



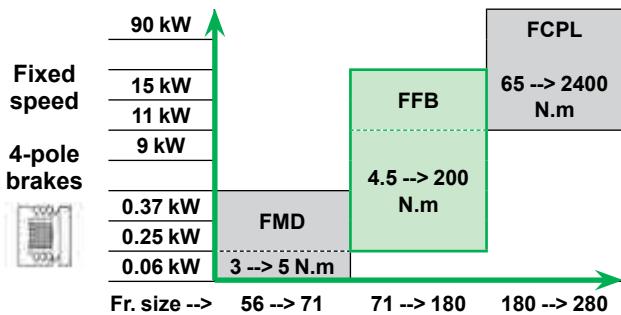
## IMfinity® FFB Brake motors

Standard Efficiency Not Concerned by IE Standards and IE3 High Efficiency  
**Variable speed and Fixed speed**  
Frame size from 71 to 180  
Power from 0.25 to 18.5 kW

**LEROY-SOMER™**

**Nidec**  
All for dreams

## Brake Ranges



### Associated documentations

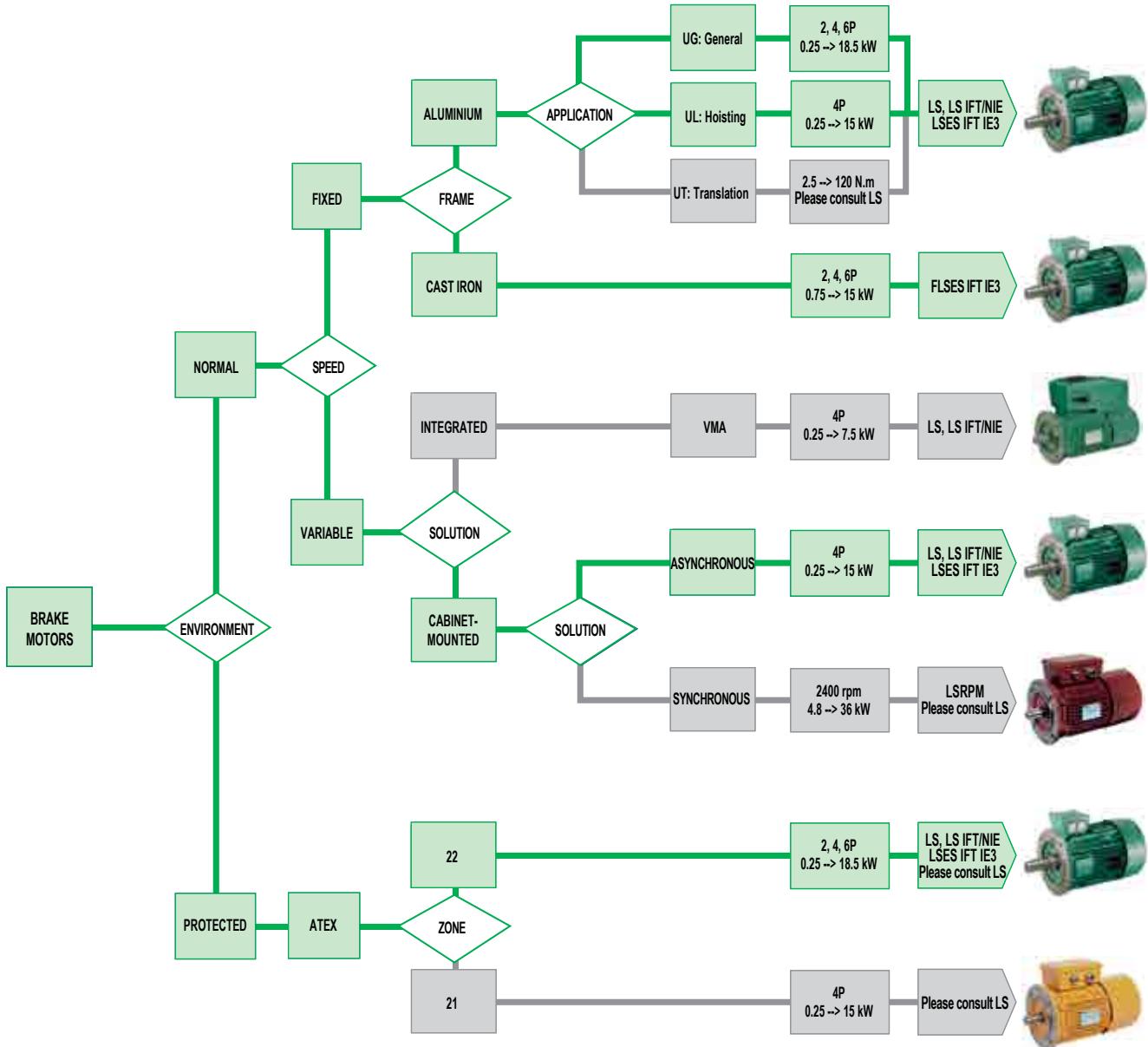
Environment		Commissioning		
Normal	Dust-protected	FFB installation	FFB maintenance	Ex II3D II2D
FFB brochure	FFB catalog	5281	5286	5287
				Pending



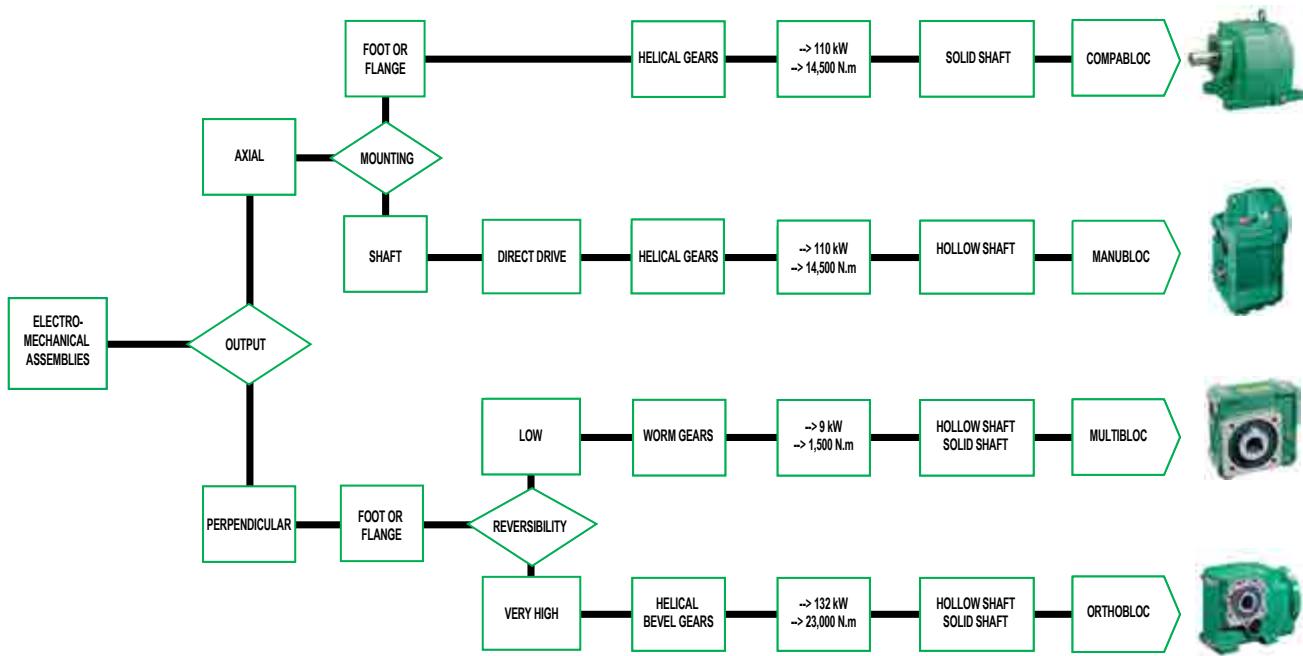
All brake motors in this catalogue that don't fall within the scope of regulation 640/2009 in directive 2009/125/EC they can be offered for sale\* on the European Union market.

\* according to the definition relating to application of European Union regulations concerning products

## FFB Brake Motors Offer



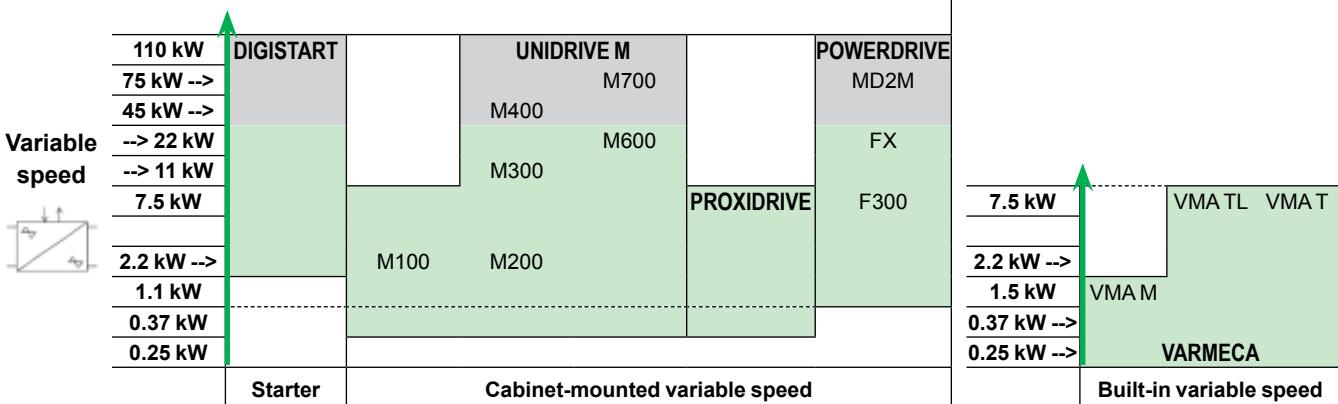
## Associated Gearbox Ranges



## Associated Drive Ranges

LS IFT/NIE,  
LSES IFT/IE3  
FLSES IFT/IE3

LS IFT/NIE



## Contents

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### INTRODUCTION

Offer, Range .....	2-3
Index .....	5
Glossary .....	6

### CONSTRUCTION

Mounting forms and operating positions .....	7
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### OPERATION

#### DEFINITION OF BRAKE MOTOR

Areas of use .....	8
Failsafe brake .....	8
Using the brake motor at constant torque (0 to 87 Hz).....	8

#### DUTY CYCLE DEFINITIONS

Duty cycles .....	9
S4 Operating Rates.....	10
No-Load Starting Frequency .....	10

#### ELECTROMAGNET CHARACTERISTICS

BRAKE POWER SUPPLY UNIT CHARACTERISTICS .....	11
Operating Principle .....	11
Definition of built-in or separate power supply .....	11

#### BRAKING TORQUES .....

#### MOMENT OF INERTIA .....

#### RESPONSE TIME WITH BRAKE ONLY AND STOPPING DISTANCE

Definition of Response Times .....	13
Response Time Values .....	14
Noise Level.....	14
Stopping Time and Distance Calculations .....	14
Brake Wear Calculation.....	14

#### LOADS APPLIED TO THE MOTOR (MAIN) SHAFT .....

#### EXAMPLE OF SELECTION .....

### IP55 ALUMINIUM FRAME

#### DESIGNATION .....

#### LS(ES) FFB DESCRIPTION .....

#### CHARACTERISTICS TABLES

LS FFB IFT/NIE - 4 Poles.....	18
LS FFB IFT/NIE - 2 Poles.....	20
LS FFB IFT/NIE - 6 Poles.....	21
LSES FFB IFT/IE3 - 4 Poles.....	22-23
LSES FFB IFT/IE3 - 2, 6 Poles.....	24

#### LS(ES) FFB DIMENSIONS

Foot mounted IM 1001 (IM B3).....	25
Flange mounted IM 3001 (IM B5).....	26
Face mounted IM 3601 (IM B14).....	27

### IP55 CAST IRON FRAME

#### DESIGNATION .....

#### FLSES FFB DESCRIPTION .....

#### CHARACTERISTICS TABLES

FLSES FFB IFT/IE3 - 4 Poles .....	30-31
FLSES FFB IFT/IE3 - 2, 6 Poles .....	32

#### FLSES FFB DIMENSIONS

Foot mounted IM 1001 (IM B3).....	33
Flange mounted IM 3001 (IM B5).....	34
Face mounted IM 3601 (IM B14).....	35

### EQUIPMENT AND OPTIONS

#### LIST AND COMPATIBILITY OF OPTIONS .....

#### MECHANICAL OPTIONS

Optional flanges for LS(ES) FFB, FLSES FFB series .....	37
Release systems .....	38-39
Optional braking torque .....	40
Indicator lamp (release/application, wear).....	40
Drip cover .....	40

#### ELECTRICAL OPTIONS

Sensors .....	41
Cable gland .....	42
Forced axial ventilation .....	42
Choice of speed feedback .....	43
Encoders characteristics .....	43
Encoders dimensions .....	42-43
Encoders connection .....	44

### IDENTIFICATION - INSTALLATION

#### IDENTIFICATION

Motor nameplate .....	45
Brake nameplate .....	45

#### EXPLODED VIEWS .....

#### PARTS LIST .....

#### INSTALLATION

Receipt .....	48
Storage .....	48
Commissioning .....	48
Mechanical installation .....	48
Wiring .....	48-49

