

Superior Clamping and Gripping



Product Information

Gripper for small components MPG-plus 40

Powerful. Fast. Long fingers.

Gripper for small components MPG-plus

2-finger parallel gripper with smooth roller guides of the base jaws

Field of application

Gripping and moving of small to medium-sized workpieces in low contaminated environments, such as assembly, testing, laboratory and pharmaceutical industry

Advantages - Your benefits

Cross roller guidance for precise gripping through due to a scope-free base jaw guidance

Base jaws guided on double roller bearings ensuring low friction and smoothly running

Optimized basic load rating suitable for using long gripper fingers

Drive concept oval piston for maximum gripping forces

Monitoring with electronic magnetic switches for a maximized process reliability

Mounting from two sides in four screw directions for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Compact dimensions for minimal interfering contours in handling

NEW: food-grade lubrication as a solution for an easy entry into medical technology, lab automation, pharmaceutical and food industry













Functional description

The oval piston is moved up or down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, parallel jaw motion.



- Base Jaw
 for the connection of workpiece-specific gripper fingers
- ② Wedge-hook design for high force transmission and centric gripping
- ③ Cross roller guidance precise gripping due to backlash-free base jaw guidance
- Sensor system for monitoring two switching points
- 5 Oval piston drive for power generation
- 6 Housing is weight-optimized due to the use of high-strength aluminum alloy

General notes about the series

Operating principle: Wedge-hook kinematics **Housing material:** Aluminum alloy, anodized

Cover housing material: Steel

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per

ISO 8573-1:2010 [7:4:4]. **Warranty:** 24 months

Service life characteristics: on request

Scope of delivery: Centering sleeves, 0-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Pneumatic pick & place unit for small components.

- Pillar assembly system
- 2 Linear module CLM
- 3 2-finger parallel gripper MPG-plus



SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.











Rotation unit

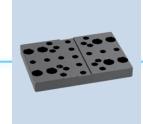
Linear module

Pick & Place Unit

Manual change system









Attachment valve

Pressure maintenance valve

Adapter plate

Finger blank







① For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

Optional adapter plates: allows frontal mounting of the gripper

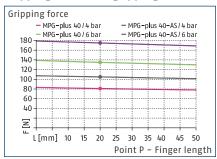
Precision version P: for the highest accuracy

Version FPS for flexible position sensor: This version is prepared for the use with the flexible position sensor FPS, and allows monitoring of several gripping positions.

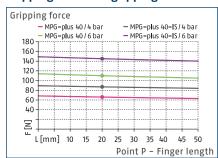
protective cover version HUE: Fully protects the gripper against external influences **Food-grade lubrication:** The requirements of EN 1672-2:2020 are not fully met.



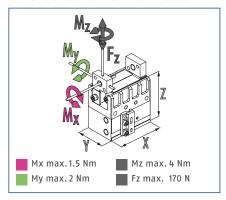
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads

