Applanix POS AVX 310 RTX

CenterPoint RTX powered GNSS-Inertial solutions for reliable, efficient and high-accuracy mapping

The Applanix® POS AVX 310 RTX represents the latest in GNSS-Inertial technology, engineered for maximum efficiency and precision in airborne mapping operations. This advanced solution delivers unparalleled accuracy in both real-time and post-processed environments. It is ideally suited for all airborne sensors, ranging from medium-format and hyperspectral cameras to high-performance LiDAR and SAR systems. The POS AVX 310 RTX substantially reduces operational costs by eliminating reliance on ground infrastructure, thereby significantly boosting airborne mapping productivity.

The Applanix POS AVX 310 RTX is designed for reliable, efficient, and high-accuracy mapping. This state-of-the-art system features a robust enclosure integrating a high-precision dual GNSS receiver, an external inertial sensor unit (IMU Type 117), and advanced data logging capabilities. It provides comprehensive interface support for seamless integration with diverse airborne mapping sensors and flight management systems.

The Applanix POS AVX 310 RTX is fully supported by Applanix POSPac™ Complete, our powerful, factory-enabled GNSS-Inertial processing software. This industry-leading suite incorporates the advanced Applanix IN-Fusion®+ with PP-RTX technology for supreme productivity.

Cost effective and high performance

The Applanix POS AVX 310 RTX delivers a superior Direct Georeferencing solution, significantly enhancing the efficiency and accuracy of mapping operations. It is specifically designed for integration with medium format digital and hyperspectral cameras, as well as LiDAR sensors. By leveraging POSPac Complete, this solution offers substantial operational advantages, including:

- · Operating without the necessity of a base station
- Minimizing and often eliminating the need for Ground Control Points (GCPs)
- · Comprehensive support for camera payload calibration
- Enabling reduced sidelap coverage in mapping projects

Key Features

- Optimal Productivity:
 Significantly boost operational efficiency by minimizing reliance on ground infrastructure and reducing or eliminating the need for Ground Control Points (GCPs).
- Centimeter-Level Accuracy:
 Achieve uncompromised real-time and post-processed centimeter-level position accuracy combined with high-accuracy orientation, powered by Trimble RTX® technology.
- Integrated Applanix IN-Fusion+:
 Leverage advanced GNSS-Inertial
 integration with Applanix SmartCal™
 compensation technology for superior
 position and orientation performance.
- Seamless Workflow: Supported by Applanix POSPac Complete, the industry-leading software for Direct Georeferencing of airborne mapping sensors.
- Out-of-the-Box Ready: Includes 1-year factory-enabled real-time Trimble® CenterPoint® RTX and POSPac Complete service, allowing for immediate mapping operations without additional licenses.





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TECHNICAL SPECIFICATIONS

- · Advanced Applanix IN-Fusion+ GNSS-Inertial integration technology
- Onboard Solid-state MEMS inertial sensors with Applanix SmartCal compensation technology
- Advanced Trimble Maxwell[™] Custom GNSS survey technology with 2 × 336 tracking channels
- · Primary Antenna
 - GPS: L1 C/A, L2C, L2E, L5
 - GLONASS: L1 C/A, L2 C/A, L3 CDMA
 - BeiDou: B1, B2, B3
 - · Galileo: E1, E5A, E5B, E5AltBOC, E66

 - QZSS: L1 C/A, L1S, L1C, L2C, L5, LEX
 - SBAS: L1 C/A, L5
 - · MSS L-Band: Trimble RTX
- · Secondary Antenna:
 - GPS: L1 C/A, L2C, L2E, L5
 - · GLONASS: L1 C/A, L2 C/A, L3 CDMA
 - BeiDou: B1, B2, B3
 - Galileo: E1, E5A, E5B, E5AltBOC, E6⁶

 - QZSS: L1 C/A, L1S, L1C, L2C, L5, LEX
 - SBAS: L1 C/A, L5
- · High-precision multiple correlators for GNSS pseudorange measurements
- Unfiltered, unsmoothed pseudorange measurements data with low noise, low multipath error, low time domain and high dynamic response
- Very low noise GNSS carrier phase measurements with <1 mm precision in a 1 Hz bandwidth
- · Proven Trimble low elevation tracking technology
- Real-time GNSS Trimble RTX positioning mode (1-year license included)
- Real-time 100 Hz position, attitude output, 200 Hz IMU data rate logging
- Gimbal support with vaw drift correction included
- External IMU support (IMU Type 117)
- Two antenna GNSS heading support for low-speed and hovering applications included
- · Navigation output format: ASCII (NMEA-0183), binary (Trimble GSOF)
- RTK license support for Reference Inputs CMR, CMR+™, sCMRx, RTCM 2.1, 2.2, 3.0, 3.1, 3.2, sold separately
- · Supported by POSPac Complete (1-year license included)
- · No export permit required

