



All information in this manual is current at the time of printing and is subject to change. The current manual, the detailed assembly and operating manual as well as further information and documents can be downloaded from schunk.com

1 Sizes

This operating manual applies to the following sizes:

- EGP 25
- EGP 40
- EGP 50
- EGP 64

2 Variants

This operating manual applies to the following variations:

- EGP
- EGP Speed (S)
- EGP IO-Link

3 Applicable documents

- General terms of business *
- Catalog data sheet of the purchased product *
- Safety information
- Assembly and operating manual for the product *
 - incl. declaration of conformity
 - incl. declaration of installation
- For variant "IO-Link": Software guide "SCHUNK gripper with IO-Link" *
- Assembly and operating manuals of the accessories *
 - The documents labeled with an asterisk (*) can be downloaded from schunk.com.

4 Basic safety notes

4.1 Intended use

The product is designed exclusively for gripping and temporarily holding workpieces or objects.

- The product may only be used within the scope of its technical data, ► Chap. 5, Technical data.
- The product is intended for installation in a machine/automated system. The applicable guidelines for the machine/automated system must be observed and complied with.
- The product is intended for industrial and industry-oriented use. Its use outside enclosed spaces is only permitted if suitable protective measures are taken against outdoor exposure. The product is not suitable for use in salty air.
- The product can be used within the permissible load limits and technical data for holding workpieces during simple machining operations, but is not a clamping device according to EN 1550:1997+A1:2008.
- Appropriate use of the product includes compliance with all instructions in this manual.
- Any utilization that exceeds or differs from the appropriate use is regarded as misuse.

4.2 Personnel qualification

- All work may only be performed by qualified personnel.
- Before working with the product, the personnel must have read and understood the complete assembly and operating manual.

4.3 Personal protective equipment

- When working on and with the product, observe the occupational health and safety regulations and wear the required personal protective equipment.
- Wear protective gloves to guard against sharp edges and corners or rough surfaces.
- Wear heat-resistant protective gloves when handling hot surfaces.
- Wear close-fitting protective clothing and wear long hair in a hairnet when dealing with moving components.

4.4 Constructional changes

- Constructional changes may only be done with the permission of SCHUNK.

4.5 Notes for transport

- When handling heavy weights, use lifting equipment to lift the product and transport it by appropriate means.
- Secure the product against falling during transportation and handling.
- Stand clear of suspended loads.

4.6 Notes for assembly

- Before assembly, secure the danger zone by suitable measures.
- Switch off the power supply before mounting work, ensure that no residual energy is present and secure against reconnection.

5 Technical data

5.1 Connection data

5.1.1 EGP 25

Designation	EGP		
	25	100	25-S
Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4		
Min. Supply current power supply unit [A] *	1.0		
Max. Current input [A]**	1.0		
Gripping force [%]	50	100	100
Current input in blocked state [A] ***	0.07	0.14	0.14
Integrated electronic control unit			
Communication interface	Digital I/O		
Number of digital inputs/ outputs	2/2		

- * minimum supply current for reliable operation of product
- ** maximum current input in the acceleration phase (max. t = 50 ms)
- *** Current input in blocked state (in gripper end position or while gripping a workpiece) with active command "Open Gripper" or "Close Gripper"

More technical data is included in the catalog data sheet. Whichever is the latest version.

5.1.2 EGP 40

Designation	EGP				
	40		40-S		
Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4				
Min. Supply current power supply unit [A] *	1.0				
Max. Current input [A]**	2.0				
Gripping force [%]	25	50	75	100	100
Current input in blocked state [A] ***	0.05	0.10	0.15	0.20	0.20
Integrated electronic control unit					
Communication interface	Digital I/O				
Number of digital inputs/ outputs	2/2				

Designation	EGP 40 IO-Link				
	Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4			
Min. Supply current power supply unit [A] *	1.0				
Max. Current input [A]**	2.0				
Gripping modes	FastGrip/SoftGrip				
Gripping force [%]	25	50	75	75	100
Current input in blocked state [A] ***	0.05	0.10	0.15	0.15	0.2
End position detection tolerances [mm] (in delivery status/after stroke measurement)	±0.5				
Integrated electronic control unit					
Communication interface	IO-Link				
Specification:	V1.1				
Transmission rate	COM2				
Port	Class B				

- * minimum supply current for reliable operation of product
- ** maximum current input in the acceleration phase (max. t = 50 ms)
- *** Current input in blocked state (in gripper end position or while gripping a workpiece) with active command "Open Gripper" or "Close Gripper"

More technical data is included in the catalog data sheet. Whichever is the latest version.