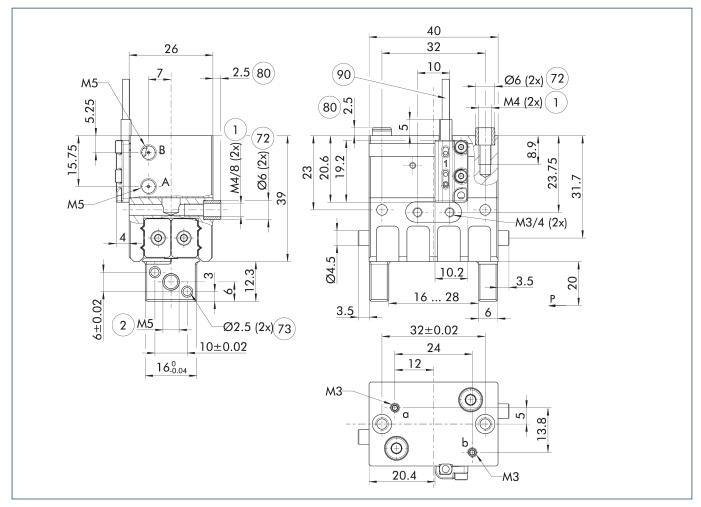


The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		MPG-plus 40	MPG-plus 40-AS	MPG-plus 40-IS
ID		0305521	0305522	0305523
Stroke per jaw	[mm]	6	6	6
Closing/opening force	[N]	135/110	170/-	-/135
Min. spring force	[N]		35	25
Weight	[kg]	0.18	0.24	0.24
Recommended workpiece weight	[kg]	0.7	0.7	0.7
Fluid consumption double stroke	[cm³]	4.1	10.7	10
Min./nom./max. operating pressure	[bar]	2/6/8	4/6/6.5	4/6/6.5
Closing/opening time	[s]	0.04/0.04	0.045/0.075	0.075/0.045
Closing/opening time with spring	[s]		0.20	0.20
Max. permissible finger length	[mm]	50	50	50
Max. permissible weight per finger	[kg]	0.08	0.08	0.08
IP protection class		30	30	30
Min./max. ambient temperature	[°C]	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02
Cleanroom class ISO 14644-1:2015		6	6	6
Dimensions X x Y x Z	[mm]	40 x 26 x 39	40 x 26 x 63.75	40 x 26 x 63.75
Options and their characteristics				
High-temperature version		39305521	39305522	39305523
Min./max. ambient temperature	[°C]	5/100	5/100	5/100
Precision version		0305526	0305528	0305529
protective cover version HUE		1460637	1460639	1460640
Weight	[kg]	0.27	0.33	0.33
IP protection class		54	54	54
Max. permissible weight per finger	[kg]	0.05	0.05	0.05
Dimensions X x Y x Z	[mm]	69 x 41.5 x 56.5	69 x 41.5 x 81.25	69 x 41.5 x 81.25

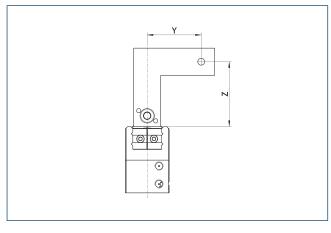
Main view

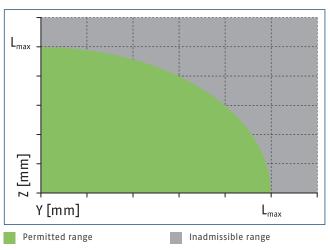


The drawing shows the basic version of the gripper with open jaws, without dimensional consideration of the options described below.

- ① The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- (1) Gripper connection
- (2) Finger connection
- 72 Fit for centering sleeves
- (73) Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 MMS 22...-PI2-... sensor

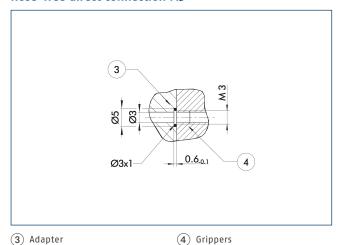
Maximum permitted finger projection





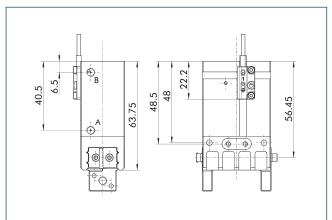
 L^{max} is equivalent to the maximum permitted finger length, see the technical data table.

Hose-free direct connection M3



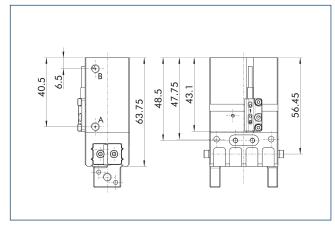
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Gripping force maintenance IS



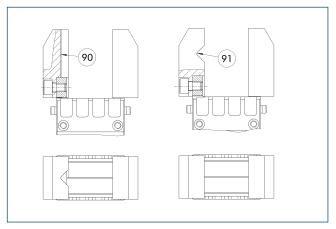
The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

Gripping force maintenance AS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

Jaw design

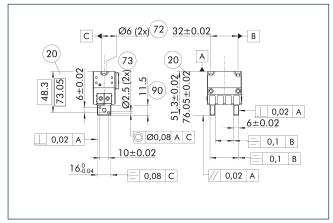


90 Vertically positioned prism

(91) Horizontally positioned prism

A workpiece, which is gripped using three points of contact, can be reliably gripped with high repeatability. A system with more than three points of contact is overdetermined. The drawing shows two alternative gripper finger designs for coaxial and radial gripping of a cylindrical part.

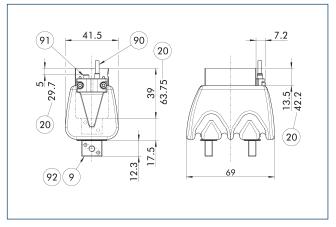
Precision version



- 20 For AS / IS version
- (72) Fit for centering sleeves
- (73) Fit for centering pins
- 90 Length of the usable finger

The indicated tolerances just refer to the variants of precision versions shown in the chart of technical specifications. All other variants of precision versions are available on request.

