



Superior Clamping and Gripping



Product Information

Manual change system CMS 050

CMS

Manual change system

Flexible. Compact. Intuitive. Manual change system CMS

User-friendly manual change system with extensive complementary portfolio

Field of application

Ideally suited for use in the flexible production and assembly of products with a comprehensive range of variants in which reliable manual changes are required. The system is suitable for use on robots as well as for stationary applications.

Advantages – Your benefits

Series with six unit sizes for optimal size selection and a broad application range

ISO mounting pattern for easy assembly to most types of robots without needing additional adapter plates

Wide range of electric, pneumatic, and fluid modules can be screwed on directly for universal energy transmission options

Optional locking and presence monitoring integrated in the housing for all sizes

Integrated air feed-throughs for a reliable power supply of the handling modules and tools with pneumatic and vacuum, can be used radially and axially

Basic version without integrated air feed-through and sensor option available for simple and cost-sensitive applications



Sizes
Quantity: 6



Handling weight
9 .. 58 kg



Moment load Mx
22.5 .. 478 Nm

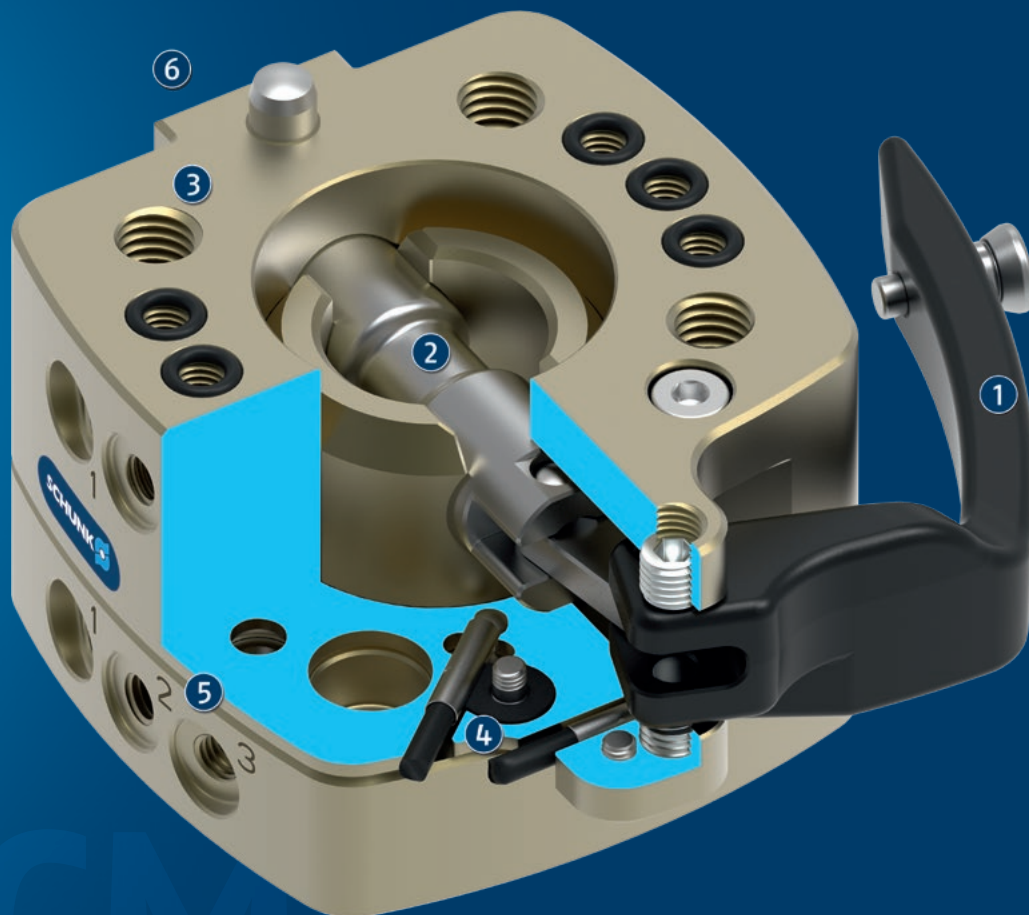


Moment load Mz
15 .. 465 Nm

Functional description

The manual change system (CMS) consists of a change head (CMS-K) and a change adapter (CMS-A). Closing the hand lever provides a form-fit lock that is free from play between the change head and the change adapter using a pin and without the need for any additional tools. Opening the hand lever unlocks the system, allowing the change adapter to be removed. End effectors can be

supplied with compressed air or vacuum via integrated pneumatic feed-throughs. In addition, there is an identically constructed variant without pneumatic feed-throughs and without a monitoring option (CMS-B). In both product variants, the tool can be supplied with other media such as electrical signals or fluids through optional modules.