#### PACKAGING WEIGHTS AND DIMENSIONS .....

### APPENDIX

Configurator.....	51
Express Availability.....	51

## Index

PAGES	PAGES
Air gap ..... 12, 13	Identification ..... 45
Ambient temperature ..... 12	Inertia ..... 16, 18-24, 30-32
Application ..... 16, 28	Ingress protection ..... 17, 39, 45
Application/release indicator ..... 36, 40	Installation ..... 48, 49
Approvals ..... 45	
ATEX ..... 2, 45	Lining ..... 12
Axial force ..... 15	Load on the shaft ..... 14
Brake motor at constant torque ..... 8	LS(ES) FFB UG/UL ..... 16-27
Brake power supply ..... 11	
Brake release ..... 14, 38, 40	Maintenance ..... 2
Brakes ..... 2, 8-49	Manual release ..... 14, 38, 40
Braking torque ..... 12, 18-24, 30-32, 40	Mb: Multibloc ..... 2
Cable gland ..... 7, 17, 29, 42	Moment of inertia ..... 13, 18-24, 30-32
Cb: Compabloc ..... 2	Mounting ..... 7, 25-27, 33-35
CE ..... 45	Mub: Manubloc ..... 2
Characteristics ..... 11, 18-24, 30-32	Nameplates ..... 45
Choice of speed feedback ..... 43	Noise ..... 14
Components ..... 17, 29, 46, 47	No-load starting frequency ..... 10
Configurator ..... 51	Number of braking operations ..... 12
Connection diagrams ..... 11, 13, 49	
CSA ..... 45	Operating positions ..... 7
Definition of symbols ..... 7, 45	Options ..... 36-44
Description ..... 17, 29	Ot: Orthobloc ..... 2
Designation ..... 16, 28	
Dimensions of options ..... 37-44	Packaging ..... 50
Dimensions ..... 25-27, 33-35	Parts list ..... 47
Direction of rotation ..... 17, 29	Possible flanges ..... 26, 27, 34, 35, 37
Drain holes ..... 17, 29, 36	
Drip cover ..... 36, 40	Reduced brake response time ..... 14
Drive power supply ..... 18, 19-22, 23-30, 31	Release lever ..... 38, 39
Drives ..... 2	Release systems ..... 38, 39
Duty cycles ..... 9, 10	Running-in ..... 13
Electromagnet ..... 11	
Encoders ..... 43, 44	Safety ..... 8
Environment ..... 12	Selection data ..... 18-24, 30-32
Equipment ..... 36-44	Selection tables ..... 18-24, 30-32
Example of selection ..... 15	Sensors ..... 36, 41
Exploded views ..... 46	Starting ..... 10
Express Availability ..... 51	Storage ..... 48
External finish ..... 17, 29	
Flange form ..... 7, 26, 27, 34, 35, 37	Terminal box ..... 17, 19
FLSES FFB UG/UL ..... 28-35	
Foot form ..... 7, 25, 33	UG general applications ..... 8, 16, 17, 28, 29
Forced ventilation ..... 36, 38, 42, 43	UL hoisting applications ..... 8, 11, 16, 17, 28, 29
Ground terminal ..... 17, 29	
Grounding ..... 12	Variable speed ..... 8, 18-24, 30-32, 49
Help in defining your order ..... 15	
Holding the load ..... 8	Wear indicator ..... 36, 40
Humidity ..... 12	Wear ..... 15

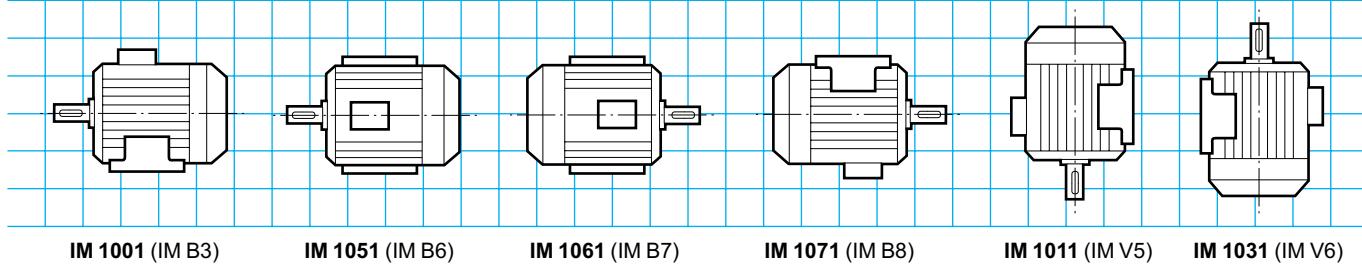
## Glossary

BA	Shaft extension
Cb	Compabloc
Cos φ	Power factor
FLSES	Cast iron motor series
OF	Operating factor (%)
F <sub>d</sub>	Starting frequency
F <sub>J</sub>	Inertia factor
η	Efficiency
R.H.	Relative humidity
Fr. S	Frame size
I <sub>d</sub>	Starting current
I <sub>n</sub>	Rated current
J	Moment of inertia
J <sub>C</sub>	Moment of inertia of the driven load
kg	Brake motor weight
KVA <sub>n</sub>	Apparent rated power
kW	Kilowatt
LS(ES)	Aluminium motor series
M <sub>a</sub>	Pull-up torque
Mb	Multibloc
M <sub>d</sub>	Starting torque
M <sub>f</sub>	Braking torque
M <sub>m</sub>	Maximum torque
M <sub>n</sub>	Rated torque
M <sub>R</sub>	Resistive torque

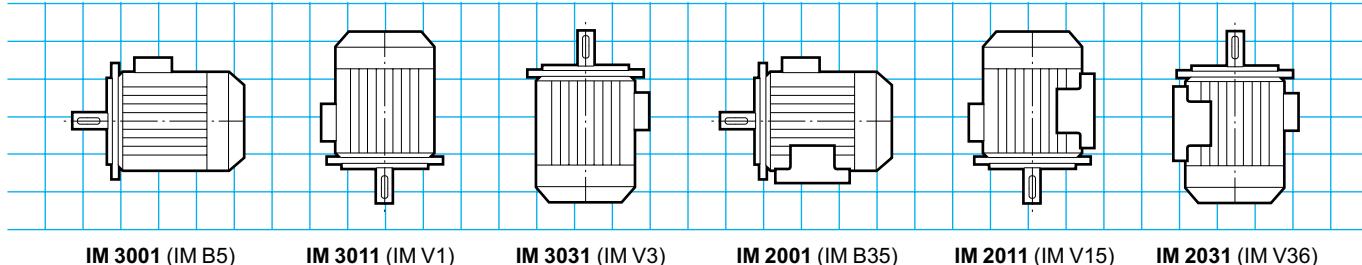
Mub	Manubloc
m	Weight
n	Number of starts
NIE	Not in any efficiency class
N <sub>n</sub>	Rated speed
ω <sub>N</sub>	Angular speed of the motor
Ot	Orthobloc
P <sub>n</sub>	Rated power
P <sub>u</sub>	Output power
T	Cycle time
T.A.	Ambient temperature
t	Travel time
t <sub>1</sub>	Release response time
t <sub>2</sub>	Application response time
t <sub>2 DC</sub>	Application response time with DC switch-off
t <sub>c</sub>	Total cycle time
t <sub>f</sub>	Braking time
t <sub>m</sub>	Motor running time in the cycle
U.G.	General applications
U.L.	Hoisting applications
v	Linear speed (m/s)
Z <sub>c</sub>	Cycle starting frequency
Z <sub>o</sub>	Brake motor starting frequency
Z <sub>oc</sub>	Cycle equivalent starting frequency

## Mounting Arrangements

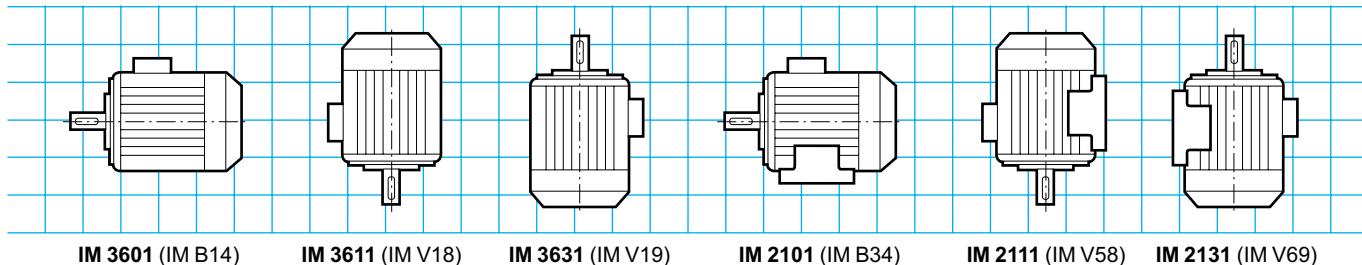
### Foot mounted



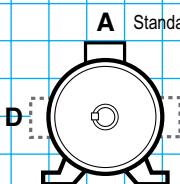
### Flange mounted (FF)



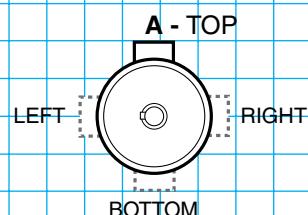
### Face mounted (FT)



Terminal box positions

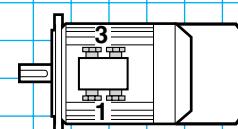


Foot mounted motor  
A - Top: standard



Flange mounted motor  
A - Top: Standard

Optional cable gland positions



1 - Right  
3 - Left

## Definition of the Brake Motor

The brake motor combines, in a single electromechanical assembly

- a motor: rotor + stator which forms the drive mechanism
- a control device: electromagnet + springs which apply or release the brake,
- friction: lining + mating surface which provide the braking action.

### AERAS OF USE

• Intermittent duty: a mechanical device driven by a motor on its own takes a long time to stop if there is little friction. The brake motor ensures **shorter, accurate and safe stopping times**. It is used in handling where accuracy on stopping is required, and on production lines where the basic operations should be as done as quickly as possible.

• Emergency stops: on dangerous machinery such as presses, machine-tools, woodworking machines, the brake motor brings the machinery to a stop almost instantly and ensures **the operator's safety**. The brake motor can also improve product quality and the machine usage rate.

Indeed, on machines operating at continuous flow (printing or production line), **stopping quickly when a defect or fault appears** limits the effects and reduces the time taken to get started again.

• Holding a device under load: the brake motor can be used to hold the motor in standstill position, even if torque is still applied. Since the motor is powered off in UL hoisting applications (hoists, elevators, elevating platforms, etc.), the brake stops and then **holds the load**.

### **RESTRICTION OF USE IN HOISTING APPLICATION:**

According to the standard NF EN 13135 Ed. April, 2013, the starting torque ( $M_d$ ) as well as pull-up torque ( $M_a$ ) have to be at least 1.6 times superior at the rated torque ( $M_n$ ) of the application (Refer to the characteristics tables).

Consequently, the choice of the brake motor has to respect these regulations and is of the responsibility of the integrator of the equipment.

### FAILSAFE BRAKE

It brakes when the power is switched off, and can stop the motor and the driven machine and keep them immobile. When the brake motor power is switched on, the electromagnet attracts the armature, compresses the springs and releases the brake.

When the brake motor power is switched off, the electromagnet lets the armature go. The thrust from the springs generates friction between the brake disk, the armature and the backplate, resulting in braking.

Braking is brought about by the thrust from springs, hence without external energy input. This is safety braking: it is the most commonly used control mode.

### Use with variable speed:

The brake must be supplied separately from the motor. The brake is controlled by the drive (see Installation section).

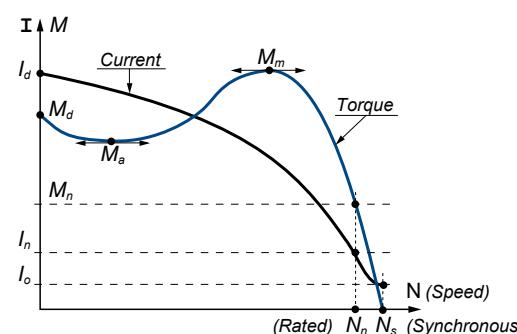
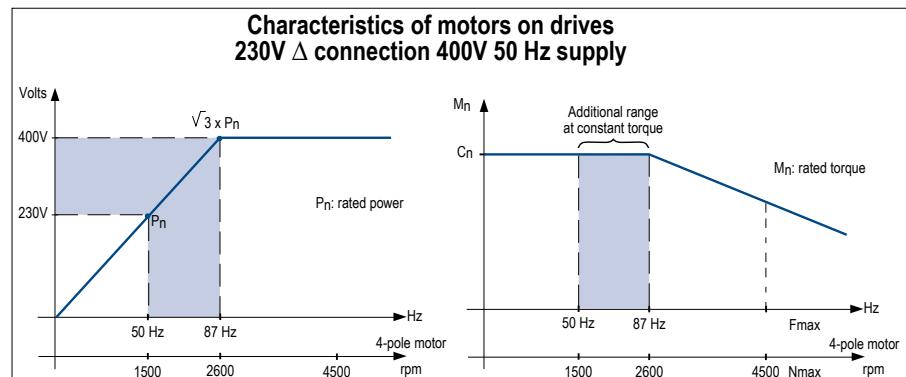
### USING THE BRAKE MOTOR AT CONSTANT TORQUE (0 to 87 Hz)

Using the brake motor with a  $\Delta$  connection combined with a frequency inverter can increase the constant torque range from 50 to 87 Hz, which increases the power in the same ratio.

The size of the frequency inverter is determined by the current value in 230 V and programmed with a voltage/frequency ratio of 400 V, 87 Hz.