Protection cover HUE



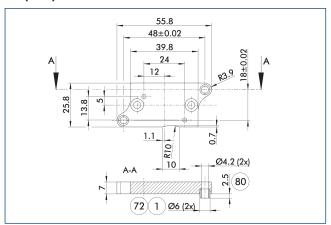
- (9) For mounting screw connection diagram, see basic version
 - (91) Cylindrical pins
- 20 For AS / IS version
- (92) Intermediate jaw (stainless

90 Sensor IN ...

The HUE protection cover fully protects the gripper against external influences. The assembly diagram shifts by the height of the intermediate jaw. The finger length is still measured from the upper edge of the gripper housing. The protection cover is a wear part and can be ordered separately as a spare part.

① Two sensors are required per unit for monitoring two positions. Only sensors from the IN 40 series can be used. The gripper is prepared for this, and no additional mounting kit is required. Monitoring with magnetic sensors is not possible. The bracket for magnetic sensors is not included in the scope of delivery. If the gripper is used without a sensor, the two cylindrical pins (item 91) must not be removed so that the IP protection class of the product remains guaranteed.

Adapter plate

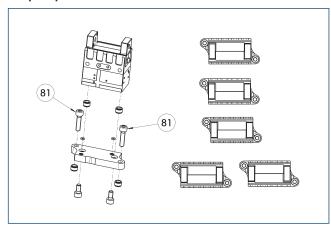


- (1) Gripper connection
- (80) Depth of the centering sleeve hole in the counter part
- (72) Fit for centering sleeves
- The adapter plate includes an O-ring* for a direct air connection, additional centering sleeves, and screws for mounting the gripper. *Optional only with pneumatic actuators

Description ID Adapter plate APL-MPG-plus 40 0305527

① The adapter plate is a separately ordered, optional accessory.

Adapter plate

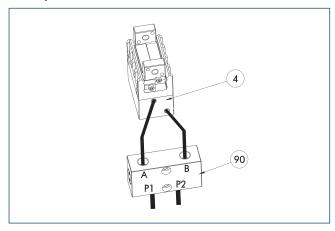


(81) Not included in the scope of delivery

The adapter plate includes an O-ring* for a direct air connection, additional centering sleeves, and screws for mounting the gripper.*Optional only with pneumatic actuators

(i) The adapter plate is a separately ordered, optional accessory.

SDV-P pressure maintenance valve



The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

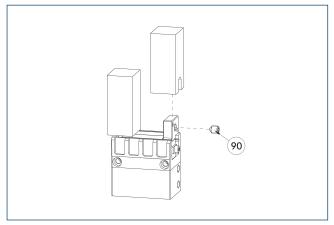
(90) SDV-P pressure maintenance

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance	e valve	
SDV-P 04	0403130	6
Pressure maintenance	valve with a	ir bleed screw
SDV-P 04-E	0300120	6

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

Finger blanks with BSWS

4 Grippers

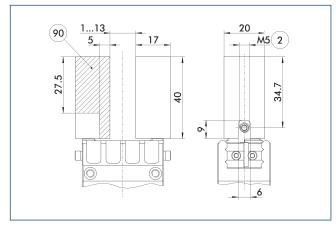


90 Included in the jaw quickchange system's scope of delivery

The finger blanks with jaw quick-change system allow fast and manual gripper finger changes. The mechanical interface to the gripper is already integrated. Only the specific workpiece geometry needs to be machined into the finger blank.

Description	ID	Scope of delivery
Finger blank with jaw quick-	change syster	n
ABR-BSWS-MPG-plus 40	0302896	2

Finger blanks with BSWS ABR-BSWS-MPG-plus 40



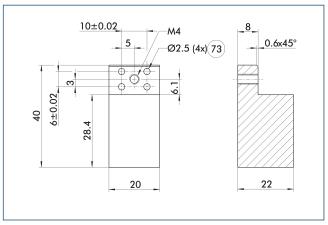
2 Finger connection

90 Machining volume

Finger blanks for customized subsequent machining with integrated jaw quick-change system for precise and fast finger changes.