- ① **Locking lever**
Proven technology for manual actuation without additional tools
- ② **Locking bolt**
made of corrosion-free steel for easy and secure locking
- ③ **ISO mounting pattern**
Master and adapter side, for easy assembly to most types of robots without needing additional adapter plates
- ④ **Integrated locking and tool presence monitoring**
optional, for process-reliable monitoring of the locking condition and tool presence
- ⑤ **Integrated air feed-through**
all can be used radially and axially for pneumatics and vacuum.
- ⑥ **Standardized screw-on surface for direct attachment of electrical, pneumatic and fluid modules**
Enables versatile energy transmission for controlling a wide range of tools

General notes about the series

Actuation: Manual via locking lever

Operating principle: The head and adapter are locked and unlocked with a pin by operating the manual lever.

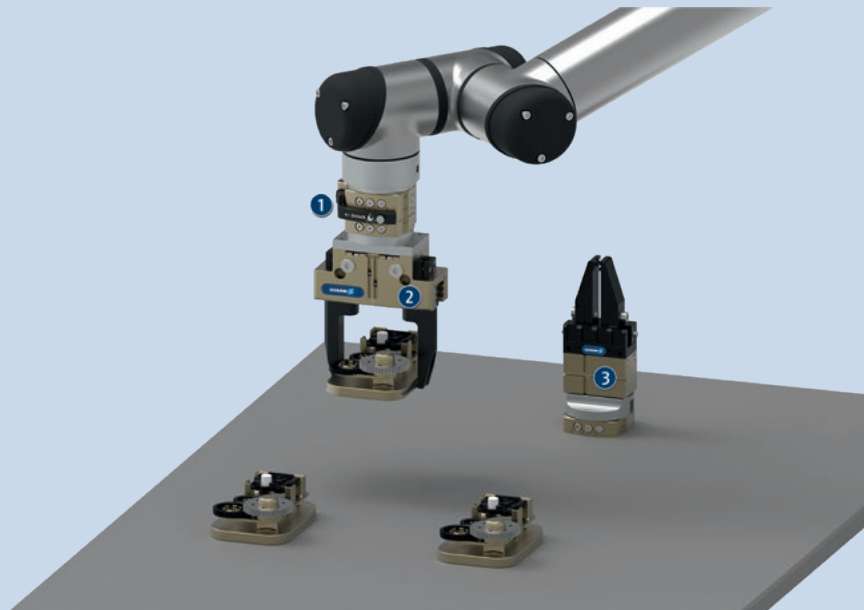
Media transmission:: Pneumatic and vacuum feed-through integrated in the housing. Other media such as signals or fluids possible via option modules (SW0).

Housing: The housing consists of high-strength, hard-coated aluminum alloy. The functional components are made of hardened steel.

Warranty: 24 months

Harsh environmental conditions: Please note that use under harsh environmental conditions (e.g. in the coolant area, cast and grinding dust) can considerably reduce the service life of the units, and we will not take over any warranty. However, in many cases we can find a solution. Please contact us for assistance.

Handling weight: is the weight of the total load attached to the flange. When designing, the permissible forces and moments have to be paid attention to. Please note that exceeding the recommended handling weight will shorten the lifespan.



Application example

Tool for handling and assembling small to medium-sized workpieces, consisting of manual change system and gripper.

- 1 Manual change system CMS
- 2 2-finger parallel gripper PGN-plus-P with customized gripper fingers
- 3 2-finger parallel gripper MPG-plus with customized gripper fingers

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Rotary feed-through



Compensation unit



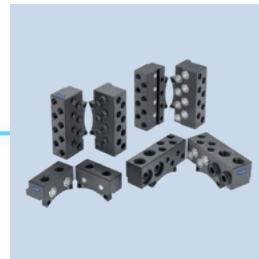
Anti-collision and overload protection sensor



