

ABSOLUTE ROTARY ENCODER CANOPEN HEAVY DUTY



Main Features

- Compact and heavy-duty industrial design
- Interface: CANopen / CAN
- Housing: 58 mm Ø
- Solid / hollow shaft: 6 or 10 mm Ø / 15 mm Ø
- Max. 65536 steps per revolution (16 Bit)
- Max. 16384 revolutions (14 Bit)
- Code: Binary

Mechanical Structure

- Aluminium flange and housing
- Stainless steel shaft
- Precision ball bearings with sealing or cover rings
- Code disc made of unbreakable and durable plastic

Programmable Parameters

- Direction of rotation (complement)
- Resolution per revolution
- Total resolution
- Preset value
- Two limit switches
- Baudrate and CAN-identifier
- Transmission mode: Polled mode, cyclic mode, sync mode

Electrical Features

- Temperature insensitive IR-opto-receiver-asic
- Highly integrated circuit in SMD-technology
- Polarity inversion protection
- Over-voltage-peak protection

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Technical Data

Electrical Data

Interface	Transceiver according ISO 11898, galvanically isolated by opto-couplers
Transmission rate	max. 1 MBaud
Device addressing	programmable via SDO telegrams
Supply voltage	10 - 30 V* DC (absolute limits)
Current consumption	max. 230 mA with 10 V DC, max. 100 mA with 24 V DC
Power consumption	max. 2.5 Watts
Step frequency LSB	800 kHz
Accuracy of division	$\pm 1/2$ LSB (12 bit), ± 2 LSB (16 bit)
EMC	Emitted interference: EN 61000-6-4
	Noise immunity: EN 61000-6-2
Electrical lifetime	> 10 ⁵ h

*Absolute rotary encoders should be connected only to subsequent electronics whose power supplies comply with EN 50178 (protective low voltage)

Mechanical Data

Housing	Aluminum, stainless steel on request			
Lifetime	Dependent on shaft version and shaft loading – refer to table			
Max. shaft loading	Axial 40 N, radial 110 N			
Inertia of rotor	$\leq 30 \text{ gcm}^2$			
Friction torque	$\leq 3 \text{ Ncm}$ (without shaft sealing)			
RPM (continuous operation)	Singleturn: max. 12,000 RPM			
	Multiturn: max. 6,000 RPM			
Shock (EN 60068-2-27)	$\leq 100 \text{ g}$ (half sine, 6 ms)			
Permanent shock (EN 60028-2-29)	$\leq 10 \text{ g}$ (half sine, 16 ms)			
Vibration (EN 60068-2-6)	$\leq 10 \text{ g}$ (10 Hz ... 2000 Hz)			
Weight (standard version)	Singleturn: $\approx 400 \text{ g}$			
	Multiturn: $\approx 500 \text{ g}$			

Flange	Synchro (S)		Clamp (C)	Hollow shaft (B)
Shaft diameter	6 mm	10 mm	10 mm	15 mm
Shaft length	10 mm	20mm	20 mm	-
hollow shaft depth min. / max.	-	-	-	15 mm / 30 mm

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Minimum (mechanical) lifetime

Flange	Lifetime in 10 ⁸ revolutions with F _a / F _r		
	40 N / 60 N	40 N / 80 N	40 N / 110 N
C10 (Clamp flange 10 x 20)	247	104	40
S10 (Synchro flange 10 x 20)	262	110	42
S06 (Synchro flange 6 x 10) without shaft sealing	822	347	133

S06 (Synchro flange 6 x 10) with shaft sealing: max. 20 N axial, 80 N radial

Environmental Conditions

Operating temperature	- 40 .. +85 °C*
Storage temperature	- 40 .. + 85 °C*
Humidity	98 % (without liquid state)
Protection class (EN 60529)	Casing side: IP 67
	Shaft side: IP66

* Cable exit: -30 ... + 70 °C (static), -5 ... + 70 °C (flexing)

ABSOLUTE ROTARY ENCODER

CANOPEN HEAVY DUTY

Interface

Configuration

The standard configuration of the encoder is: node number 32 and baudrate 20KBaud. For adapting the encoder for a respective application the customer could use SDO telegrams. Valid baudrate range is 20 kBaud up to 1MBaud and for the node number from 0 to 89.

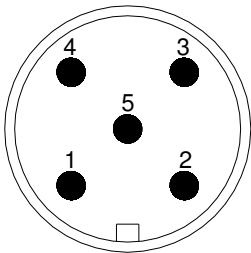
Remark: The encoder adds internal 1 to the adjusted device address.