Description	ID	Scope of delivery
Finger blank with jaw quick	-change syste	m
ABR-BSWS-MPG-plus 40	0302896	2

Finger blanks ABR-MPG-plus 40

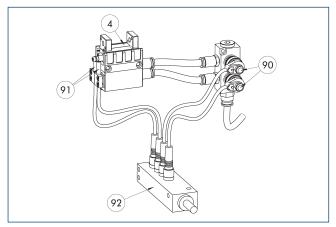


(73) Fit for centering pins

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-MPG-plus 40	0340213	Aluminum (3.4365)	2

Attachment valves



- (4) Grippers
- 90 Micro valves
- 90 Micio valves
- 91) Sensor

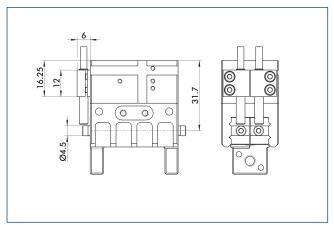
- 92 Sensor distributor
- 93 Y distributor

The set of attachment valves reduces the compressed air consumption as there is no need to ventilate or bleed the supply lines. This can also reduce cycle time. The hose-free direct assembly of the micro valves reduces the hosing effort for the gripper. To further simplify electrical connection of the valves and sensors, their signals can be bundled via an optional distributor.

Description	ID	Often combined
Add-on valve set		
ABV-MV15-S2-M5	0303375	
ABV-MV15-S2-M5-V2-M8	0303376	
ABV-MV15-S2-M5-V4-M8	0303377	•
ABV-MV15-S2-M5-V8-M8	0303378	

A set of add-on valves ABV is required per actuator. The ABV set contains two 3/2 micro valves, a valve base, pneumatic screw connections, and optionally a sensor distributor with two, four or eight inputs or outputs. Sensors for monitoring the gripper need to be ordered separately. Pneumatic hoses are not included in the scope of delivery.

Attachment kit for proximity switch IN 40

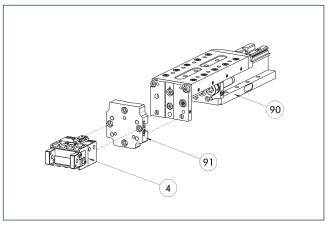


The attachment kit includes a bracket, switch cams, and mounting screws. Proximity switches have to be ordered separately.

Description	ID
Attachment kit for proximi	y switch
AS-IN40-MPG-plus 40	0305525

① This attachment kit needs to be ordered optionally as an accessory.

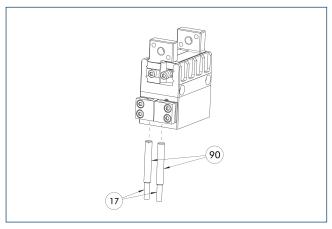
Modular Assembly Automation



- (4) Grippers
- 91) ASG adapter plate
- 90 CLM/KLM/LM/ELP/ELM/ELS/HLM linear modules

Grippers and linear modules can be combined with standard adapter plates from the modular assembly system. For more information see our main catalog "Modular Assembly Automation".

IN 40 inductive proximity switches



(17) Cable outlet

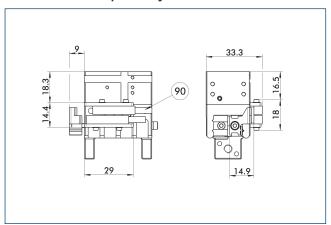
90 Sensor IN ...

End position monitoring can be mounted with an attachment kit.

Description	ID	Often combined
Attachment kit for proximit	ty switch	
AS-IN40-MPG-plus 40	0305525	
Inductive proximity switch	es	
IN 40-S-M12	0301574	
IN 40-S-M8	0301474	•
INK 40-S	0301555	

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

Attachment kit for proximity switch IN 5



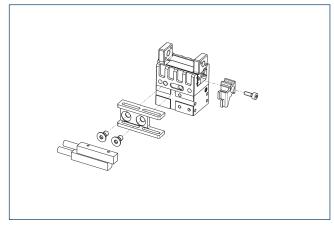
90 Sensor IN ...

The attachment kit includes a bracket, switch cams, and mounting screws. Proximity switches have to be ordered separately.

Description	ID
Attachment kit for proxim	ity switch
AS-IN5-MPG-plus 40	0340152

① This attachment kit needs to be ordered optionally as an accessory.

IN 5 inductive proximity switches

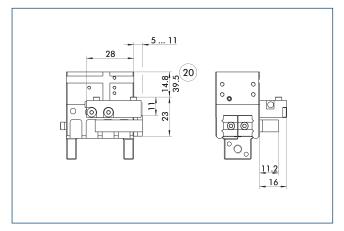


End position monitoring can be mounted with an attachment kit.

Description	ID	Often combined
Attachment kit for proxin	nity switch	
AS-IN5-MPG-plus 40	0340152	
Inductive proximity swite	:hes	
IN 5-S-M12	0301569	
IN 5-S-M8	0301469	•
INK 5-S	0301501	•

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

Attachment kit for FPS



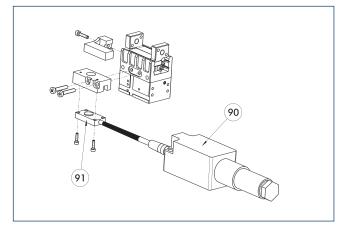
20 For AS / IS version

The following FPS position sensor can differentiate between five programmable areas or switching points for the stroke of a gripper, and can be used in connection with a PC as a measuring system.