Universal gripper



Inductive proximity switches



Fluid module



Electronic module

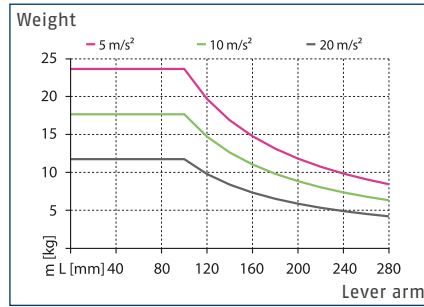
For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

Basic version: simplified version without integrated air ducts and without monitoring options for maximum economy.
SHA version (-N): with the same tool-sided screw connection diagram as the predecessor product SHA. Allows simple replacement of existing SHS systems with the CMS without changing the customer-specific tools. The SHA version differs from the basic design only on the adapter side (CMS-A).

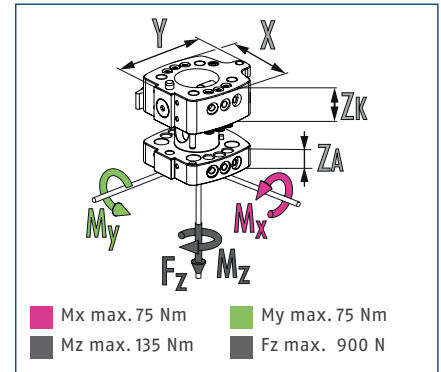


Load diagram



Maximum handling weight as a function of acceleration and lever arm (by Mx/My). The diagram does not replace the technical design.

Dimensions and maximum loads



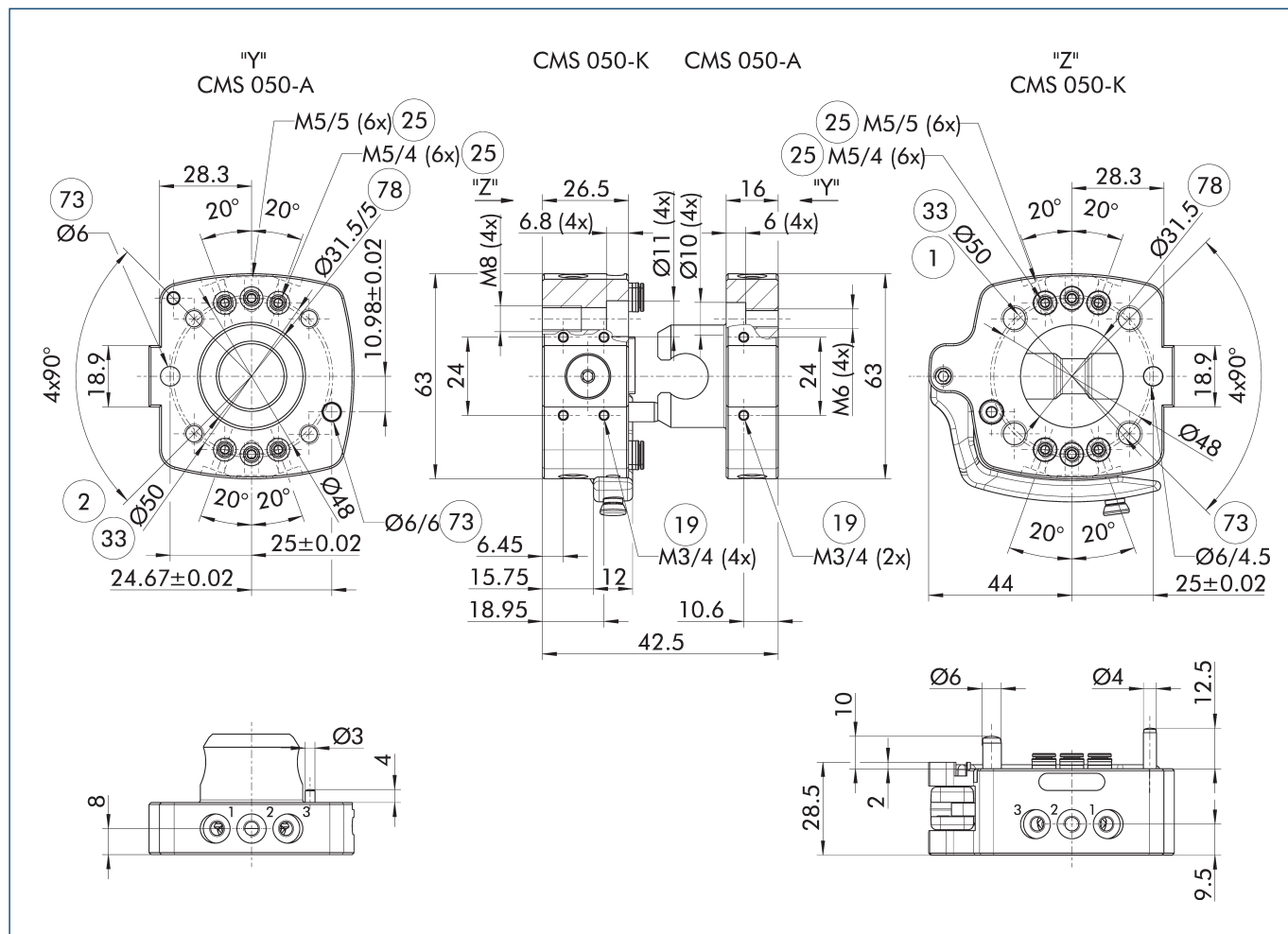
ⓘ This is the sum of all static loads that are permitted to act on the change system to ensure error-free functioning.