**! Maximum mechanical speed allowed: 4,500 rpm.**

See the relevant characteristics pages at 87 Hz, power supply with drive on pages 19, 23, 31.



## Duty Cycle Definitions

### CONDITIONS AND DUTY CYCLES

#### CONDITIONS

By "condition", we mean all the electrical and mechanical values that typify machine operation at a given time.

#### DUTY CYCLES

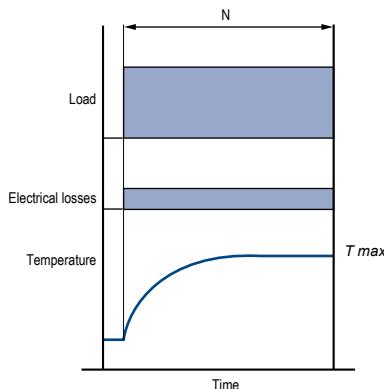
(according to IEC 60034-1)

By "duty", we mean the stipulated conditions to which the machine is subjected, their respective durations and order of succession over time.

#### 1 - Continuous duty - Type S1

Operation at constant load of sufficient duration for thermal equilibrium to be reached (see figure 1). 5 starts maximum per hour.

**Fig. 1. - Continuous duty.  
Type S1.**



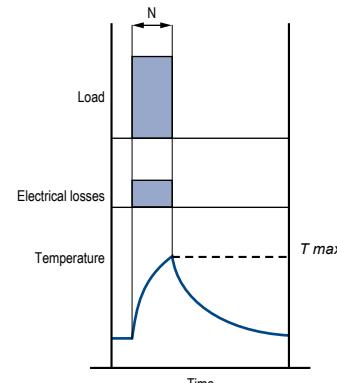
N = operation at constant load

T<sub>max</sub> = maximum temperature attained

#### 2 - Short-time duty - Type S2

Operation at constant load during a given time, less than that required for thermal equilibrium to be reached, followed by a rest and de-energized period of sufficient duration to re-establish machine temperatures within 2 K of the coolant (see figure 2).

**Fig. 2. - Short-time duty.  
Type S2.**



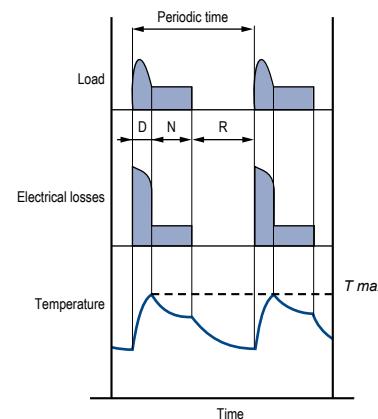
N = operation at constant load

T<sub>max</sub> = maximum temperature attained

#### 4 - Intermittent periodic duty with starting - Type S4

A sequence of identical duty cycles, each consisting of a significant starting period, a period of operation at constant load and a rest and de-energized period (see figure 4).

**Fig. 4. - Intermittent periodic duty with starting - Type S4.**



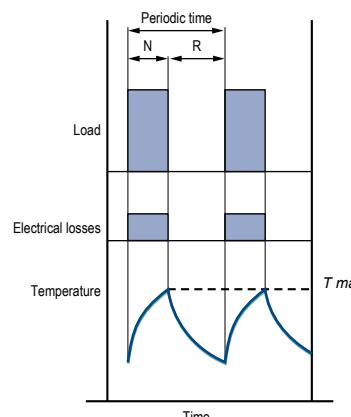
D = starting

N = operation at constant load

R = rest

T<sub>max</sub> = maximum temperature attained during cycle

$$\text{Operating factor (\%)} = \frac{D + N}{N + R + D} \cdot 100$$



N = operation at constant load

R = rest

T<sub>max</sub> = maximum temperature attained

$$\text{Operating factor (\%)} = \frac{N}{N + R} \cdot 100$$

## Duty Cycle Definitions

### S4 OPERATING RATES

The different number of starts and driven loads can result in excessive temperature rise in the brake motor.

Select the motor so that  $Z_o \geq Z_{oc}$   
( $Z_o$  brake motor starting frequency).

$Z_{oc}$  : EQUIVALENT CYCLE STARTING FREQUENCY ( $\text{h}^{-1}$ )

$$Z_{oc} = Z_c \frac{J_c + J_M}{J_M}$$

$Z_c$  : CYCLE STARTING FREQUENCY ( $\text{h}^{-1}$ )

$$Z_c = \frac{n}{t_c}$$

$J_M$  : MOTOR MOMENT OF INERTIA ( $\text{kg.m}^2$ )

$J_c$  : MOMENT OF INERTIA OF THE DRIVEN LOAD ( $\text{kg.m}^2$ )

$n$  : NUMBER OF CYCLE STARTS DURING  $T$

$T$  : TOTAL CYCLE TIME (h)

$FM$  : OPERATING FACTOR (%)

$$FM = \frac{t_m}{T} \times 100$$

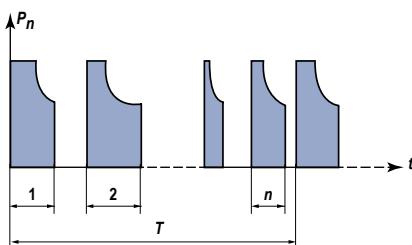
$t_m$  : MOTOR RUNNING TIME IN THE CYCLE (h)

### S4 DUTY TYPE

For each type of brake motor, the  $Z_o$  values are given for **OFs** of 25%, 40%, 60%. These starting frequencies are valid for motors at rated power where  $J_c = 0$ . They correspond to the standard brake motor.

There are several ways to obtain higher starting frequencies:

- early release
- motor derating
- for special versions, please consult Leroy-Somer.



$n$  = Number of starts in a cycle

$P_n$  = Rated motor power

$t$  = Travel time (s)

$T$  = Total cycle time (h)

### NO-LOAD STARTING FREQUENCY: $Z_o$

(For  $\Delta T = 100^\circ$ , values expressed in h-1)

#### 4 poles<sup>1</sup> - 1500 rpm - IFT/NIE (except motors in italics)

Motor type	Brake type	$P_n$ kW	Operating factor		
			25 %	40 %	60 %
LS 71 M	FFB1	0.25	4400	3500	3000
LS 71 M	FFB1	0.37	4400	3500	3000
LS 71 L	FFB1	0.55	4400	3500	3000
LS 80 L	FFB1	0.55	2800	2000	1650
LS 80 L	FFB1	0.75	2800	2000	1650
LS 80 L	FFB1	0.9	2800	2000	1650
LS 90 SL	FFB2	1.1	1400	1200	1000
LS 90 L	FFB2	1.5	1400	1200	1000
LS 90 L	FFB2	1.8	1400	1200	1000
LS 100 L	FFB2	2.2	1800	1500	1300
LS 100 L	FFB3	3	1800	1500	1300
LS 112 M	FFB3	4	900	800	700
LS 132 S	FFB3	5.5	700	600	500
LS 132 M	FFB4	7.5	350	320	290
LS 132 M	FFB4	9	350	320	290
LS 160 MP	FFB5	11	300	270	250
LS 160 LR	FFB5	15	300	270	250

1, 2, 6 poles: consult Leroy-Somer

#### 4 poles<sup>1</sup> - 1500 rpm - IFT/IE3 - General Use: UG

Motor type	Brake type	$P_n$ kW	Operating factor		
			25 %	40 %	60 %
LSES 80 LG	FFB1	0.75	2000	1500	1000
LSES 80 LG	FFB1	0.9	1200	1000	800
LSES 90 SL	FFB2	1.1	1100	900	800
LSES 90 LU	FFB2	1.5	1000	800	700
LSES 100 L	FFB2	1.8	1500	1300	1000
LSES 100 LR	FFB2	2.2	1500	1300	1000
LSES 100 LG	FFB3	3	800	700	600
LSES 112 MU	FFB3	4	600	500	400
LSES 132 SM	FFB4	5.5	300	280	250
LSES 132 MU	FFB4	7.5	300	280	250
LSES 160 MR	FFB4	9	280	250	220
LSES 160 M	FFB5	11	250	220	200
LSES 160 LUR	FFB5	15	200	180	150

1, 2, 6 poles: consult Leroy-Somer

## Electromagnet Characteristics

The DC electromagnet consists of a resin-coated coil in a cast iron yoke. The yoke and the armature form the magnetic circuit. All our coils are made for a DC voltage of 180 VDC (400 or 230 VAC supply) or 20 VDC (24 VAC supply).

All the electromagnets are class F and can be continuously supplied with power.

Since it is difficult to distinguish between some DC coils by size alone, the coil resistance should be measured with an appropriately rated ohmmeter and

compared with the value given in the table below.

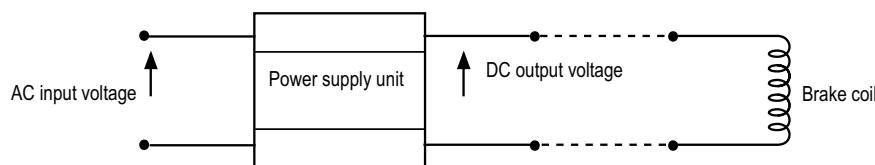
These values are theoretical, calculated for an ambient temperature of 20°C.

Electromagnet characteristics ±5%, at 20°C

Brake type	180V coil			20V coil		
	Current A	Resistance Ω	Power W	Current A	Resistance Ω	Power W
FFB1	0.232	776	42	1.974	10.1	39
FFB2	0.295	610	53	2.633	7.6	53
FFB3	0.345	522	62	2.793	7.2	56
FFB4	0.339	530	61	3.602	5.6	72
FFB5	0.547	329	98	4.211	4.8	84

## Brake Power Supply Unit Characteristics

### OPERATING PRINCIPLE



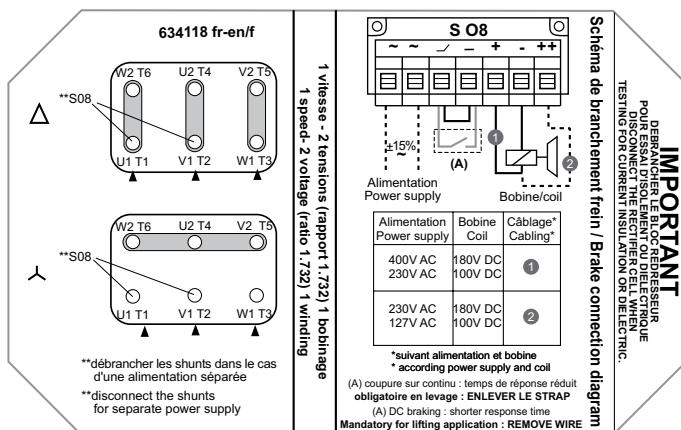
### DEFINITION OF BUILT-IN OR SEPARATE POWER SUPPLY

#### Built-in power supply:

The rectifier power supply unit is connected in parallel on the motor power supply.

#### Example:

- S08 brake power supply unit, 180 V DC coil for standard single-speed brake motor, direct supply (or separate)

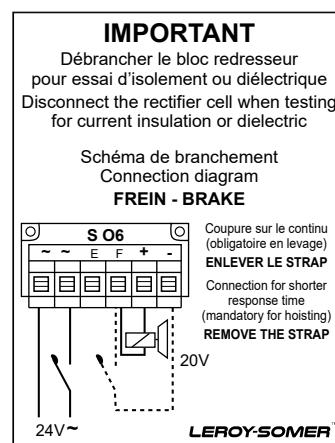


#### Separate power supply:

The motor and rectifier unit power supplies are independent. It is mandatory for Hoisting applications, as well as variable speed.

#### Examples:

- S08 brake power supply unit, 180 V DC coil, separate power supply
- S06 brake power supply unit, 20 V DC coil, 24 V separate power supply, below



## Braking Torques

The braking torque  $M_f$  is obtained from the friction between a lining made of fibrous composite material and a mating surface. If the braking torque is higher than the highest motor torque, there is a risk of the drivetrain becoming fatigued or breaking. It is therefore advisable to use:

$$M_f = 1.5 \times M_n$$

and never to exceed  $M_d$ .

### The stated dynamic braking torque

is optimum (tolerance from -10 to +40%). A standard is determined as a function of the motor power and its efficiency class:

see the selection tables in the Characteristics Tables section.

A non-standard braking torque is possible as an option (see Optional Braking Torque section).

If you encounter any difficulty relating to standards, please consult Leroy-Somer.

### Influence od the environment

The brake components are treated with anti-corrosion protection to prevent sticking and oxidation of mechanical parts in a damp environment.

### Influence of temperature

The heat released during successive braking operations increases the temperature. The resulting reduction in braking torque can be as much as 15% of the rated value.

## Wear

This is inevitable and requires regular brake adjustment. For each braking operation it is proportional to:

$$0.5 \times (J_M + J_c) \times \omega_N^2$$

It is therefore advisable to avoid braking operations at high rotation speeds (3,000 rpm and above) to reduce the amount of wear.

Wear also occurs, to a lesser extent, on release.

Motor starting and brake release occur simultaneously. For a short time, the braking torque is reduced before reaching zero; this results in brake wear and overheating of the motor. This can be avoided with early release (which consists of releasing the brake before starting the motor, using a time-delay contact).

An optional indicator lamp supplements monitoring and advises when it is necessary to adjust the air gap or change the lining (see Indicator: release/application, wear section).