5.1.3 EGP 50

Designation	EGP 50				
	Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4			
Min. Supply current power supply unit [A] *	2.0				
Max. Current input [A]**	2.0				
Gripping force [%]	25	50	75	75	100
Current input in blocked state [A] ***	0.07	0.15	0.22	0.22	0.3
Integrated electronic control unit					
Communication interface	Digital I/O				

Designation	EGP 50				
	Number of digital inputs/ outputs	2/2			
Designation	EGP 50 IO-Link				
	Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4			
Min. Supply current power supply unit [A] *	2.0				
Max. Current input [A]**	2.0				
Gripping modes	FastGrip/SoftGrip				
Gripping force [%]	25	50	75	75	100
Current input in blocked state [A] ***	0.07	0.15	0.22	0.22	0.3
End position detection tolerances [mm] (in delivery status/after stroke measurement)	±0.5				
Integrated electronic control unit					
Communication interface	IO-Link				
Specification:	V1.1				
Transmission rate	COM2				
Port	Class B				

- * minimum supply current for reliable operation of product
- ** maximum current input in the acceleration phase (max. t = 50 ms)
- *** Current input in blocked state (in gripper end position or while gripping a workpiece) with active command "Open Gripper" or "Close Gripper"

More technical data is included in the catalog data sheet. Whichever is the latest version.

5.1.4 EGP 64

Designation	EGP 64				
	Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4			
Min. Supply current power supply unit [A] *	2.0				
Max. Current input [A]**	2.0				
Gripping force [%]	25	50	75	75	100
Current input in blocked state [A] ***	0.04	0.08	0.1	0.1	0.15
Designation					
EGP 64 IO-Link					
Supply voltage [VDC] Min. [VDC] Max. [VDC]	24 21.6 26.4				
Min. Supply current power supply unit [A] *	2.0				
Max. Current input [A]**	2.0				
Gripping modes	FastGrip/SoftGrip				
Gripping force [%]	25	50	75	75	100
Current input in blocked state [A] ***	0.04	0.08	0.1	0.1	0.15
End position detection tolerances [mm] (in delivery status/after stroke measurement)	±0.5				
Integrated electronic control unit					
Communication interface	IO-Link				
Specification:	V1.1				
Transmission rate	COM2				
Port	Class B				

- * minimum supply current for reliable operation of product
- ** maximum current input in the acceleration phase (max. t = 50 ms)
- *** Current input in blocked state (in gripper end position or while gripping a workpiece) with active command "Open Gripper" or "Close Gripper"

More technical data is included in the catalog data sheet. Whichever is the latest version.

5.2 Ambient conditions and operating conditions

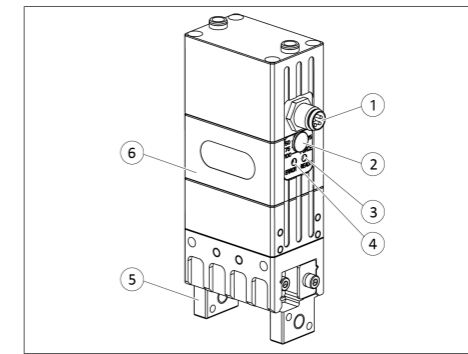
Designation	EGP 25 – 64	
	IP protection class (mechanical) *	30
IP protection class (electrical) * (only with center plug)	40	
Noise emission [dB(A)]	≤ 70	
Ambient temperature [°C]		
Min.	5	
Max.	55	

- * For use in dirty ambient conditions (e.g. sprayed water, vapors, abrasion or processing dust) SCHUNK offers corresponding product options as standard. SCHUNK also offers customized solutions for special applications in dirty ambient conditions.