Technical data

Description		CMS 050-K	CMS 050-A
		Manual change head	Manual change adapter
ID		1545289	1545310
Recommended handling weight	[kg]	11	11
Lock sensing		optional	
Tool presence monitoring		optional	
Repeat accuracy	[mm]	0.02	0.02
Weight	[kg]	0.27	0.14
Number of pneumatic feed-throughs		6	6
Feed-throughs for radial use		6	6
Air connection thread pneumatic feed-through (radial)		M5	M5
Robot-side coupling flange		ISO 9409-1-50-4-M6	
Coupling flange, tool side			ISO 9409-1-50-4-M6
Dimensions X x Y x Z*	[mm]	63/75.5/26.5	63/63/16
Min./max. ambient temperature	[°C]	5/60	5/60
Screw connection diagram		S7	S7
Max. dynamic moment Mx/My	[Nm]	35	35
Max. dynamic moment Mz	[Nm]	27	27
Options and their characteristics			
Basic version		CMS 050-K-B	CMS 050-A-B
ID		1545314	1545315
Weight	[kg]	0.27	0.15
SHA version (-N)			CMS 050-A-N
ID			1545313
Weight	[kg]		0.14
Tool-side connection			∅50, 4xM8

* Please note that the heights of the change master (Zk) and change adapter (Za) differ. The sum represents the total height of a coupled change system.

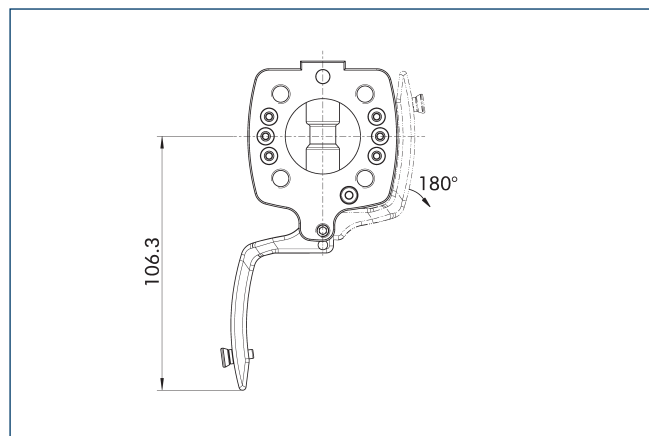
Main view



The main view shows the unit in its basic version.

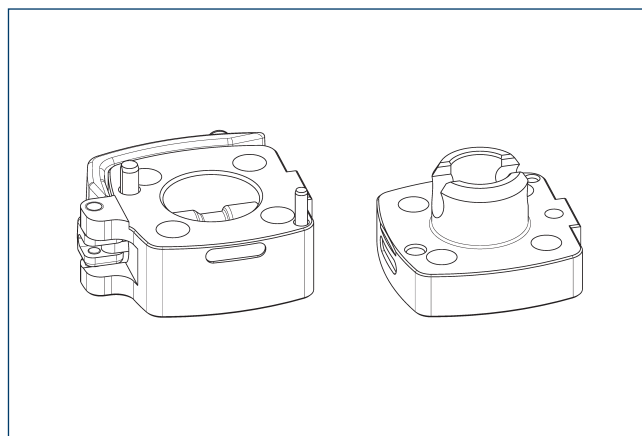
- ① Robot-side connection
- ② Tool-side connection
- ③ DIN ISO-9409 bolt circle
- ⑦ Fit for centering pins
- ⑧ Fit for centering
- ⑨ Mounting surface for options
- ⑫ Pneumatic feed-throughs

