

The DOBOT M1 Pro industrial robot is fast, precise and reliable. Whether for pick and place, dispensing, separating or sorting in a laboratory, with its 4 axes it is used in a wide variety of applications. Compared to multi-axis robots, the kinematics calculation in space is much simpler. It is robust, fast, requires little space, has a high repeat accuracy and, in addition to simple operation, is probably the most cost-effective start in this robot classification. With its reduced amortization period, it offers small and medium-sized businesses in particular the possibility of cost-efficient automation.

We are available for you by mail and during our opening hours by phone.

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## **DOBOT M1 Pro. Technical specifications.**

4

1.5 kg

400 mm

**Number of Axis** 

**Payload** 

Reach

itodon	400 111111	
Repeatability	± 0.02 mm	
Working Temperature	0° C - 40° C	
Base Dimensions	230 mm x 175 mm	
Weight without Tools	15.7 kg	
Software	DobotStudio Pro	
Programming	Blockly, LUA, SDK (Python 3)	
Communication	TCP/IP, Modbus TCP	
Power Input	100 V - 240 V AC, 50/60 Hz	
Rated Voltage	48 VDC	
Rated Power	150 W	
Max. Output current via single digital output road / summarized over all outputs	0.5 A / 2 A	
Max. Ouput current between 24 V and GND pin	2 A	
Electrical design	PNP	
Joing Range	J 1 (rear arm)	±85°
	J 2 (forearm)	±135 °
	J 3 (lift)	5 mm ~ 245 mm
	J 4 (rotation servo)	±360 °
Max. Speed	J 1 (rear arm)	180°/s
	J 2 (forearm)	180°/s
	J 3 (lift)	1000 mm / s
	J 4 (rotation servo)	1000° / s
Base I/O Interface	Digital Input	16
	Digital Output	16
	Ethernet	2
	USB	2
	Encoder Input (ABZ-Encorder)	1
Forearm I/O Interface	Digital Input	4
	Digital Output	4
	RS 485 (Modbus RTU)	1

Misprints and technical changes reserved. Status: 04/2023

## Scope of delivery

DOBOT M1 Pro

Ethernet cable

Flange adapter

Emergency stop

Power supply

Tool kit

Documentation (Shipping list, quick start guide, etc.) - english/chinese

(vacuum pump is not included in the scope of delivery)