## Number of braking operations allowed

### 4 poles<sup>1</sup> - 1500 rpm - IFT/NIE (except motors in italics)

Motor type	Brake type	$P_n$ kW	Maximum number of braking operations ( $10^6$ )					Number of braking operations before air gap adjustment ( $10^6$ )				
			$F_j=1$	$F_j=5$	$F_j=10$	$F_j=15$	$F_j=20$	$F_j=1$	$F_j=5$	$F_j=10$	$F_j=15$	$F_j=20$
LS 71 M	FFB1	0.25	24.64	8.21	4.48	3.08	2.35	4.93	1.64	0.90	0.62	0.47
LS 71 M	FFB1	0.37	20.87	6.96	3.79	2.61	1.99	4.17	1.39	0.76	0.52	0.40
LS 71 L	FFB1	0.55	17.03	5.68	3.10	2.13	1.62	3.41	1.14	0.62	0.43	0.32
LS 80 L	FFB1	0.55	14.84	4.95	2.70	1.85	1.41	2.97	0.99	0.54	0.37	0.28
LS 80 L	FFB1	0.75	11.24	3.75	2.04	1.41	1.07	2.25	0.75	0.41	0.28	0.21
LS 80 L	FFB1	0.9	8.71	2.90	1.58	1.09	0.83	1.74	0.58	0.32	0.22	0.17
LS 90 SL	FFB2	1.1	11.46	3.82	2.08	1.43	1.09	2.29	0.76	0.42	0.29	0.22
LS 90 L	FFB2	1.5	9.75	3.25	1.77	1.22	0.93	1.95	0.65	0.35	0.24	0.19
LS 90 L	FFB2	1.8	8.67	2.89	1.58	1.08	0.83	1.73	0.58	0.32	0.22	0.17
LS 100 L	FFB2	2.2	7.66	2.55	1.39	0.96	0.73	1.53	0.51	0.28	0.19	0.15
LS 100 L	FFB3	3	6.21	2.07	1.13	0.78	0.59	1.24	0.41	0.23	0.16	0.12
LS 112 M	FFB3	4	5.23	1.74	0.95	0.65	0.50	1.05	0.35	0.19	0.13	0.10
LS 132 S	FFB3	5.5	2.66	0.89	0.48	0.33	0.25	0.53	0.18	0.10	0.07	0.05
LS 132 M	FFB4	7.5	4.91	1.64	0.89	0.61	0.47	0.74	0.25	0.13	0.09	0.07
LS 132 M	FFB4	9	4.23	1.41	0.77	0.53	0.40	0.63	0.21	0.12	0.08	0.06
LS 160 MP	FFB5	11	3.41	1.14	0.62	0.43	0.32	0.51	0.17	0.09	0.06	0.05
LS 160 LR	FFB5	15	2.92	0.97	0.53	0.37	0.28	0.44	0.15	0.08	0.05	0.04

1. 2, 6 poles: consult Leroy-Somer

### 4 poles<sup>1</sup> - 1500 rpm - IFT/IE3 - General Use: UG

Motor type	Brake type	$P_n$ kW	Maximum number of braking operations ( $10^6$ )					Number of braking operations before air gap adjustment ( $10^6$ )				
			$F_j=1$	$F_j=5$	$F_j=10$	$F_j=15$	$F_j=20$	$F_j=1$	$F_j=5$	$F_j=10$	$F_j=15$	$F_j=20$
LSES 80 LG	FFB1	0.75	6.42	2.14	1.17	0.80	0.61	1.28	0.43	0.23	0.16	0.12
LSES 80 LG	FFB1	0.9	5.69	1.90	1.03	0.71	0.54	1.14	0.38	0.21	0.14	0.11
LSES 90 SL	FFB2	1.1	7.85	2.62	1.43	0.98	0.75	1.57	0.52	0.29	0.20	0.15
LSES 90 LU	FFB2	1.5	6.48	2.16	1.18	0.81	0.62	1.30	0.43	0.24	0.16	0.12
LSES 100 L	FFB2	1.8	6.11	2.04	1.11	0.76	0.58	1.22	0.41	0.22	0.15	0.12
LSES 100 LR	FFB2	2.2	5.18	1.73	0.94	0.65	0.49	1.04	0.35	0.19	0.13	0.10
LSES 100 LG	FFB3	3	3.19	1.06	0.58	0.40	0.30	0.64	0.21	0.12	0.08	0.06
LSES 112 MU	FFB3	4	2.61	0.87	0.47	0.33	0.25	0.52	0.17	0.09	0.07	0.05
LSES 132 SM	FFB4	5.5	4.30	1.43	0.78	0.54	0.41	0.64	0.21	0.12	0.08	0.06
LSES 132 MU	FFB4	7.5	2.98	0.99	0.54	0.37	0.28	0.45	0.15	0.08	0.06	0.04
LSES 160 MR	FFB4	9	2.59	0.86	0.47	0.32	0.25	0.39	0.13	0.07	0.05	0.04
LSES 160 M	FFB5	11	1.59	0.53	0.29	0.20	0.15	0.24	0.08	0.04	0.03	0.02
LSES 160 LUR	FFB5	15	1.21	0.40	0.22	0.15	0.11	0.18	0.06	0.03	0.02	0.02

1. 2, 6 poles: consult Leroy-Somer

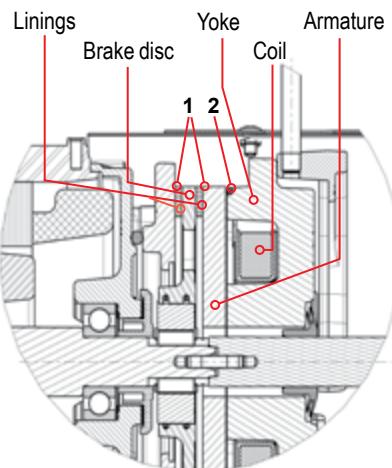
## Braking Torques

### Air gap

In order to be able to apply and release the brake, there needs to be displacement of the lining and the armature; this displacement is the air gap. The air gap must be adjusted after the lining is worn down by a maximum of 3 mm (1.5 mm on each side). The thickness of the lining must be checked on each adjustment to ensure that the wear does not exceed dimension R in mm ( $R/2$  on each side of the disk).

It must be changed when the following measurement is found between the two linings:

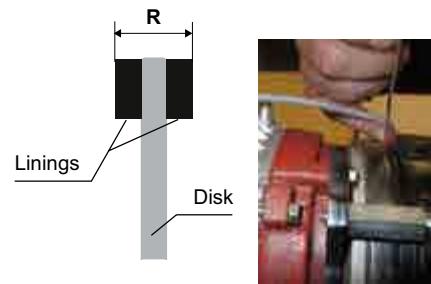
Brake size	Minimum R dimension
FFB1, FFB2, FFB3	9 mm
FFB4, FFB5	15 mm



1: air gap with coil energized, brake released  
2: air gap with coil de-energized, brake applied

### Running-in

The lining allows for a running-in period during which the braking torque is at its maximum value. All the brake linings are run in at the factory prior to assembly on the motor.



## Moments of Inertia

The moments of inertia of all our brake motors are given in the characteristics table, in the section with the same name, where J is expressed in kg.m<sup>2</sup>.

## Brake Response Time and Stopping Distance

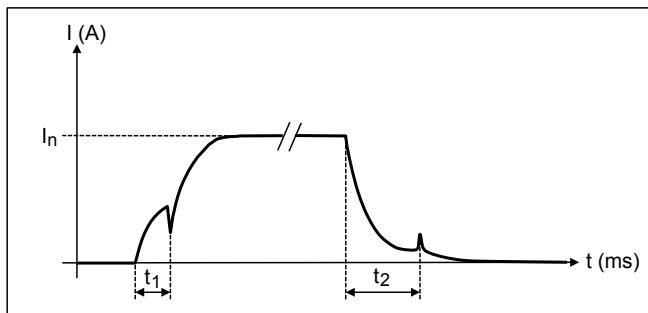
### DEFINITION OF RESPONSE TIMES

#### Brake release response time $t_1$ :

Time between the moment when the coil is supplied with power and the moment when the armature is in contact with the yoke; this moment is shown on the current curve below as a peak. This interval includes the magnetization time and the armature travel time.

#### Brake application (engage) response time $t_2$ :

Time between the moment when the coil power supply is cut and the moment when the armature is in contact with the disk; this moment is shown on the current curve below as a peak. This interval includes the demagnetization time and the armature travel time.



I: current (Amps)

$I_n$ : rated current

$t_1$ : Release response time (milliseconds ms)

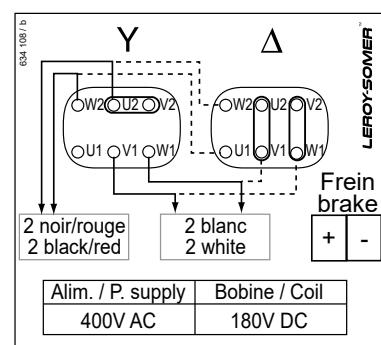
$t_2$ : Application response time (milliseconds ms)

#### Option:

TRR response time reduced by electronic booster: offered exclusively with built-in power supply and connected at the factory (0.25 to 9 kW).

Using this option allows the frequency of starts to be increased and improves accuracy on stopping by reducing the response time and application time by a third or a half depending on the size of the brake.

In addition, it saves the cost of wiring up a DC switch-off device, which is no longer needed.



**⚠️** This option is not compatible with motors for operation on a drive. It is not compatible with separate brake power supply (and built-in power supply on two-speed motors).

The brake response time depends on the value of the air gap adjustment. It should therefore be checked regularly (see above)

## Brake Response Time and Stopping Distance

### RESPONSE TIME VALUES

The response times below are given for a brand-new brake (air gap at its rated value), supplied independently of the motor and at a coil temperature of 20°C ± 5 %.

Brake type	M <sub>f</sub> N.m	180V coil				20V coil			
		Brake release response time t <sub>1</sub> (ms)		Response time brake application t <sub>2</sub> (ms)		Brake release response time t <sub>1</sub> (ms)		Response time brake application t <sub>2</sub> (ms)	
		Standard	TRR <sup>1</sup>	AC switch-off	DC switch-off	Standard	AC switch-off	DC switch-off	
FFB1	4.5	25	21,2	198	< 5	6.4	28	177	< 5
	6	28	17	159	< 5	8	30	142	< 5
	7.5	30	21	134	< 5	27	32	120	< 5
	9	32	20	117	< 5	15	34	105	< 5
	10.5	34	20	104	< 5	27	36	93	< 5
	12	36	19	94	< 5	26	37	84	< 5
FFB2	11	52	28	416	< 5	20	58	235	< 5
	15	56	33	295	< 5	23	58	178	< 5
	19	59	32	226	< 5	16	57	143	< 5
	23	62	39	182	< 5	36	57	120	< 5
	26	65	40	151	< 5	30	57	103	< 5
	30	67	40	129	< 5	19	57	90	< 5
FFB3	37	85	50	166	< 20	49	75	216	< 5
	45	91	62	132	< 20	46	78	189	< 5
	52	97	62	108	< 20	38	81	168	< 5
	59	102	68	91	< 20	28	84	152	< 5
	67	107	69	79	< 20	27	86	140	< 5
	74	112	66	69	< 20	27	88	129	< 5
FFB4	41	71	50	574	< 10	62	61	248	< 5
	55	82	58	382	< 10	52	72	179	< 5
	69	92	60	278	< 10	38	82	138	< 5
	83	101	70	215	< 10	36	91	112	< 5
	96	109	122	173	< 10	30	99	94	< 5
	110	117	126	143	< 10	38	107	81	< 5
FFB5	120	102	74	517	< 20	68	134	282	< 5
	140	113	76	427	< 20	66	146	236	< 5
	160	123	88	361	< 20	72	157	203	< 5
	180	133	98	311	< 20	32	168	177	< 5
	200	142	96	273	< 20	36	178	157	< 5

1. TRR: Reduced Response Time by booster (p.13)

### NOISE LEVEL

The noise levels displayed are the least favorable for values measured in side and axial positions. As a result, in numerous cases, our brake motors perform better. Please consult Leroy-Somer for actual values, giving any application constraints.