LAN INPUT/OUTPUT

All Ethernet functions are supported through dedicated IP address (static or DNS) simultaneously including web-based control GUI access and real-time data streaming TCP/IP and UDP

ASCII and Binary data streaming (Time tag, PPS sync, status, position, attitude, velocity, track and speed, dynamics, performance metrics, GNSS data), configuration messages,

Gimbal support HTTP

Web based Control software (GUI) for easy system configuration and low rate display. Support for all common

browsers (IE, Safari, Mozilla, Google Chrome, Firefox)

SERIAL INPUT/OUTPUT

RS232 ports (baud rates up to 460,800)

Parameters ASCII and Binary data streaming (Time tag, PPS track and

speed, dynamics, performance metrics, GNSS data), reference input (CMR, CMR+, sCMRx, RTCM), configuration messages,

Gimbal support

OTHER INPUT/OUTPUT

PPS (pulse-per-second) Time synchronization

Event Input (2) Two-time marks for external events, TTL 3.3V, 50 Hz max rate Strobe Output (1) Programmable camera trigger, TTL 3.3V Status LEDs (4)

Operator indicators of the system status External IMU Interface Dedicated lines for remote IMU connection (model dependent)

LOGGING

Parameters

Internal Logging 6 GB flash memory External Logging⁸

Over dedicated (user configurable) Ethernet port,

Time tag, status, position, attitude, velocity, track and speed, dynamics, performance metrics, raw IMU data (200 Hz),

raw GNSS data (5 Hz)

PERFORMANCE SPECIFICATIONS¹ (RMS ERROR) AIRBORNE						
	SPS	SBAS ³	RTX ⁴	POSPAC COMPLETE ⁵		
Position (m)	1.5 H	0.50 H	0.03 H	0.02 H		
Position (m)	3.0 V	0.85 V	0.06 V	0.03-0.05 V		
Velocity (m/s)	0.050	0.050	0.020	0.010		
Roll & Pitch (deg)	0.020	0.015	0.010	0.010		
True Heading ² (deg)	0.100	0.080	0.050	0.025		

SYSTEM SPECIFICATION

PCS (POS Computer System)

Size	185 L × 93 W × 43 H mm (nominal)
Weight	0.82 kg
Power	
	typical power consumption of 20W max
Connectors	I/O: DA26 and DA15
	Antenna (2): TNC (Female)
GNSS Antenna	AV39 ⁷

INERTIAL MEASUREME	INERTIAL MEASUREMENT UNITS (IMU)			
ТҮРЕ	RANGE	TEMPERATURE ⁶	SIZE (L × W × H) mm	WEIGHT (kg)
External IMU-117	+/-15 g +/-300 dps	-25 °C to +60 °C	116 × 116 × 71 (in tophat provided)	0.64

ENVIRONMENTAL CHARACTERISTICS

Temperature	40 °C to +75 °C (Operational)
	-55 °C to +85 °C (Storage)
Mechanical Shock	+/- 75 g Survival
Operating Humidity	5% to 95% R.H. non-condensing at +60 °C
Maximum Operating Limits	515 m/sec
	18.000 m

ADDITIONAL ACCESSORIES

.. I/O and antenna cables included

- Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects.
- Typical survey mission profile, max RMS error. The heading error will increase for lowspeed rotor applications and when hovering.
- Subject to regional coverage.
- Real-time Trimble CenterPoint RTX correction service typical airborne results subject to regional coverage. First year service included. Renewals sold separately.
 Post-Processed with Applanix POSPac Complete includes (Post-processed RTX, Single and
- Applanix SmartBase*). Factory enabled first year service included. Renewals sold separately.
- Temperature performance range subject to Applanix SmartCal, the system is operational outside of the range with possible reduced accuracy.
 Single antenna included, additional antenna for GAMS operation sold separately.
- Requires client software, not included.

Specifications subject to change without notice.

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