Electrical Interface

The encoder can be connected in the following versions: 5 pin M12 male connector one 5 pin M12 male, one 5 pin M12 connector and venting element.

Bus in

5 pin circular connector M12



Signal	5 pin circular connector
(CAN Ground)	1
24 V power supply	2
0 V power supply	3
CAN High	4
CAN Low	5

ABSOLUTE ROTARY ENCODER CANOPEN HEAVY DUTY

Programmable Encoder - Parameter

Operating Parameters	This parameter determines the counting direction, in which the output code increases or decreases. As an important operating parameter the code sequence (complement) can be programmed.
Resolution per Revolution	The parameter resolution per revolution is used to program the desired number of steps per revolution. Each value between 1 and 4,096 can be programmed.
Total Resolution	This parameter is used to program the desired number of measuring units over the total measuring range. This value may not exceed the total resolution of the absolute rotary encoder. If the encoder is used in a continuous measuring application, certain rules for the setting of this parameter must be followed. These rules are outlined in the manual.
Preset Value	The preset value is the desired position value, which should be reached at a certain physical position of the axis. The position value is set to the desired process value by the parameter pre-set.
Limit Switch, Min. and Max.	Two position values can be programmed as limit switches. By reaching these values one bit of the 32-bit process value is set to high.

Programmable CAN Transmission Modes

Polled Mode	By a remote-transmission-request telegram the connected host calls for the current process value. The absolute rotary encoder reads the current position value, calculates eventually set-parameters and sends back the obtained process value by the same identifier.
Cyclic Mode	The absolute rotary encoder transmits cyclically - without being called by the host - the current process value. The cycle time can be programmed in milliseconds for values between 1 ms and 65536 ms.
Sync Mode	After receiving a sync telegram by the host, the absolute rotary encoder answers with the current process value. If more than one node number (encoder) shall answer after receiving a sync telegram, the answer telegrams of the nodes will be received by the host in order of their node numbers. The programming of an offset-time is not necessary. If a node should not answer after each sync telegram on the CAN network, the parameter sync counter can be programmed to skip a certain number of sync telegrams before answering again.

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Mechanical drawings

Heavy Duty version

These „Outdoor encoder“ is suitable for harsh industrial environments e.g. heavy construction machines, steel mills, etc.. The heavy-duty option for the Pure CANopen encoder provides an extended temperature range, protection elements against perspiration water inside the encoder and a heavy-duty housing. Uppermost attention was laid on a high EMI protection. Micro style connectors for power supply and bus-in / bus-out connection allow easy installation of the encoder. The Pure CANopen encoder can be configured with all available project tools by implementing the ESD file into the current project.

Main features

- Compact dimensions
- Heavy Duty housing
- Protective element against perspiration water
- Integrated T-coupler
- Standard protection class:

IP66 shaft side

IP67 casing side



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Models/Ordering Description

Description	Typekey						
Optocode	OCD-	----	-	---	-	---	PRN
Interface	CANopen Single Turn Binary Code	C600B-					
	CANopen Multi Turn Binary Code	C5B1B-					
Revolutions (Bits)	Singleturn	00					
	Multiturn (4096 revolutions)	12					
	Multiturn (16384 revolutions)	14					
Seps per revolution (Bits)	4096	12					
	8192	13					
	65536	16					
Flange	Clampflange			C			
	Synchroflange			S			
	Blindshaft			B			
Shaft Diameter	10 mm			10			
	15 mm (Hollow shaft)			15			
Mechanical Options	Heavy Duty Version					H	
	customized					C	
Electrical Connection	1x 5 pin M12 connector male, 1x 5 pin M12 connector female, venting element						PRN
	1x 5 pin M12 connector male, venting element						PRM

Standard = bold, further models on request

Accessories and documentation

Description		Article Name	Article Number
Shaft Coupling	Drilling: 10 mm / 10 mm	GS 10	29100450
	Drilling: 6 mm / 6 mm	GS 06	29100350
Clamp Disc	Set (4 pieces).	SP 15	32400155
Clamp Ring	Set (2 pieces)	SP H	32400152
Reducing Ring*	15 mm to 12 mm	RR 12	32220291
Reducing Ring *	15 mm to 10 mm	RR 10	32220292
Reducing Ring *	15 mm to 8 mm	RR 8	32220295

Note: All datasheets and manuals can be downloaded for free from our website www.posital.eu

* only for hollow shaft

We do not assume responsibility for technical inaccuracies or omissions. Specifications are subject to change without notice.