Electric Parallel Grippers EIG3-10010 3-Finger

Advantages

- Compact size
 Slim rectangular body with five installation positions for flexible mounting
 Grip control: force and position adjustment
 Quick open/close time with speed adjustment
 Grip feedback and part detection: gripper status can be read at the PLC/Controller and visualized on the unit via LED's
- Multiple communication modes: the gripper supports Modbus RTU protocol and IO mode control. Other protocols such as USB and ETHERNET can be implemented through a protocol converter.
 Grip actuation via embedded controller.



SPECIFICATIONS

Model	Stroke per Jaw	Gripping Force per Jaw	Total Gripping Force	Opening/ Closing Time	Nominal Voltage	Nominal Current	Max Current	Repeatability (Positioning)	Recommended Workpiece Weight*	Weight
EIG3-10010	10 mm 0.39 in	3 - 10 N 0.67 - 2.25 lb	9 - 30 N 2.02 - 6.74 lb	0.3/0.3 s	24 V DC ± 10%	0.30 A	0.60 A	± 0.03 mm ± 0.001 in	0.1 kg 0.22 lb	0.43 kg 0.98 lb

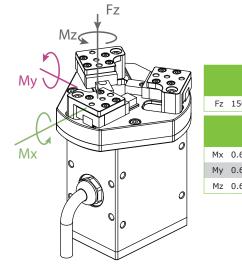
* Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

Communication Interface Standard: Modbus RTU (RS485), Digital I/O Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

IP Protection Class IP 40

Noise Emission (Sound Pressure) ≤ 40 dB(A) in any direction Recommended operating environment 0-40 °C (32-104 °F), < 85% RH

For this type of gripper the use of the standard fingers is recommended.



Allowable vertical load (static)

Fz 150 N (33.72 lb)

Mx 0.62 Nm (5.49 in-lb) My 0.62 Nm (5.49 in-lb)

Mz 0.62 Nm (5.49 in-lb)



PRODUCT INFORMATION

EIG3-10010 3-Finger