Interference Contour when locking/unlocking



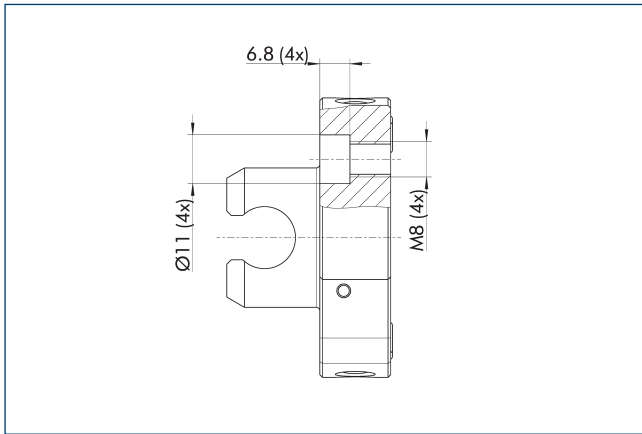
The drawing shows the interfering contour when locking and unlocking. The specified values may vary depending on the opening angle of the locking lever.

Basic version (-B)



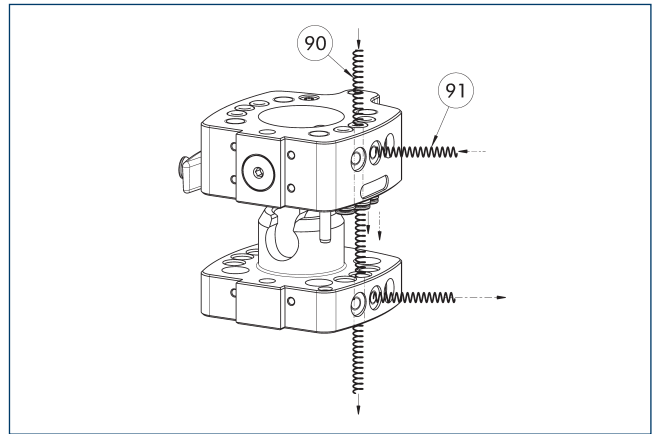
The basic version is a simplified basic design variant without integrated air feed-throughs and without monitoring options.

SHA version (-N)



The SHA version has the same screw-on pattern on the tool side as the predecessor product SHS. Thus, existing SHS systems can be replaced by the CMS without changing the tools.

Pneumatic feed-through

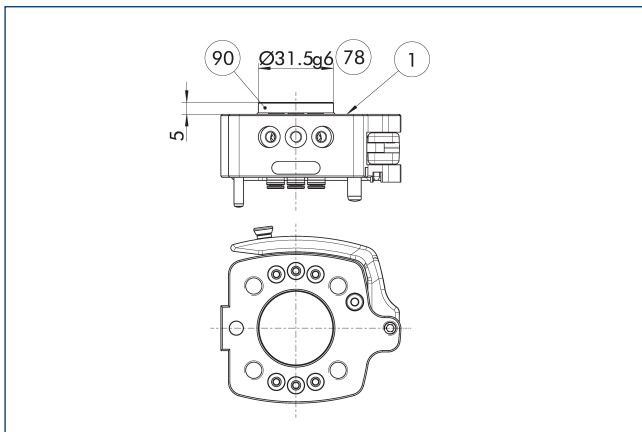


90 Feed-through axial

91 Feed-through radial

The change system has feed-throughs for pneumatics integrated in the housing. They can be used hose-free via an adapter plate (axial) or with a hose (radial). Vacuum feed-through is also possible on request. Please ask for details.