Brake type	M <sub>f</sub> N.m	180V coil				20V coil			
		Noise level on brake release		Noise level on brake application		Noise level on brake release		Noise level on brake application	
		dB(A) <sup>1</sup>	AC switch-off	dB(A) <sup>1</sup>	DC switch-off	dB(A) <sup>1</sup>	AC switch-off	dB(A) <sup>1</sup>	DC switch-off
FFB1	4.5	51	50	58		42	48	58	
	6	52	52	60		43	51	60	
	7.5	53	54	62		44	54	62	
	9	53	55	63		44	57	63	
	10.5	54	56	65		45	59	64	
	12	54	57	66		45	61	65	
FFB2	11	47	32	45		47	32	45	
	15	47	33	50		47	33	48	
	19	48	34	54		48	34	50	
	23	48	34	58		48	34	51	
	26	48	35	60		48	35	53	
	30	48	35	63		48	35	54	
FFB3	37	52	50	61		52	50	61	
	45	53	53	63		53	53	63	
	52	54	55	65		54	55	65	
	59	55	57	66		55	57	66	
	67	55	58	67		55	58	67	
	74	56	60	68		56	60	68	
FFB4	41	60	48	64		60	56	65	
	55	60	51	67		61	57	68	
	69	60	53	69		63	58	70	
	83	60	54	71		64	60	72	
	96	60	56	73		64	62	73	
	110	60	57	74		65	63	75	
FFB5	120	70	49	70		61	57	68	
	140	69	51	71		61	59	70	
	160	69	53	72		61	61	72	
	180	69	54	73		61	63	74	
	200	69	56	74		61	64	75	

1. Sound pressure shall be measured at 1 metre

### STOPPING TIME AND DISTANCE CALCULATIONS

STOPPING TIME (in ms):  $t_a$

$$t_a = t_c + t_2 + t_f$$

$t_c$ : Control device response time (in ms) (see opposite)

$t_2$ : Brake application response time (in ms)

$t_f$ : Brake application response time (in ms)

BRAKING TIME (in s):  $t_f$

$$t_f = \frac{(J_M + J_{c/M})}{M_f \pm M_{R/M}} \cdot \omega_N$$

$J_M$ : Motor moment of inertia (in kgm<sup>2</sup>)

$J_{c/M}$ : Moment of inertia of the load applied to the brake motor shaft

$\omega_N$ : Motor angular speed (in rd/s)

$M_f$ : Brake motor braking torque (in N.m)

$M_{R/M}$ : Load resistive torque (in N.m) (+ if it is braking, - if it is driving) applied to the brake motor shaft

### MOMENT OF INERTIA OF THE LOAD APPLIED TO THE MOTOR SHAFT (kgm<sup>2</sup>)

$J_{c/M}$

$$J_{c/M} = J_1 + J_2 \left( \frac{\omega_2}{\omega_N} \right)^2 + m \left( \frac{v}{\omega_N} \right)^2$$

$J_1$ : Moment of inertia rotating at (in kgm<sup>2</sup>)

$\omega_N$ : Motor angular speed (in rd/s)

$J_2$ : Moment of inertia rotating at (in kgm<sup>2</sup>)

$\omega_2$ : Angular speed (in rd/s)

$m$ : Mass travelling at (in kg)

$v$ : Linear speed (in m/s)

STOPPING DISTANCE (in m):  $l_a$

$$l_a = v \sqrt{t_c + t_2 + \frac{t_f}{2}}$$

$v$ : Linear speed (in m/s)

$t_c$ ,  $t_2$ ,  $t_f$ : Time (in s)

### NUMBER OF REVOLUTIONS BEFORE THE MOTOR STOPS (in ms): $a$

$$a = \frac{\omega_N}{2\pi} \left( t_c + t_2 + \frac{t_f}{2} \right)$$

$\omega_N$ : Motor angular speed (in rd/s)

$t_c$ ,  $t_2$ ,  $t_f$ : Time (in s)

### ACCURACY ON STOPPING (%)

Accuracy on stopping or repeatability of braking depends on many factors: temperature, air gap, brake wear, drivetrain backlash, etc. It is reasonable to assume accuracy on stopping of ±20%.

AC electromagnet, or DC electromagnet with DC switch-off, and taking special care: ±10%.

### BRAKE WEAR CALCULATION

INERTIA FACTOR:  $F_J$

$$F_J = \frac{J_{c/M}}{J_M}$$

$J_{c/M}$ : Moment of inertia of the load applied to the brake motor shaft

$J_M$ : Brake motor moment of inertia

## Loads Applied to the Motor (Main) Shaft

In pulley and belt couplings, the shaft extension carrying the pulley is subjected to a radial force. Formulae and charts can be read in the IMfinity® Motors catalog ref.5147. In the same catalog, the axial force on the shaft can be found for a bearing life L10h of 25,000 and 40,000 hours.

### EXAMPLE OF SELECTION

#### CUSTOMER REQUEST:

Normal, non-corrosive environment, General applications. 0.75 kW 4p brake motor for motorizing a 15-tonne trolley.

- Linear speed: 15 m/min
- Accuracy on stopping: to be stated
- Safety brake and release by a lever
- Running time: 12 s, stopping: 33 s
- Control device response time: 0.01s
- Drivetrain efficiency: 0.8
- Rolling resistance coefficient Kr = 0.1 N/kg
- Mounted on standard flange

#### CONVERSION TO SI UNITS

$$\omega = 1400 \times \frac{2\pi}{60} = 147 \text{ rd/s}$$

Under load

$$v = \frac{15}{60} = 0.25 \text{ m/s}$$

#### OPERATION CYCLE

Cycle time

$$T = 12 + 33 = 45 \text{ s}$$

Operating factor

$$OF = \frac{12}{45} = 25 \%$$

#### STARTING FREQUENCY

$$Z_{oc} = Z_c \times \frac{J_M + J_c}{J_M} = 25 \%$$

$$Z_c = \frac{n}{t_c} = \frac{1}{45/3600} = 80 \text{ h-1}$$

$$J_c = m \times \left( \frac{v}{\omega} \right)^2 = 15,000 \times \left( \frac{0.25}{147} \right)^2 = 0.043 \text{ kgm}^2$$

The flow chart on page 2 leads us to select the FFB brake series. The 4p, 0.75 kW brake motor inertia is:

$$J_M = 0.0019 \text{ kgm}^2 \text{ (see page 18)}$$

$$Z_{oc} = 80 \times \frac{0.0019 + 0.043}{0.0019} = 1890 \text{ h-1}$$

$Z_o \geq Z_{oc}$  (the table on page 10 indicates 2800 d/h-1) for a 4p, 0.75 kW brake motor with non-IE efficiency class (NIE):

4p - LS - 80L - 0.75kW - IM B5 - 230/400V  
50Hz - UG - FFB1 - 12Nm - + DLRA (auto-return hand brake release)

Code : 4988074

#### BRAKING TIME

Resistive torque:

$$M_R = m \times kr \times \frac{v}{\omega} \times \frac{1}{\eta} = 15,000 \times 0.1 \times \frac{0.25}{147} \times \frac{1}{0.8} = 3 \text{ Nm}$$

$$t_f \text{ rated} = (J_M + J_c) \times \frac{\omega_N}{M_f + M_R} = (0.0019 + 0.043) \times \frac{147}{12 + 3} = 0.44 \text{ s}$$

0.44s = rated braking time

for  $M_f + 40\% = 17 \text{ Nm} \rightarrow t_f = 0.33 \text{ s}$  (minimum)

for  $M_f - 10\% = 11 \text{ Nm} \rightarrow t_f = 0.47 \text{ s}$  (maximum)

#### STOPPING DISTANCE AND ACCURACY

$$l_a = v \left( t_C + t_2 + \frac{t_f}{2} \right) = 0.25 \times (0.01 + 0.094 + \frac{0.44}{2}) = 0.0810 \text{ m rated stopping distance}$$

Accuracy on stopping:

for  $t_f$  min. 0.33 s  $\rightarrow l_a = 0.0673 \text{ m}$  minimum stopping distance

for  $t_f$  max. 0.47 s  $\rightarrow l_a = 0.0848 \text{ m}$  maximum stopping distance.

#### NUMBER OF BRAKING OPERATIONS BEFORE ADJUSTMENT

Inertia factor calculation

$$FJ = \frac{J_{c/M}}{J_M} = \frac{0.043}{0.0019} = 22$$

The table on page 12 gives us directly the number of braking operations before adjustment, say for a non-IE 4p, 0.75 kW IFT =  $0.21 \times 10^6 = 210,000$  braking operations.

IMfinity®

LS FFB - LSES FFB - FLSES FFB Brake motors

IP55 Aluminium housing

**Designation**

4P	LS	80	L	0.75 kW	IFT/NIE	IM 3001 (IM B5)	230/400 V 50 Hz	UG	FFB	1	12 N.m	OPTIONS
Number of poles, speed: 2, 4, 6	Motor series: LS, LSES	Frame size: 71 to 180	Length code and manufacturer code: L, LG, LR, LU, LUR, M, MG, MP, MR, MU, S, SL, SM, SU	Rated power (kW) (or starting torque N.m on request): 0.25 to 18.5 kW	Range - Efficiency class: LS IFT/NIE <sup>1</sup> , LSES (IFT/IE3)	Operating position: - Foot or foot and flange mounted: IM 1001 (IM B3), IM 1051 (IM B6), IM 1061 (IM B7), IM 1071 (IM B8), IM 1011 (IM V5), IM 1031 (IM V6), IM 2001 (IM B35), IM 2011 (IM V15), IM 2031 (IM V36), IM 2101 (IM B34), IM 2111 (IM V58), IM 2131 (IM V69) - Flange mounted: IM 3001 (IM B5), IM 3011 (IM V1), IM 3031 (IM V3), IM 3601 (IM B14), IM 3611 (IM V18), IM 3631 (IM V19)	Supply voltage (V) and frequency (Hz), connection: 230 V/380/400/415 V 50 Hz – 460 V 60 Hz	Application: <b>UG:</b> General applications <b>UL:</b> Hoisting applications	Brake series: <b>FFB</b>	Brake size: 1 to 5	Braking torque (N.m): 4.5 to 200 N.m	Two-speed on request  • PTO, PTC (71 to 132), KTY and PT100 sensors • Drain holes • Separate brake power supply  • Drip cover • Choice of release: DLRA, DLM, DMD • Choice of braking torque • Reduced response time (TRR) • Indicators: wear, release • Drain holes • Incremental, absolute encoder and/or forced ventilation unit

<sup>1</sup> NIE: not in any efficiency class

## Description of LS(ES) FFB

### Description of LS(ES) FFB brake motors

Component	Materials	Comments
Finned housing	Aluminium alloy	<ul style="list-style-type: none"> <li>- with integral feet (4 fixing holes), or without feet</li> <li>- lifting ring for frame size <math>\geq 100</math></li> <li>- ground terminal with an optional jumper screw</li> </ul>
Stator	Insulated low-carbon magnetic steel laminations Electroplated copper	<ul style="list-style-type: none"> <li>- low carbon content guarantees long-term lamination pack stability</li> <li>- semi-enclosed slots</li> <li>- class F insulation</li> <li>- PTC for motor <math>\geq</math> frame size 160</li> </ul>
Rotor	Insulated low-carbon magnetic steel laminations Aluminium	<ul style="list-style-type: none"> <li>- inclined cage bars</li> <li>- rotor cage pressure die-cast in aluminium (or alloy for special applications)</li> <li>- rotor balanced dynamically, 1/2 key</li> </ul>
Shaft	Steel	<ul style="list-style-type: none"> <li>- for all frame sizes with centre hole fitted with:           <ul style="list-style-type: none"> <li>• a screw and a washer</li> <li>• closed keyway</li> </ul> </li> </ul>
End shields	Cast iron	<ul style="list-style-type: none"> <li>- DE and NDE, assembled using tie rods</li> </ul>
Bearings		<ul style="list-style-type: none"> <li>- protected ball bearings, permanently greased</li> <li>- bearings preloaded at non drive end</li> </ul>
Lipseals Labyrinth seal	Synthetic rubber	<ul style="list-style-type: none"> <li>- DE and NDE lipseals or deflectors to ensure IP55 sealing on the shaft</li> <li>- O ring seals to ensure IP55 sealing of the brake (motor NDE shield/backplate, brake disk/splined sleeve, armature/yoke)</li> </ul>
Fan	Composite material	<ul style="list-style-type: none"> <li>- bi-directional: straight blades</li> </ul>
Fan cover	Presssed steel	<ul style="list-style-type: none"> <li>- fitted, on request, with a drip cover for operation in vertical position, shaft end facing down</li> </ul>
Terminal box	Aluminium alloy	<ul style="list-style-type: none"> <li>- IP55, can be turned in 4 directions for flange mounted version, on opposite side from the feet for foot or foot and flange mounted version for frame size <math>\geq 80</math></li> <li>- fitted with a terminal block with 6 steel terminals as standard (brass as an option)</li> <li>- terminal box fitted with threaded plugs (supplied without cable glands) (cable gland as an option)</li> <li>- 1 ground terminal in each terminal box</li> <li>- fixing system consisting of a cover with captive screws</li> </ul>
Brake	Cast iron: yoke, backplate, release handle Anti-corrosion hardened steel: armature, screws, release lever Stainless steel: pressure springs, encoder extension Copper: brake coil	<p>FFB: failsafe brake with factory-set braking torque, already run in</p> <ul style="list-style-type: none"> <li>• 4.5 to 200 N.m of braking torque in accordance with IEC 60034, 60072, EN 50281</li> <li>• built-in power supply (including brake power supply unit); if it is separate (as an option) the power supply is independent of the motor (including brake power supply unit)</li> <li>• electromagnet encased in plastic to ensure it is fully sealed</li> </ul>
External finish		<ul style="list-style-type: none"> <li>- System Ia, shade RAL 6000 (green)</li> <li>- resistance to neutral saline mist: 120 hrs (in accordance with ISO 9227)</li> </ul>

From 0.25 to 18.5 kW in accordance with IEC 60034, as standard brake motors are wound as 230/380/400/415V 50Hz, 460V 60Hz with:

- power ratings  $\leq$  5.5 kW:  $\lambda$  connection
- power ratings  $\geq$  7.5 kW:  $\Delta$  connection

They are available in 2, 4 and 6-pole versions.

Adaptation to variable speed applications:

- LS, LS IFT/NIE, LSES IFT/IE3 series

Cabinet-mounted drive (offer on page 3):

- LS, LS IFT/NIE, series drive integrated in the VARMECA series brake motor.

Adaptation to particular environments:

- Dust (ATEX certification pending, IP55 in zone 22)
- Mineral industry.

Equipment and options:

- brake release (auto-return hand release (DLRA), release lock off system (DLM) and remote lock off system (DMD))
- indicator lamps (release, wear)
- reduced response time (TRR)
- drain hole (non-standard positions: B3, B5, B14)
- encoder: incremental or absolute, and/or forced ventilation unit
- applications: UG General, UL Hoisting (UT Translation on request).



