Trimble SPS986 GNSS SMART ANTENNA

The ultra-tough Trimble® SPS986 GNSS Smart Antenna offers unmatched reliability for positioning. Ideal for use in a variety of applications, the SPS986 can serve as a GNSS rover system or as a base station for other GNSS operations including machine control.

The most rugged receiver Trimble has ever built, the SPS is faster and scalable, has a longer battery life and incorporates the latest technology to make ag positioning and surveying easier, safer and more productive.

Trimble ProPoint Technology

Trimble ProPoint GNSS technology uses all available signals to provide survey-grade positioning in many areas where other GNSS systems either can't provide a solution at all or produce unreliable error estimates.

Trimble xFill Technology

Trimble xFill[™] technology expands site productivity by allowing short excursions into locations where GNSS corrections were not previously available.

Tilt Compensation

Using the Trimble SPS986 GNSS Smart Antenna and Trimble Siteworks Positioning Software it is now possible to capture accurate points while standing, walking or driving the site in a vehicle, while the receiver is not level.

Full GNSS tilt compensation makes Siteworks easier to learn for beginners and saves significant time for more experienced surveyors. Tilt compensation in vehicle mode is designed to capture higher accuracy measurements on steeper slopes from a moving vehicle, and more accurate volume measurements to save time and money on material planning.

- Easily and safely survey hard to reach areas (corners, traffic lanes, utility flowlines)
- Faster measurements
- More efficient stake-outs
- No magnetic interference

Mount the SPS986 to a vehicle and do site topos, check as-builts, and road center lines in even the roughest site conditions. The SPS986 can withstand high vibration scenarios without interruption or fear of damage.

It has never been so easy to get measuring. Initial site work and topo can even be done base-station-free using satellite-delivered GNSS corrections to the rover.

Applications

With Trimble Siteworks Software, you can:

- Determine cut/fill on a range pole, utility vehicle or truck
- Record tilt data when taking measurements
- Stake out site or road features, utilities, daylight lines and side slopes
- Measure progress and calculate material stockpile volumes
- Carry out as-built measurements, grade checks and thickness checks

Using your smartphone, quickly check the health and status of the receiver with the Trimble GNSS Status App. For a more in-depth look, Trimble Web UI can be accessed over Wi-Fi. Setting a new standard for rugged reliability, the SPS986 GNSS Smart Antenna keeps your crews working, not wasting time with GNSS maintenance.

Reliable Base Station

The SPS986 can also serve as a powerful site base station, using integrated Wi-Fi or optional radio to send and receive corrections for rover or machine control work. It is the easiest base station on the market The SPS986 will automatically establish a connection with the machine radio or GNSS rover and begin transmitting corrections—just put it on the tripod, switch it on and go.

Key Features

- Compact design with unprecedented strength and durability, easy to use and virtually indestructible
- Tilt compensation makes positioning easier and more accessible for new users, while saving time and money for experienced users
- Real-Time Kinematic (RTK) corrections for higher accuracy site measurements
- Uses more GNSS constellations, satellites and signals to increase productivity and uptime, greater accuracy in difficult conditions (under tree canopy or near buildings)
- Great flexibility easily go from carrying case to range pole, tripod, t-bar or vehicle with a single click so you can get going faster.