Centering collar on CMS-K



1 Robot-side connection

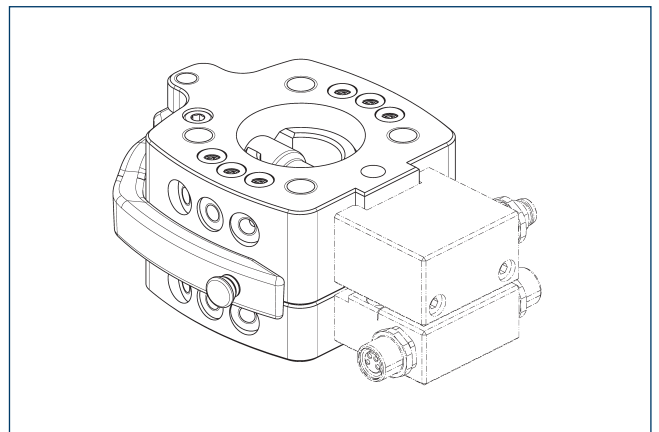
90 Centring disc

78 Fit for centering

Description	ID
Centering disc	
A-HWK-050-BOSS	0302752

1 Serves as a fitting collar for centering on mechanical interfaces, e. g. on the robot.

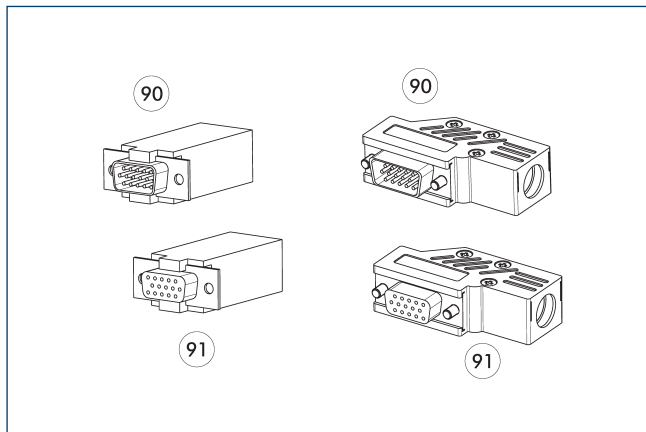
Electric feed-through module



Description	ID	No. Pins
Feed-through module for signal on the robot side		
SW0-A15-K	9936357	15
SW0-E10-011-K	9935801	10
SW0-E20-011-K	9936525	20
SW0-EM8-011-K	9966153	8
SW0-ML12R-K	1426575	12
SW0-ML8A-K	1426624	8
Feed-through module for signal on the tool side		
SW0-A15-A	9936356	15
SW0-E10-011-A	9935802	10
SW0-E20-011-A	9936526	20
SW0-EM8-011-A	9966154	8
SW0-ML12R-A	1426576	12
SW0-ML6-A	1426626	6
SW0-ML8A-A	1426625	8

1 For more detailed information and further modules and matching cable connectors, see catalog chapter "SW0" or visit our website.

Cable connector



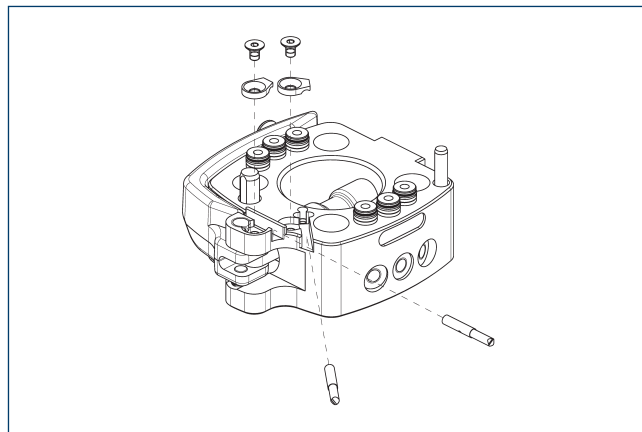
90 D-sub connecting plug

91 D-sub connector

Description	ID
Angled cable connector, robot-side	
KAS-A15-K-90	0301301
Angled cable connector, tool-side	
KAS-A15-A-90	0301302
Straight cable connector, robot-side	
KAS-A15-K-0	0301264
Straight cable connector, tool-side	
KAS-A15-A-0	0301265
Cable extension	
KV-2-SWA-08G-M8-0	0302181
KV-2-SWA-08G-M8-90	0302183
KV-5-SWK-08G-M8-0	0302180
KV-5-SWK-08G-M8-90	0302182

① For more detailed information and other cable connectors, see catalog chapter "SWO" or visit our website.

Monitoring via inductive proximity switches



The CMS-K is prepared for locking monitoring as well as tool presence. One attachment kit each is required for this. Each attachment kit includes one sensor and one bracket incl. a screw.

Description	ID
Robot side	
AS-CMS-K-IN30K	1548743

① This attachment kit is optional and must be ordered separately as an accessory.



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