Following on from the success of ABB’s dual-arm YuMi, introduced in 2015, the world’s first truly collaborative robot, ABB has developed a single-arm YuMi to expand its collaborative portfolio.

Versatile installation for convenient deployment

Single-arm YuMi is compact and lightweight (9.5 kg) and supports mounting in any direction including ceiling, table, and wall mounting for rapid and flexible installation to fit into existing production lines. The ultra-light magnesium arm rotates on seven axes to mimic human-like movements with greater agility than 6-axis robots. The robot was specifically designed to meet the flexible production needs required by small parts assembly processes including consumer electronics, consumer goods, and small and medium enterprises.

Easy-to-use lead-through programming

Single-arm YuMi also features the same intuitive, easy-to-use lead-through movement programming as dual-arm YuMi, meaning workers can teach the robot motions and positions easily and quickly, greatly simplifying robot programming. Combining this simplicity with the robot’s deployment flexibility, it will help manufacturers in many industries to offset shortages of skilled workers and help reduce entry barriers for new potential robot users, particularly small and medium enterprises. Extremely versatile, the YuMi family of robots can be combined in numerous configurations. For example, a single-arm YuMi can be used to feed parts to dual-arm YuMi to increase flexibility, or added as an extra arm for more complex assembly tasks requiring more than 2 robot arms.

Wizard easy programming

Single-arm YuMi comes delivered with Wizard, ABB’s new graphical programming interface that enables you to quickly create robot programs using drag-and-drop blocks on the Flexpendant.

SaveMove option

To fulfill the enhanced safety requirements of specific usage scenarios, ABB’s SafeMove will be available as option for the single-arm YuMi, giving it the full range of safety certified functions that other ABB robots have.

Key features

– 500 g rated payload
– Small footprint, 7-axis dexterity
– Very lightweight manipulator, 9.5 kg
– Mounting in any position
– Integrated gripper with servo gripper, vision and vacuum
– Best-in-class safety design
– High speed and accuracy
– PL d Cat 3 Protective stop and emergency stop

Customer benefits

– Short cycle times
– Fenceless operation
– Lead-through technology
– Wizard easy programming
– Lower investment
– Easier to integrate
## Specification

<table>
<thead>
<tr>
<th>Robot version</th>
<th>Reach (mm)</th>
<th>Payload (g)</th>
<th>Armload</th>
</tr>
</thead>
<tbody>
<tr>
<td>IRB 14050</td>
<td>559</td>
<td>500</td>
<td>No armloads</td>
</tr>
</tbody>
</table>

- Number of axes: 7
- Protection: Std: IP30 and Clean Room
- Mounting: All angles. AbsAcc available for all mounting positions.
- Controller: OmniCore C30
- Customer power supply: 24V/1A supply
- Customer signals: 4 signals (for IO, Fieldbus, or Ethernet)
- Integrated air supply: 4 Bar
- Functional safety: PL d Cat 3 Protective stop and emergency stop SafeMove as option

## Performance (according to ISO 9283)

- Max TCP Velocity: 1.5 m/s
- Max TCP Acceleration (normal control motion @nominal load): 39.1 m/s²
- Max TCP Acceleration (e-stop @nominal load): 85.4 m/s²
- Acceleration time 0-1m/s: 0.12 s
- Pose repeatability: 0.02 mm
- 0.5 kg picking cycle: 25 x 300 x 25 mm
  - Time: 0.86 s

## Physical

- Dimensions bottom: 160 x 160 mm
- Weight: 9.5 kg

## Movement

<table>
<thead>
<tr>
<th>Axis movement</th>
<th>Working range</th>
<th>Axis max. speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>Axis 1 rotation</td>
<td>−168.5° to 168.5°</td>
<td>180°/s</td>
</tr>
<tr>
<td>Axis 2 arm</td>
<td>−143.5° to 43.5°</td>
<td>180°/s</td>
</tr>
<tr>
<td>Axis 3 arm</td>
<td>−123.5° to 80.0°</td>
<td>180°/s</td>
</tr>
<tr>
<td>Axis 4 wrist</td>
<td>−290.0° to 290.0°</td>
<td>400°/s</td>
</tr>
<tr>
<td>Axis 5 bend</td>
<td>−88.0° to 138.0°</td>
<td>400°/s</td>
</tr>
<tr>
<td>Axis 6 turn</td>
<td>−229.0° to 229.0°</td>
<td>400°/s</td>
</tr>
<tr>
<td>Axis 7 rotation</td>
<td>−168.5° to 168.5°</td>
<td>180°/s</td>
</tr>
</tbody>
</table>