TRIMBLE SPS986 GNSS SMART ANTENNA

Technical Specifications			
Configuration Option		xFill Positioning	
Base and Rover	Yes, upgradeable to Rover, Base or Rover / Base	xFill accuracy	RTK ¹¹ + 10mm(0.03 ft)/min Horiz. + 20mm(0.06 ft)/min Vert. RMS
interchangeability		Location RTK Positioning	
Rover position update	1 Hz, 2 Hz, 5 Hz, 10 Hz, 20 Hz	Horizontal accuracy	Location RTK (10/10) or (10/2) 10 cm + 1 ppm RMS (0.32 ft + 1 ppm)
rate		Vertical accuracy	Location RTK (10/10) 10 cm + 1 ppm RMS (0.32 ft + 1 ppm) Location
Rover maximum range from base radio	Unrestricted, typical range 2–5 km (1.2–3 miles) without radio repeater	Deal Time Kinematic (DTK	RTK (10/2) 2 cm + 1 ppm RMS (0.065 ft + 1 ppm)
Rover operation within a	Yes	up to 30 km) Positioning ²	
VRS network	Max anti-u7	Horizontal accuracy	8 mm + 1 ppm RMS (0.026 ft + 1 ppm RMS)
Reading and Woving	res - option?	Vertical accuracy	15 mm + 1 ppm RMS (0.05 ft +1 ppm RMS)
Eactory options	See Receiver LIngrades below	Trimble VRS9	
General	See Necelver Opgrades below	Horizontal accuracy	8 mm + 0.5 ppm RMS (0.026 ft +0.5 ppm)
Keyboard and display	LED indicators for satellite tracking, radio link status, WiEi and power	Vertical accuracy	15 mm + 0.5 ppm RMS (0.05 ft +0.5 ppm)
Reyboard and display	monitoring On/Off key for one-button startup	Precise Heading	
Dimensions $(I \times W \times D)$	13.9 cm (5.5 in) Diameter x 13 cm (5.1 in) including connectors	Heading accuracy	When combined with SPS9867
Weight	1.55 kg (3.42 lb) receiver only including radio and battery	2 m antenna separation	0.09°RMS
inoigint.	Complete system (rover including controller and pole) 3.9 kg (8.6 lbs)	10 m antenna separation	0.05°RMS
Temperature		High Precision Static	
Operating ¹	-40 °C to +65 °C (-40 °E to +149 °E)	Horizontal accuracy	3 mm + 0.1 ppm RMS (0.01 ft +0.1 ppm)
Storage	-40 °C to +75 °C (-40 °E to +167 °E)	Vertical accuracy	3.5 mm + 0.4 ppm RMS (0.011 ft +0.4 ppm)
Humidity	100% condensing	Initialization Time	
Waterproof	IP67 for submersion to depth of 1 m (3.3 ft), dustproof	Regular RTK operation	Single/Multi-base typically less than 8 seconds
Shock and Vibration		with base station	
Polo drop	Designed to survive a 2 m (6.6 ft) pole drop onto concrete	Initialization reliability ⁴	>99.9%
Shock Non-operating	75 Co at 6mood	Power	
Shock - Non-operating		Internal	- Rechargeable, removable 7.4 V, 2.8 Ah Lithium-ion battery in internal
Vibration	40 GS at TUMSEC Mill Std 2000 EIC 514 6E 1 Cat 24 Mill Std 2020 EIC 214 1 Condition D		battery compartment
Vibration	Mil-Stu-Stu-G, Fig 514.0E-1 Cat 24, Mil-Stu-ZuZu, Fig 214-1, Condition D		- Internal battery operates as a UPS during an ext power source failure
weasurements	- Advanced Infinible rechnology Custom GNSS chips High-precision multiple correlator for GNSS pseudorange measurements		- Internal battery will charge from external power source as long as
	- I Infiltered unsmoothed pseudo-range measurements data for low		source can support the power drain and is more than 11.8 VDC
	noise. Iow multipath error. Iow-time domain correlation, and high-		- Integrated charging circuitry
	dynamic response Very low noise carrier phase measurements with	External	- External power input with over-voltage protection on Port I (/-pin Lemo
	<1 mm precision in a 1 Hz bandwidth		2-key). Minimum 10.0 V, Maximum 20 V DC, Shutuowin optimized for 12 V
	- Trimble EVEREST+ multipath signal rejection MSS Band: CenterPoint		- Rower source supply (Internal /External) is bet-swap capable in the
	RTX and OmniSTAR by subscription Trimble xFill for short gaps in		event of power source removal or cut off
	correction messages		- DC external power input with over-voltage protection on Port 1 (Lemo)
	- GPS L1 C/A, L2C, L2E (Trimble method for tracking unencrypted L2P)		- Receiver automatically turns on when connected to external power
	upgradable to CLONASS L1/L2C (ALL2D Full Quelo Corrier	Power over Ethernet	N/A
	Opgradeable to GLUNASS L1/L2C/A, L2P Full Cycle Carrier	(PoE)	
	- Opgrade to Galileo LI ODOO, EDA, EDB & EDAITBOUG AND BEIDOU B1 B2	Power consumption	- 3.2 W in rover mode with internal receive radio
	- Integrated MEM's conserver for a Bubble 4-shapped SBAS 11C/A 15		- 5.2 W in base mode with internal 0.5 W transmit radio
	(WAAS/EGNOS/MSAS/GAGAN)	Operation Time on	
	- 07SS: L1 C/A L1C L1 SAIE L2C L5	Internal Battery	
SBAS (WAAS/FGNOS/	2200.210/1,210,210,11,220,20	Rover	5.5 hours; varies with temperature
MSAS) Positioning ³		Base station	
Accuracy	Horizontal ± 0.50m (1.6 ft), Vertical ± 0.85m (2.8 ft)	450 MHz systems	Approximately 4 hours; varies with temperature ⁵
Code Differential GPS		900 MHz systems	Approximately 4 hours; varies with temperature
Positioning ²			
Horizontal accuracy	0.25 m + 1 ppm RMS (0.8 ft + 1 ppm RMS)	1 Receiver will operate normally to	those temperature limits. Internal batteries will operate from -20 °C to $+48$ °C
Vertical accuracy	0.50 m + 1 ppm RMS (1.6 ft + 1 ppm RMS)	 Accuracy and reliability may be st atmospheric conditions. Always f 	uoject to anomalies such as multipath, obstructions, satellite geometry, interference and ollow recommended survey practices.
Regulatory Approvals	FCC Part 15 Subpart B (Class B Device) Part 15 247 Part 90	3 Depends on SBAS system perfor	mance.
		4 may be arrected by atmospheric conditions, signal multipath, and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality.	
UmniSTAR Positioning	University of an (2.2.4)	5 If your receiver is transmitting 2.0 W (450 MHz), you will experience reduced battery performance compared to the 0.5 W solution	
VBS service accuracy	Horizontal $\leq 1 \text{ m} (3.3 \text{ ft})$	 Bluetooth type approvals are country specific. For more intormation, contact your local Trimble office or representative. When receiver is combined with an SPS986 with Moving Base installed or other suitable SPS receivers. 	
XP service accuracy	Horizontal 0.2 m (0.66 ft), Vertical 0.3 m (1.0 ft)	8 Galileo Commercial Authorization Developed under a Licence of the European Union and the European Space Agency.	
HP service accuracy	Horizontal 0.1 m (0.33 ft), Vertical 0.15 m (0.5 ft)	9 Networked RTK PPM values are n 10 This Trimble SPS Receiver is capa	eterenced to the closest physical base station. able of supporting existing and planned GNSS satellite signals, including GPS, GLONASS
CenterPoint [®] RTX		GALILEO, BeiDou and QZSS, and	existing and planned augmentations to these GNSS systems.
Accuracy		11 RTK refers to the last reported pre 12 Receiver accuracy and converger	ecision before the correction source was lost and xFill started. Ince time varies based on GNSS constellation bealth, level of multipath, and provimity to
Accuracy ²²	Horizontal 4cm (0.13 ft) RMS, Vertical 9cm (0.30 ft) RM	obstructions such as large trees a	and buildings.
convergence time for	5 minutes in select regions, and within 30 minutes worldwide		
specifica precisions			

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