PPS (pulse-per-second)	Time Sync Pulse output
Event Input (2)	Two time mark of external events TTL 3.3 V pulses, max rate 50 Hz
Digital I/O (3)	LED drivers with dedicated functionality for systems integrators

### LOGGING

Internal Logging	6 GByte Flash memory
External Logging	USB 2.0 Device port
Parameters	Time tag, status, position, attitude, velocity, track and speed, dynamics, performance metrics, raw IMU data (200 Hz), raw GNSS data

- Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects.
- Typical survey mission profile, max RMS error. Heading error will increase for low speed rotor applications and when hovering.
- Requires base station and radio link, sold separately.
- POSPac UAV, short base line operation.
- Sensor bandwidth (-3 dB amplitude) ~ 50 Hz.
- Sold separately.

INERTIAL MEASUREMENT UNITS (IMU) AIRBORNE					
IMU TYPE	RANGE <sup>5</sup>	TEMPERATURE	POWER	SIZE mm (L x W x H)	WEIGHT (kg)
Internal onboard IMU-59	+/-6g, +/-350dps	-40 °C to +75 °C	n/a	n/a	n/a
External IMU-82	+/-10g, +/-490dps	-40 °C to +85 °C	4.75 to 36 VDC (4W max)	61 x 68 x 65	0.330
External IMU-90	+/-10g, +/-490dps	-40 °C to +85 °C	4.75 to 36 VDC (1.8W max)	39 x 42 x 22	0.070
External IMU-93	+/-10g, +/-490dps	-40 °C to +85 °C	4.75 to 28 VDC (3W max)	50 x 50 x 50	0.180

PERFORMANCE SPECIFICATIONS <sup>1</sup> (RMS ERROR) UNMANNED AIRBORNE VEHICLE APPLICATIONS AIRBORNE				
	SPS <sup>9</sup>	RTK <sup>3,9</sup>	PP-RTX <sup>10</sup>	POST-PROCESSED <sup>4,9</sup>
Position (m)	1.5 - 3.0	0.02 - 0.05	0.03 - 0.06	0.02 - 0.05
Velocity (m/s)	0.05	0.15	0.01	0.010
Roll & Pitch (deg)	0.03	0.025	0.015	0.015
True Heading <sup>2</sup> (deg)	0.10	0.08	0.035	0.035

### PHYSICAL CHARACTERISTICS

#### Board Set

Size <sup>8</sup>	67 L x 60 W x 34 H mm
Weight <sup>8</sup>	90 grams
Power <sup>8</sup>	Wide range input 9-30 V DC, typical power consumption of 4W at room temperature
Connectors	I/O: 44 Pin Header Samtec TMM-122-03-S-5-MW (mating part FCI 90311-044LF) IMU Connector: Molex 503148 (mating part Molex 503149)
Antenna Port	Connector: MMCX receptacle Output Voltage: 3.3 V DC to 5 V DC Maximum Current: 400 mA Minimum Input Signal Strength: 32 dB (>35 dB Recommended)

### ENVIRONMENTAL CHARACTERISTICS

Temperature	-40 °C to +75 °C (Operational) -55 °C to +85 °C (Storage)
Mechanical Shock	+/- 75g Survival
Operating Humidity	5% to 95% R.H. non-condensing at +60 °C
Maximum Operating Limits	515 m/sec 18,000 m

### ADDITIONAL ACCESSORIES<sup>6</sup>

- Evaluation Kit (Development Board)

### POSPAC UAV OFFICE SOFTWARE

- Post-processed Differential GNSS-Inertial SW for APX-15 EI
  - 200 Hz Navigation solution (Position, Velocity, Orientation, Rates, Accelerations)
  - Applanix IN-Fusion GNSS-Integration technology
  - Full support for UAV dynamic models
  - Single Base Differential GNSS-Inertial processing
  - Forward and reverse processing with optimal Smoother with support for Applanix SmartBase™ virtual reference station module<sup>6</sup>
  - Support for PP-RTX<sup>10</sup>
- There is no official GLONASS L3CDMA or Galileo E6 ICD. The current tracking capability is based on publicly available information. Full receiver compatibility cannot be guaranteed.
  - Not including external IMU.
  - Performance based upon external IMU.
  - POSPac UAV/MMS, Post-processed Trimble CenterPoint® RTX, typical mission performance subscription sold separately. The accuracy is subject to quality of GNSS, durational data set, and regional coverage.

Specifications subject to change without notice.

### APPLANIX

**Canada:**  
85 Leek Crescent,  
Richmond Hill,  
ON Canada L4B 3B3  
T+1-289-695-6000

**United Kingdom:**  
Forester's House,  
Old Racecourse,  
Oswestry UK SY10 7PW  
T+44-1691-700500

**USA:**  
15840 FM 529 Rd, Suite 316,  
Houston, Texas, 77095  
T+1-713-936-2990