## Characteristics Tables

### LS FFB IFT/NIE

4 poles - 1500 rpm - IFT/NIE (except motors in italics) - AC power supply

LS FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power	Rated torque	Starting torque/ Rated torque	Maximum torque/ Rated torque	Starting current/ Rated current	Moment of inertia	Pull-up torque	Braking torque <sup>1</sup>	400V - 50Hz				Weight IM B3/B5 <sup>2</sup> kg
		P <sub>n</sub> kW	M <sub>n</sub> N.m	M <sub>d</sub> /M <sub>n</sub>	M <sub>m</sub> /M <sub>n</sub>	I <sub>d</sub> /I <sub>n</sub>	J kg.m <sup>2</sup>	M <sub>a</sub> N.m	M <sub>f</sub> N.m	N <sub>n</sub> rpm	I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor	
<i>LS 71 M</i>	<b>FFB1</b>	0.25	1.68	2.73	2.93	4.63	0.00094	4.60	4.5	1425	0.80	67.0	0.65	9.4
<i>LS 71 M</i>	<b>FFB1</b>	0.37	2.49	2.41	2.81	4.91	0.00111	6.00	4.5	1420	1.06	70.0	0.70	10.3
<i>LS 71 L</i>	<b>FFB1</b>	0.55	3.75	2.32	2.53	4.81	0.00136	8.75	6	1400	1.62	68.0	0.70	11.3
<i>LS 80 L</i>	<b>FFB1</b>	0.55	3.75	2.15	2.30	3.90	0.00154	7.88	12	1405	1.70	66.9	0.71	11.5
<i>LS 80 L</i>	<b>FFB1</b>	0.75	5.1	1.80	2.15	4.25	0.00190	7.40	12	1400	2.05	69.3	0.77	13.5
<i>LS 80 L</i>	<b>FFB1</b>	0.9	6.05	3.10	3.10	5.55	0.00266	17	12	1425	2.45	73.0	0.73	13.9
<i>LS 90 SL</i>	<b>FFB2</b>	1.1	7.35	1.50	2.15	4.50	0.00349	11	19	1425	2.50	76.1	0.84	18.2
<i>LS 90 L</i>	<b>FFB2</b>	1.5	10	1.90	2.40	5.25	0.00421	19	19	1430	3.30	79.2	0.83	20.0
<i>LS 90 L</i>	<b>FFB2</b>	1.8	12	2.00	2.55	5.60	0.00464	24	26	1435	3.95	79.9	0.82	21.0
<i>LS 100 L</i>	<b>FFB2</b>	2.2	14.6	2.30	2.70	5.70	0.00514	29	26	1435	4.80	80.2	0.82	24.9
<i>LS 100 L</i>	<b>FFB3</b>	3	20	2.60	3.10	6.65	0.00654	50	52	1435	6.35	82.2	0.83	29.1
<i>LS 112 MG</i>	<b>FFB3</b>	4	26.7	2.65	3.05	5.85	0.00704	69	52	1430	8.95	81.4	0.79	29.6
<i>LS 132 S</i>	<b>FFB3</b>	5.5	36.1	2.55	3.20	6.95	0.01534	85	67	1456	11.5	85.4	0.81	44.6
<i>LS 132 M</i>	<b>FFB4</b>	7.5	49.4	2.30	3.00	5.90	0.02508	114	110	1450	15.6	86.8	0.80	62.5
<i>LS 132 M</i>	<b>FFB4</b>	9	59.3	2.40	2.95	6.60	0.02868	128	110	1450	17.8	87.5	0.83	67.4
<i>LS 160 MP</i>	<b>FFB5</b>	11	72.3	2.90	3.30	6.85	0.03366	177	140	1452	22.1	88.8	0.81	82.9
<i>LS 160 LR</i>	<b>FFB5</b>	15	98.5	2.85	3.35	7.45	0.04153	227	180	1454	30.0	89.1	0.81	96.1

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

### 4 poles - 1500 rpm - IFT/NIE - DRIVE power supply

LS FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Separate brake power supply - Factory-set braking torque

Motor type	Brake type	Rated power	400V - 50Hz			% Rated torque				
			Rated speed	Rated current	Power factor	M <sub>n</sub> at				
P <sub>n</sub> kW	N <sub>n</sub> rpm	I <sub>n</sub> A	Cos φ 4/4	10 Hz	17 Hz	25 Hz	50 Hz	87 Hz		
LS 80 L	<b>FFB1</b>	0.75	1380	2.10	0.81	65%	80%	100%	100%	57%
LS 80 L	<b>FFB1</b>	0.9	1415	2.50	0.77	65%	80%	100%	100%	57%
LS 90 SL	<b>FFB2</b>	1.1	1410	2.68	0.87	75%	85%	90%	100%	57%
LS 90 L	<b>FFB2</b>	1.5	1420	3.52	0.86	75%	85%	90%	100%	57%
LS 90 L	<b>FFB2</b>	1.8	1425	4.23	0.85	75%	85%	90%	100%	57%
LS 100 L	<b>FFB2</b>	2.2	1425	5.11	0.86	75%	85%	90%	100%	57%
LS 100 L	<b>FFB3</b>	3	1425	6.78	0.86	60%	85%	90%	100%	57%
LS 112 MG	<b>FFB3</b>	4	1420	9.32	0.84	60%	85%	90%	100%	57%
LS 132 S	<b>FFB3</b>	5.5	1450	11.9	0.86	70%	85%	100%	100%	57%
LS 132 M	<b>FFB4</b>	7.5	1445	15.7	0.82	90%	100%	100%	100%	57%
LS 132 M	<b>FFB4</b>	9	1440	18.8	0.86	90%	100%	100%	100%	57%
LS 160 MP	<b>FFB5</b>	11	1450	22.3	0.83	90%	100%	100%	100%	57%
LS 160 LR	<b>FFB5</b>	15	1450	30.3	0.83	90%	100%	100%	100%	57%

## Characteristics Tables

### LS FFB IFT/NIE

4 poles - 1500 rpm - IFT/NIE (except motors in italics) - AC power supply

LS FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power P <sub>n</sub> kW	380V - 50Hz				415V - 50Hz				460V - 60Hz				
			Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	Rated power P <sub>n</sub> kW	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4
<i>LS 71 M</i>	<i>FFB1</i>	0.25	-	-	-	-	-	-	-	-	-	-	-	-	-
<i>LS 71 M</i>	<i>FFB1</i>	0.37	-	-	-	-	-	-	-	-	-	-	-	-	-
<i>LS 71 L</i>	<i>FFB1</i>	0.55	-	-	-	-	-	-	-	-	-	-	-	-	-
<i>LS 80 L</i>	<i>FFB1</i>	0.55	1390	1.65	67.5	0.75	1415	1.75	65.5	0.67	0.63	1710	1.40	71.6	0.70
<i>LS 80 L</i>	<i>FFB1</i>	0.75	1380	2.05	68.3	0.81	1410	2.05	69.0	0.73	0.86	1705	1.95	73.3	0.76
<i>LS 80 L</i>	<i>FFB1</i>	0.9	1415	2.45	73.0	0.77	1435	2.50	72.0	0.70	1.04	1715	2.20	75.5	0.78
<i>LS 90 SL</i>	<i>FFB2</i>	1.1	1420	3.40	77.8	0.87	1440	3.25	79.5	0.80	1.27	1730	2.40	78.8	0.84
<i>LS 90 L</i>	<i>FFB2</i>	1.5	1425	4.10	78.8	0.86	1445	4.00	80.3	0.78	1.73	1735	3.20	81.2	0.83
<i>LS 100 L</i>	<i>FFB2</i>	1.8	1410	2.60	74.3	0.85	1435	2.45	77.0	0.82	2.07	1735	3.90	81.8	0.82
<i>LS 100 L</i>	<i>FFB2</i>	2.2	1425	4.90	79.3	0.86	1445	4.90	80.6	0.78	2.53	1735	4.70	82.4	0.82
<i>LS 100 L</i>	<i>FFB3</i>	3	1425	6.50	81.3	0.86	1440	6.30	82.7	0.80	3.45	1735	6.15	83.8	0.84
<i>LS 112 MG</i>	<i>FFB3</i>	4	1420	8.90	80.9	0.84	1440	9.10	81.4	0.75	4.60	1735	8.70	83.4	0.80
<i>LS 132 S</i>	<i>FFB3</i>	5.5	1440	11.5	84.5	0.86	1456	11.2	85.5	0.81	6.33	1756	11.1	86.7	0.83
<i>LS 132 M</i>	<i>FFB4</i>	7.5	1445	15.9	86.5	0.83	1415	14.3	65.5	0.67	8.63	1740	14.8	87.9	0.83
<i>LS 132 M</i>	<i>FFB4</i>	9	1440	18.4	86.5	0.86	1410	16.9	69.0	0.73	10.35	1745	17.2	88.7	0.85
<i>LS 160 MP</i>	<i>FFB5</i>	11	1450	22.8	88.5	0.83	1435	20.6	72.0	0.70	12.65	1745	20.8	89.7	0.85
<i>LS 160 LR</i>	<i>FFB5</i>	15	1450	31.0	88.7	0.83	1440	27.8	79.5	0.80	17.25	1745	28.4	89.8	0.85

4 poles - 1500 rpm - IFT/NIE - DRIVE power supply

LS FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Separate brake power supply - Factory-set braking torque

Motor type	Brake type	Rated power P <sub>n</sub> kW	400V - 87Hz Δ <sup>1</sup>			Maximum mechanical speed rpm
			Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Power factor Cos φ 4/4	
<i>LS 80 L</i>	<i>FFB1</i>	1.31	2500	3.65	0.81	4500
<i>LS 80 L</i>	<i>FFB1</i>	1.57	2490	4.34	0.77	4500
<i>LS 90 SL</i>	<i>FFB2</i>	1.91	2525	4.66	0.87	4500
<i>LS 90 L</i>	<i>FFB2</i>	2.61	2520	6.13	0.86	4500
<i>LS 90 L</i>	<i>FFB2</i>	3.13	2530	7.36	0.85	4500
<i>LS 100 L</i>	<i>FFB2</i>	3.83	2535	8.90	0.86	4500
<i>LS 100 L</i>	<i>FFB3</i>	5.22	2535	11.8	0.86	4500
<i>LS 112 MG</i>	<i>FFB3</i>	6.96	2535	16.2	0.84	4500
<i>LS 132 S</i>	<i>FFB3</i>	9.57	2530	20.6	0.86	4500
<i>LS 132 M</i>	<i>FFB4</i>	13.1	2560	27.3	0.82	4500
<i>LS 132 M</i>	<i>FFB4</i>	15.7	2555	32.7	0.86	4500
<i>LS 160 MP</i>	<i>FFB5</i>	19.1	2550	38.7	0.83	4500
<i>LS 160 LR</i>	<i>FFB5</i>	26.1	2560	52.7	0.83	4500

1. Data only applicable to motors: 400V 50Hz Y.

## Characteristics Tables

### LS FFB IFT/NIE

2 poles - 3000 rpm - IFT/NIE (except motors in italics)

LS FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power	Rated torque	Starting torque/ Rated torque	Maximum torque/ Rated torque	Starting current/ Rated current	Moment of inertia	Pull-up torque	Braking torque <sup>1</sup>	400V - 50Hz				Weight IM B3/B5 <sup>2</sup> kg
		P <sub>n</sub> kW	M <sub>n</sub> N.m	M <sub>d</sub> /M <sub>n</sub>	M <sub>m</sub> /M <sub>n</sub>	I <sub>d</sub> /I <sub>n</sub>	J kg.m <sup>2</sup>	M <sub>a</sub> N.m	M <sub>f</sub> N.m	N <sub>n</sub> rpm	I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor	
<b>LS 71 M</b>	<b>FFB1</b>	0.37	1.26	3.30	3.14	5.20	0.00060	4.1	4.5	2800	0.98	68.4	0.82	9.40
<b>LS 71 L</b>	<b>FFB1</b>	0.55	1.88	3.24	2.91	5.98	0.00066	6.1	4.5	2800	1.32	75.7	0.80	10.3
<b>LS 71 L</b>	<b>FFB1</b>	0.75	2.58	3.29	3.92	6.00	0.00079	9	4.5	2780	1.70	77.7	0.84	12.1
<b>LS 80 L</b>	<b>FFB1</b>	0.75	2.55	2.15	2.40	5.05	0.00096	4.46	4.5	2820	1.75	73.0	0.85	11.2
<b>LS 80 L</b>	<b>FFB1</b>	1.1	3.70	2.35	2.60	5.30	0.00116	7.4	12	2830	2.50	75.0	0.84	12.7
<b>LS 90 SL</b>	<b>FFB1</b>	1.5	4.95	2.50	3.00	6.10	0.00166	11.6	12	2880	3.35	77.2	0.84	16.5
<b>LS 90 L</b>	<b>FFB2</b>	2.2	7.30	2.75	2.90	6.10	0.00294	18.3	19	2870	4.65	79.7	0.86	21.8
<b>LS 100 L</b>	<b>FFB2</b>	3	10.0	2.85	2.90	6.00	0.00304	25.0	19	2860	6.45	81.5	0.82	25.7
<b>LS 100 L</b>	<b>FFB2</b>	3.7	12.2	3.65	3.90	8.05	0.00374	36.0	26	2905	7.80	82.7	0.83	31.0
<b>LS 112 M</b>	<b>FFB2</b>	4	13.2	3.55	3.55	7.90	0.00374	38.9	26	2890	8.20	83.1	0.85	31.0
<b>LS 132 S</b>	<b>FFB3</b>	5.5	18.0	2.30	3.15	7.35	0.00874	41.4	52	2925	11.0	84.7	0.85	42.4
<b>LS 132 S</b>	<b>FFB3</b>	7.5	24.4	2.65	3.50	7.70	0.01044	64.7	52	2930	15.8	86.5	0.79	46.0
<b>LS 132 M</b>	<b>FFB4</b>	9	29.3	2.15	2.95	6.55	0.01688	60.1	96	2935	18.0	86.8	0.83	65.2
<b>LS 160 MP</b>	<b>FFB4</b>	11	35.8	2.20	3.05	6.65	0.01846	71.6	96	2935	22.4	87.6	0.81	76.2
<b>LS 160 MR</b>	<b>FFB4</b>	15	48.8	2.65	3.25	7.70	0.02086	105	96	2935	28.3	88.7	0.86	87.0
<b>LS 160 L</b>	<b>FFB4</b>	18.5	60.1	2.65	3.40	7.40	0.04959	156	110	2935	28.3	88.7	0.86	115
<b>LS 180 MT</b>	<b>FFB5</b>	22	71.5	2.65	3.20	7.30	0.05759	175	140	2935	28.3	88.7	0.86	122