6 Design and description

6.1 Design

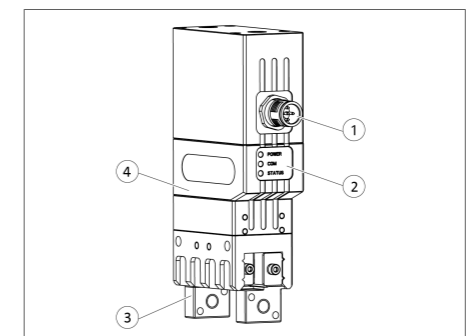
6.1.1 Digital I/O variant



Design EGP, Digital I/O

1	"Power supply and control" connection plug
2	"Gripping force" rotary switch
3	LED READY
4	LED ERROR
5	Base jaw
6	Housing

6.1.2 IO-Link variant



Design EGP, IO-Link

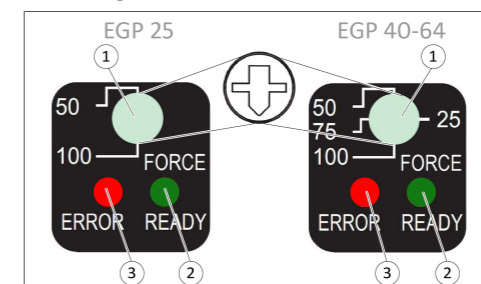
1	"IO-Link" connection plug
2	LED POWER, COM and STATUS
3	Base jaw
4	Housing

6.2 Description

The product is a servo-electric 2-finger parallel gripper featuring high power density and integrated electronics.

6.3 Display

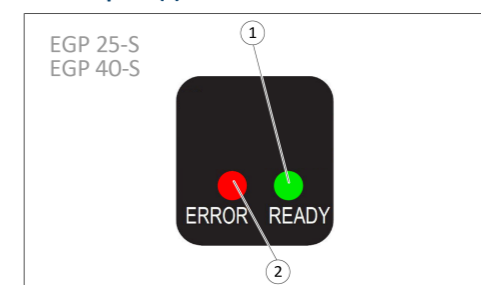
6.3.1 "Digital I/O" variant



Function label EGP 25 and EGP 40-64

1	"Gripping force" rotary switch	3	LED "ERROR"
2	LED "READY"		

6.3.2 "Speed (S)" variant



Function label EGP-Speed (S)

1	LED "READY"
2	LED "ERROR"

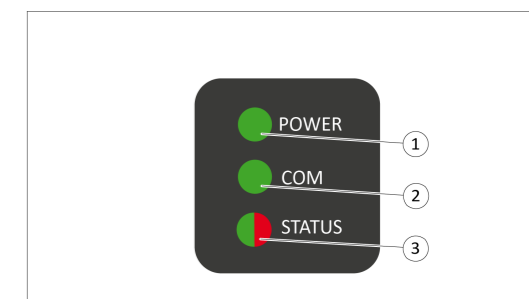
6.3.3 LED "READY" and "ERROR"

Designation	Color	Function
READY	Green	Indicates whether the voltage is connected. <ul style="list-style-type: none"> Lights up as long as voltage is present in the product. Does not light up if there is no voltage in the product.
		ERROR

Acknowledge error

- Wait until the product has cooled down.
- Actuate both digital inlets, PIN 2 and PIN 4, with high.
- OR:
Disconnect voltage supply and reconnect.
⇒ LED "error" is extinguished and the error is acknowledged.

6.3.4 "IO-Link" variant



Function label

1	LED POWER
2	LED COM
3	LED STATUS

6.3.5 LED "POWER", "COM" and "STATUS"

Designation	Color	Function
POWER	Green	Lights up if ready for operation
		Does not light up if logic or actuator voltage is reversed or not in the valid range.
COM	Green	Does not light up if IO-Link communication is not active
		Flashes if IO-Link communication is active
STATUS	Green / Red	Does not light up if electronics are not active or defective
		Lights up green if ready for operation
		Lights up red in case of a fault. Error message is communicated via IO-Link