Description	ID
Attachment kit for FPS	
AS-FPS-MPG-plus 40	0301762

① This attachment kit needs to be ordered optionally as an accessory.

Flexible position sensor



90 FPS-F5 evaluation electronic

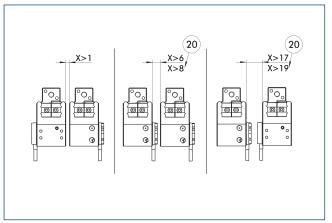
(91) FPS-S sensor

Flexible position monitoring of up to five positions.

Description	ID	Often combined
Attachment kit for FPS		
AS-FPS-MPG-plus 40	0301762	
Sensor		
FPS-S 13	0301705	
Evaluation electronics		
FPS-F5	0301805	•
Cable extension		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	

When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available - see catalog chapter "Accessories."

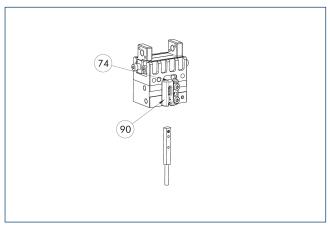
Monitoring for stacked arrangements



20 For AS / IS version

CAUTION: Monitoring is carried out by magnetic switches, and in case of side-by-side assembly of several units, a minimum distance of X mm between the units must be maintained.

Programmable magnetic switch MMS 22-PI2



74 Limit stop for sensor

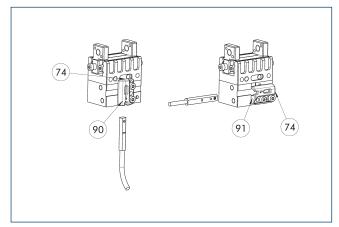
90 Vertical attachment of the bracket

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	•
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI2-S-M8-PNP-SA	0301186	
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI2-S-M8-PNP-HD	0301130	
MMSK 22-PI2-S-PNP-HD	0301132	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



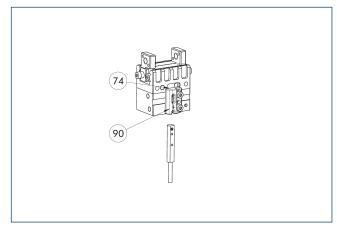
- (74) Limit stop for sensor(90) Vertical attachment of the
- (91) Horizontal attachment of the bracket

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic swit	ch	
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	•
Connection cables		
KA GLN0804-LK-00500-A	0307767	•
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

The bracket (90) is delivered vertically mounted. To use the magnetic sensor in a horizontal orientation, the bracket can be horizontally assembled (91). The mounting bracket has an internal stop for the MMS-P (74).

Analog position sensor MMS-A



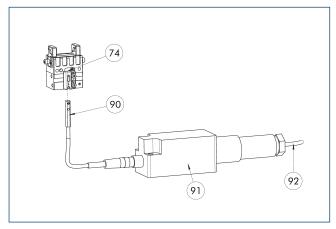
- 74 Limit stop for sensor
- 90 Vertical attachment of the bracket

No-contact measuring, analog multi-position monitoring for any number of positions.

Description	ID
Analog position sensor	
MMS 22-A-10V-M08	0315825
MMS 22-A-10V-M12	0315828

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

Flexible position sensor with MMS-A



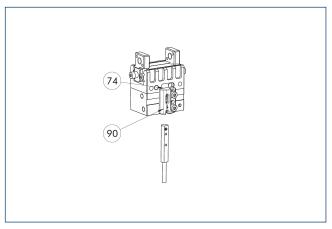
- 74) Limit stop for sensor
- (91) FPS-F5 evaluation electronic
- 90 MMS 22-A-... sensor
- 92 Connection cables

Flexible position monitoring of up to five positions.

Description	ID
Analog position sensor	
MMS 22-A-05V-M08	0315805
Evaluation electronics	
FPS-F5	0301805
Connection cables	
KA BG16-L 12P-1000	0301801

When using an FPS system, one MMS 22-A-05V and one electronic processor (FPS-F5) are required per each gripper, as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter "Accessories."

Programmable magnetic switch MMS-I0-Link



74 Limit stop for sensor

90 Vertical attachment of the bracket

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

Gripper for small components



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