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

## Characteristics Tables

### LS FFB IFT/NIE

6 poles - 1000 rpm - IFT/NIE (except motors in italics) - AC power supply

LS FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power	Rated torque	Starting torque/ Rated torque	Maximum torque/ Rated torque	Starting current/ Rated current	Moment of inertia	Pull-up torque	Braking torque <sup>1</sup>	400V - 50Hz				Weight IM B3/B5 <sup>2</sup> kg
		P <sub>n</sub> kW	M <sub>n</sub> N.m	M <sub>d</sub> /M <sub>n</sub>	M <sub>m</sub> /M <sub>n</sub>	I <sub>d</sub> /I <sub>n</sub>	J kg.m <sup>2</sup>	M <sub>a</sub> N.m	M <sub>f</sub> N.m	N <sub>n</sub> rpm	I <sub>n</sub> A	η% 4/4	Cos φ 4/4	
<b>LS 71 L</b>	<b>FFB1</b>	0.25	2.6	2.0	2.2	3.13	0.00156	5.1	4.5	915	1.15	50.0	0.60	10.9
<b>LS 80 L</b>	<b>FFB1</b>	0.37	3.7	2.1	2.5	3.85	0.00346	7.77	12	954	1.30	61.7	0.66	12.7
<b>LS 80 L</b>	<b>FFB2</b>	0.55	5.5	2.55	3.0	3.4	0.00446	14.0	12	956	2.15	61.0	0.60	14.0
<b>LS 90 SL</b>	<b>FFB2</b>	0.75	7.5	1.9	2.4	3.7	0.00414	13.9	19	952	2.25	70.0	0.68	21.0
<b>LS 90 L</b>	<b>FFB2</b>	1.1	11.2	1.85	2.2	3.85	0.00464	20.7	19	940	3.05	72.9	0.71	22.2
<b>LS 100 L</b>	<b>FFB2</b>	1.5	15.4	1.95	2.3	3.75	0.00521	27.7	26	930	4.00	75.2	0.72	26.5
<b>LS 112 MG</b>	<b>FFB3</b>	2.2	21.9	2.05	2.4	4.75	0.01604	41.6	52	960	5.60	77.7	0.73	37.0
<b>LS 132 S</b>	<b>FFB3</b>	3	29.8	2.35	2.7	5	0.02032	67.1	52	960	7.65	79.7	0.71	45.0
<b>LS 132 M</b>	<b>FFB4</b>	4	39.6	2.15	2.6	5.35	0.03116	79.2	96	964	9.25	81.4	0.77	62.5
<b>LS 132 M</b>	<b>FFB4</b>	5.5	54.4	2.55	2.8	5.6	0.03615	114	96	966	13.1	83.1	0.73	77.5
<b>LS 160 M</b>	<b>FFB5</b>	7.5	73.5	1.7	2.7	5.2	0.09423	110	140	966	13.1	83.1	0.73	97.3
<b>LS 160 L</b>	<b>FFB5</b>	11	109	1.9	2.6	5.3	0.12159	169	180	966	13.1	83.1	0.73	115

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

## Characteristics Tables

### LSES FFB IFT/IE3

4 poles - 1500 rpm - IFT/IE3 - AC power supply

LSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	400V - 50Hz												Weight IM B3/B5 <sup>2</sup> kg
		Rated power P <sub>n</sub> kW	Rated torque M <sub>n</sub> N.m	Starting torque/ Rated torque M <sub>m</sub> /M <sub>n</sub>	Maximum torque/ Rated torque M <sub>m</sub> /M <sub>n</sub>	Starting current/ Rated current I <sub>d</sub> /I <sub>n</sub>	Moment of inertia J kg.m <sup>2</sup>	Pull-up torque M <sub>a</sub> N.m	Braking torque <sup>1</sup> M <sub>f</sub> N.m	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	
LSES 80 LG	FFB1	0.75	4.95	2.20	2.9	6.20	0.0036	10.9	12	1450	1.65	83.2	0.80	16.6
LSES 80 LG	FFB1	0.9	5.90	2.58	3.1	6.42	0.0041	13.2	12	1450	1.90	83.5	0.80	17.1
LSES 90 SL	FFB2	1.1	7.25	2.45	3.2	6.90	0.0050	16.3	19	1450	2.30	84.8	0.81	22.4
LSES 90 LU	FFB2	1.5	9.85	2.90	3.7	7.65	0.0061	26.6	19	1452	3.20	85.6	0.79	26.6
LSES 100 L	FFB2	1.8	11.8	2.40	2.7	6.59	0.0065	26.8	26	1452	3.70	86.0	0.82	28.8
LSES 100 LR	FFB2	2.2	14.4	3.20	3.8	8.05	0.0076	46.1	26	1454	4.60	87.1	0.79	32.0
LSES 100 LG	FFB3	3	19.6	2.45	3.3	7.15	0.0124	46.1	52	1460	6.05	88.3	0.81	37.6
LSES 112 MU	FFB3	4	26.2	2.70	3.1	7.05	0.0140	56.3	52	1458	8.10	88.8	0.80	43.6
LSES 132 SM	FFB4	5.5	35.9	2.80	3.6	8.55	0.0287	96.9	67	1462	10.3	90.3	0.85	66.5
LSES 132 MU	FFB4	7.5	49.1	2.95	3.4	8.00	0.0355	133	110	1458	14.0	90.6	0.86	77.1
LSES 160 MR	FFB4	9	58.7	3.10	3.7	8.85	0.0416	158	110	1464	16.7	91.2	0.85	92.3
LSES 160 M	FFB5	11	71.7	2.25	3.1	7.25	0.0770	133	140	1466	20.5	91.6	0.85	110
LSES 160 LUR	FFB5	15	97.6	2.55	3.5	8.35	0.1012	185	180	1468	27.7	92.3	0.85	117

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

4 poles - 1500 rpm - IFT/IE3 - DRIVE power supply

LSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Separate brake power supply - Factory-set braking torque

Motor type	Brake type	400V - 50Hz			% Rated torque						
		Rated power P <sub>n</sub> kW	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Power factor Cos φ 4/4	M <sub>n</sub> at					
10 Hz	17 Hz	25 Hz	50 Hz	87 Hz							
LSES 80 LG	FFB1	0.75	1450	1.70	0.80	90%	100%	100%	100%	57%	
LSES 80 LG	FFB1	0.9	1440	2.45	0.80	90%	100%	100%	100%	57%	
LSES 90 SL	FFB2	1.1	1450	2.43	0.81	90%	100%	100%	100%	57%	
LSES 90 LU	FFB2	1.5	1452	3.31	0.79	90%	100%	100%	100%	57%	
LSES 100 L	FFB2	1.8	1440	3.9	0.82	90%	100%	100%	100%	57%	
LSES 100 LR	FFB2	2.2	1454	4.77	0.79	90%	100%	100%	100%	57%	
LSES 100 LG	FFB3	3	1460	6.37	0.81	90%	100%	100%	100%	57%	
LSES 112 MU	FFB3	4	1458	8.37	0.80	90%	100%	100%	100%	57%	
LSES 132 SM	FFB4	5.5	1462	11.0	0.85	90%	90%	100%	100%	57%	
LSES 132 MU	FFB4	7.5	1458	14.9	0.86	90%	90%	100%	100%	57%	
LSES 160 MR	FFB4	9	1464	17.8	0.85	90%	90%	100%	100%	57%	
LSES 160 M	FFB5	11	1466	21.6	0.85	85%	95%	100%	100%	57%	
LSES 160 LUR	FFB5	15	1468	29.2	0.85	85%	95%	100%	100%	57%	

## Characteristics Tables

### LSES FFB IFT/IE3

4 poles - 1500 rpm - IFT/IE3 - AC power supply

LSES FFB brake - 230 $\Delta$ /380Y/400Y/415Y-460Y or 400V  $\Delta$  - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power P <sub>n</sub> kW	380V - 50Hz				415V - 50Hz				460V - 60Hz				
			Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	Rated power P <sub>n</sub> kW	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4
LSES 80 LG	FFB1	0.75	1440	1.65	82.6	0.82	1452	1.60	83.3	0.78	0.75	1758	1.45	85.1	0.76
LSES 80 LG	FFB1	0.9	1440	2.00	83.0	0.82	1452	1.80	83.6	0.78	0.9	1758	1.70	85.6	0.76
LSES 90 SL	FFB2	1.1	1445	2.35	84.1	0.83	1454	2.30	85.4	0.79	1.1	1760	2.05	86.6	0.78
LSES 90 LU	FFB2	1.5	1445	3.25	85.3	0.82	1456	3.20	85.8	0.77	1.5	1760	2.80	87.3	0.76
LSES 100 L	FFB2	1.8	1445	3.90	85.4	0.83	1454	3.90	86.2	0.79	1.8	1760	3.30	87.0	0.78
LSES 100 LR	FFB2	2.2	1445	4.70	86.7	0.82	1456	4.60	87.3	0.77	2.2	1760	4.15	88.4	0.76
LSES 100 LG	FFB3	3	1452	6.20	87.74	0.84	1462	6.05	88.4	0.78	3	1766	5.35	90.0	0.79
LSES 112 MU	FFB3	4	1450	8.30	88.6	0.83	1462	8.05	88.9	0.78	4	1764	7.10	90.2	0.79
LSES 132 SM	FFB4	5.5	1456	10.7	89.64	0.87	1466	10.2	90.4	0.83	5.5	1768	9.05	91.7	0.83
LSES 132 MU	FFB4	7.5	1450	14.5	90.4	0.87	1462	13.6	90.9	0.85	7.5	1766	12.1	92.0	0.84
LSES 160 MR	FFB4	9	1458	17.4	90.6	0.86	1466	16.5	91.5	0.83	9	1768	14.7	92.4	0.83
LSES 160 M	FFB5	11	1462	21.1	91.4	0.86	1470	19.8	91.9	0.84	11	1774	17.8	92.8	0.84
LSES 160 LUR	FFB5	15	1464	28.7	92.1	0.86	1472	26.8	92.5	0.84	15	1774	24.2	93.3	0.93

4 poles - 1500 rpm - IFT/IE3 - DRIVE power supply

LSES FFB brake - 230 $\Delta$ /380Y/400Y/415Y-460Y or 400V  $\Delta$  - IP55 - Separate brake power supply - Factory-set braking torque

Motor type	Brake type	Rated power P <sub>n</sub> kW	400V - 87Hz $\Delta^1$			Maximum mechanical speed rpm
			Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Power factor Cos φ 4/4	
LSES 80 LG	FFB1	1.31	2511	2.96	0.80	4500
LSES 80 LG	FFB1	1.55	2550	3.47	0.80	4500
LSES 90 SL	FFB2	1.91	2511	4.23	0.81	4500
LSES 90 LU	FFB2	2.61	2514	5.76	0.79	4500
LSES 100 L	FFB2	3.13	2550	6.77	0.82	4500
LSES 100 LR	FFB2	3.83	2518	8.30	0.79	4500
LSES 100 LG	FFB3	5.22	2528	11.1	0.81	4500
LSES 112 MU	FFB3	6.96	2525	14.6	0.80	4500
LSES 132 SM	FFB4	9.57	2532	19.1	0.85	4500
LSES 132 MU	FFB4	13.1	2525	25.9	0.86	4500
LSES 160 MR	FFB4	15.7	2535	31.0	0.85	4500
LSES 160 M	FFB5	19.1	2538	37.6	0.85	4500
LSES 160 LUR	FFB5	26.1	2542	50.8	0.85	4500

1. Data only applicable to motors: 400V 50Hz Y.

## Characteristics Tables

### IFT/IE3 BRAKE MOTORS

2 poles - 3000 rpm - IFT/IE3 - AC power supply

LSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	400V - 50Hz												Weight IM B3/B5 <sup>2</sup>
		Rated power P <sub>n</sub> kW	Rated torque M <sub>n</sub> N.m	Starting torque/ Rated torque M <sub>d</sub> /M <sub>n</sub>	Maximum torque/ Rated torque M <sub>m</sub> /M <sub>n</sub>	Starting current/ Rated current I <sub>d</sub> /I <sub>n</sub>	Moment of inertia J kg.m <sup>2</sup>	Pull-up torque M <sub>a</sub> N.m	Braking torque <sup>1</sup> M <sub>f</sub> N.m	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	
LSES 80 L	FFB1	0.75	2.50	3.45	3.50	7.75	0.00121	7.75	4.5	2890	1.60	81.7	0.83	12.9
LSES 80 LG	FFB1	1.1	3.65	2.65	3.20	6.85	0.00249	8.94	12	2885	2.25	83.7	0.85	17.1
LSES 90 SL	FFB1	1.5	4.95	2.95	3.30	7.45	0.00249	13.6	12	2890	3.00	85.0	0.85	18.6
LSES 90 L	FFB1	1.8	6.00	3.10	3.36	7.52	0.00319	17.3	12	2890	3.75	85.5	0.85	20.8
LSES 90 LU	FFB2	2.2	7.25	3.10	3.40	8.00	0.00376	21.0	19	2895	4.25	86.3	0.86	26.6
LSES 100 L	FFB2	3	9.95	3.55	3.50	8.35	0.00448	33.3	19	2885	5.80	87.3	0.86	30.8
LSES 100 LG	FFB2	3.7	12.1	2.08	3.00	7.44	0.01025	25.2	26	2920	6.65	88.2	0.89	41.4
LSES 112 MG	FFB2	4	13.1	2.00	2.90	7.00	0.01025	26.2	26	2920	7.30	88.6	0.89	38.9
LSES 132 S	FFB3	5.5	18.0	2.30	3.10	7.40	0.01200	37.8	52	2925	10.3	89.6	0.87	45.8
LSES 132 SM	FFB4	7.5	24.4	2.10	2.90	6.75	0.01690	48.8	55	2935	13.9	90.7	0.86	70.2
LSES 132 M	FFB4	9	29.2	2.15	3.30	7.70	0.01791	62.8	96	2945	16.6	91.2	0.86	73.8
LSES 160 MP	FFB4	11	35.7	1.90	2.90	6.85	0.01976	66.1	96	2940	20.2	91.6	0.86	84.5
LSES 160 M	FFB4	15	48.6	2.30	2.80	7.80	0.05486	97.2	96	2945	26.7	92.1	0.88	110
LSES 160 L	FFB4	18.5	59.9	2.80	3.20	7.60	0.06069	138	110	2930	32.8	92.6	0.88	115
LSES 180 MR	FFB5	22	71.2	3.20	3.20	8.70	0.06839	167	140	2930	38.8	92.9	0.88	122

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

### 6 poles - 1000 rpm - IFT/IE3 - AC power supply

LSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

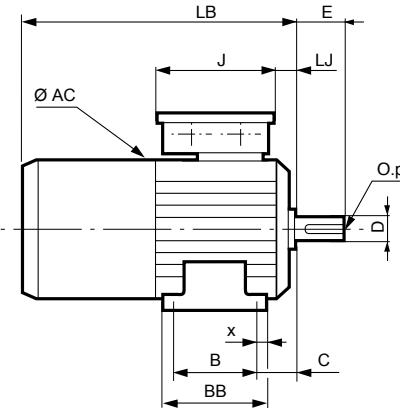
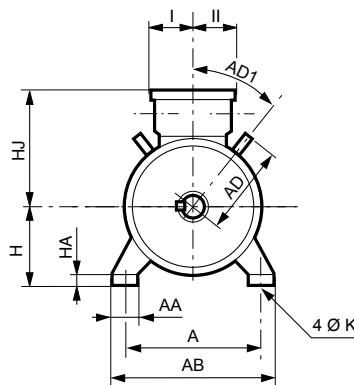
Motor type	Brake type	400V - 50Hz												Weight IM B3/B5 <sup>2</sup>
		Rated power P <sub>n</sub> kW	Rated torque M <sub>n</sub> N.m	Starting torque/ Rated torque M <sub>d</sub> /M <sub>n</sub>	Maximum torque/ Rated torque M <sub>m</sub> /M <sub>n</sub>	Starting current/ Rated current I <sub>d</sub> /I <sub>n</sub>	Moment of inertia J kg.m <sup>2</sup>	Pull-up torque M <sub>a</sub> N.m	Braking torque <sup>1</sup> M <sub>f</sub> N.m	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	
LSES 90 SL	FFB2	0.75	7.55	1.85	2.3	4.45	0.00462	13.6	19	950	1.90	79.1	0.72	22.2
LSES 90 LU	FFB2	1.1	11.0	2.35	2.7	4.85	0.00603	24.8	19	956	2.75	81.9	0.71	27.7
LSES 100 LG	FFB2	1.5	14.8	2.35	2.8	5.65	0.01607	28.9	26	966	3.60	83.5	0.72	36.2
LSES 112 MU	FFB3	2.2	21.7	2.30	2.8	5.45	0.01983	45.6	52	966	5.40	84.5	0.70	43.6
LSES 132 SM	FFB4	3	29.5	2.75	3.2	6.55	0.03116	67.9	55	972	6.85	86.5	0.73	54.6
LSES 132 M	FFB4	4	39.3	2.65	2.9	6.45	0.03615	82.5	96	972	9.00	87.4	0.73	68.5
LSES 132 MU	FFB4	5.5	54.4	2.60	2.9	6.35	0.04287	120	96	966	11.8	88.2	0.76	77.6
LSES 160 MU	FFB5	7.5	73.2	2.00	3.1	6.00	0.13533	124	140	978	18.6	89.6	0.72	99.3

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

**LS(ES) FFB dimensions**

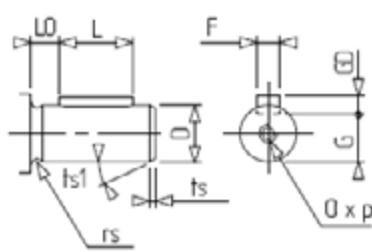
Dimensions in millimeters

**FOOT MOUNTED IM B3 (IM 1001)**

Motor type	Brake type	Main dimensions																		
		A	AA	AB	AC <sup>1</sup>	AD	AD1	B	BB	C	H	HA	HJ	J	I	II	K	LB	LJ	x
LS 71 M	FFB1	112	23	126	140	-	-	90	104	45	71	9	130	160	55	55	7	286	12	7.5
LS 71 L	FFB1	112	23	126	140	-	-	90	104	45	71	9	130	160	55	55	9	312	13.5	10
LS 80 L	FFB1	125	29	157	170	-	-	100	120	50	80	10	141	160	55	55	9	312	13.5	10
LSES 80 L	FFB1	125	29	157	170	-	-	100	120	50	80	10	141	160	55	55	9	312	13.5	10
LSES 80 LG	FFB1	125	31	157	190	-	-	100	125	50	80	10	151	160	55	55	9	389	13.5	14
LS 90 L	FFB2	140	39	172	190	-	-	125	162	56	90	11	151	160	55	55	10	389	13.5	28
LS 90 SL	FFB1, 2	140	39	172	190	-	-	125	162	56	90	11	151	160	55	55	10	389	13.5	28
LSES 90 SL	FFB1, 2	140	39	172	190	-	-	125	162	56	90	11	151	160	55	55	10	389	13.5	28
LSES 90 L	FFB1	140	39	172	190	-	-	125	162	56	90	11	151	160	55	55	10	389	13.5	28
LSES 90 LU	FFB2	140	39	172	190	-	-	125	162	56	90	11	151	160	55	55	10	389	13.5	28
LS 100 L	FFB2, 3	160	40	196	200	118	45	140	165	63	100	13	156	160	55	55	12	437	14.5	12
LSES 100 L	FFB2	160	40	196	200	118	45	140	165	63	100	13	156	160	55	55	12	437	14.5	12
LSES 100 LR	FFB2	160	40	196	200	118	45	140	165	63	100	13	156	160	55	55	12	437	14.5	12
LSES 100 LG	FFB2, 3	160	49	196	235	-	-	140	170	63	100	13	165	160	55	55	12	423	22.5	11
LS 112 M	FFB2	190	45	220	200	118	45	140	165	70	112	14	156	160	55	55	12	437	14.5	13
LS 112 MG	FFB3	190	52	220	235	-	-	140	165	70	112	14	165	160	55	55	12	448	22.5	12
LSES 112 MG	FFB2	190	52	220	235	-	-	140	165	70	112	14	165	160	55	55	12	448	22.5	12
LSES 112 MU	FFB3	190	52	220	235	-	-	140	165	70	112	14	165	160	55	55	12	448	22.5	12
LS 132 S	FFB3	216	42	250	227	130	45	140	170	89	132	16	168	160	55	55	16	490	40.5	16
LSES 132 S	FFB3	216	42	250	227	130	45	140	170	89	132	16	168	160	55	55	12	490	40.5	16
LSES 132 SM	FFB4	216	50	250	272	140	45	140	208	89	132	15	186	160	55	55	12	596	25	15
LS 132 M	FFB4	216	50	250	272	140	45	178	208	89	132	15	186	160	55	55	12	596	25	15
LSES 132 M	FFB4	216	50	250	272	140	45	178	208	89	132	15	186	160	55	55	12	596	25	15
LSES 132 MU	FFB4	216	50	250	272	140	45	178	208	89	132	15	186	160	55	55	12	596	25	15
LS 160 MP	FFB4, 5	254	64	294	272	156	45	210	294	108	160	25	186	160	55	55	14	671	66.5	20
LSES 160 MP	FFB4	254	64	294	272	156	45	210	294	108	160	25	186	160	55	55	14	671	66.5	20
LS 160 MR	FFB4	254	64	294	272	156	45	210	294	108	160	25	186	160	55	55	14	671	66.5	20
LSES 160 MR	FFB4	254	64	294	272	156	45	210	294	108	160	25	186	160	55	55	14	671	66.5	20
LS 160 LR	FFB5	254	64	294	272	156	45	254	294	108	160	25	186	160	55	55	14	671	66.5	20
LS 160 M	FFB5	254	60	294	312	186	45	210	294	108	160	25	235	160	55	55	14.5	682	50.8	20
LSES 160 M	FFB4, 5	254	60	294	312	-	-	254	294	108	160	25	235	160	55	55	14.5	682	50.8	20
LS 160 L	FFB4	254	60	294	312	186	45	254	294	108	160	25	235	160	55	55	14.5	682	50.8	20
LSES 160 L	FFB4, 5	254	60	294	312	-	-	254	294	108	160	25	235	160	55	55	14.5	682	50.8	20
LSES 160 LUR	FFB5	254	60	294	312	-	-	254	294	108	160	25	235	160	55	55	14.5	677	50.8	20
LSES 160 MU	FFB5	254	60	294	312	-	-	254	294	108	160	25	235	160	55	55	14.5	677	50.8	20
LS 180 MT	FFB5	279	79	324	312	186	45	241	316	121	180	28	248	160	55	55	14.5	682	50.8	20
LSES 180 MR	FFB5	279	79	324	312	-	-	279	316	121	180	28	248	160	55	55	14.5	677	50.8	20

1. Housing diameter without lifting rings

Motor type	Brake type	Output shaft details											
		D	E	F	G	GD	L	LO	rs	ts	ts1	M.O.xP	
LS 71	FFB1	14j6	30	5	11	5	25	4	-	-	-	M5x15	
LS(ES) 80	FFB1, 2	19j6	40	6	15.5	6	30	6	0.5	2	20	M6x16	
LS(ES) 90	FFB1, 2	24j6	50	8	20	7	40	6	0.5	2	20	M8x19	
LS(ES) 100	FFB2, 3	28j6	60	8	24	7	50	6	0.5	2	20	M10x22	
LS(ES) 112	FFB2, 3	28j6	60	8	24	7	50	6	0.5	2	20	M10x22	
LS(ES) 132	FFB3, 4	38k6	80	10	33	8	63	10	0.5	2	20	M12x28	
LS(ES) 160	FFB4, 5	42k6	110	12	37	8	100	6	0.8	1	45	M16x36	
LS(ES) 180	FFB5	48k6	110	14	42.5	9	98	12	0.8	1	45	M16x36	



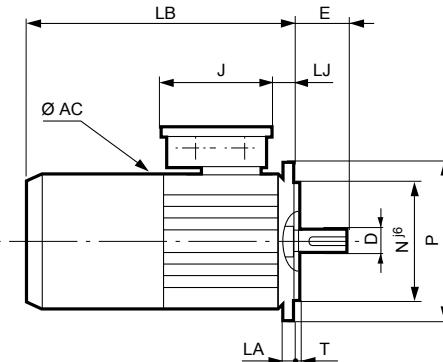
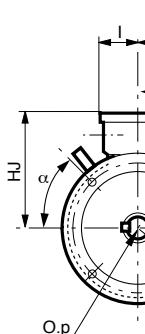
IMfinity®

LS FFB - LSES FFB - FLSES FFB Brake motors

IP55 Aluminium housing

**LS(ES) FFB dimensions**

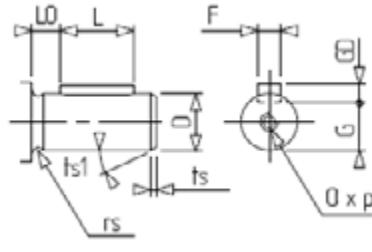
Dimensions in millimeters

**FLANGE MOUNTED (FF) IM B5 (IM 3001)**

Motor type	Brake type	Main dimensions								IEC symbol	Flange (FF) output dimensions							
		AC <sup>1</sup>	AD	AD1	HJ	J	I	II	LB		M	N	P	n	a°	S	T	LA
LS 71 M	FFB1	140	-	-	130	160	55	55	286	FF130	130	110	160	4	45	10	3.5	10
LS 71 L	FFB1	140	-	-	130	160	55	55	286	FF130	130	110	160	4	45	10	3.5	10
LS 80 L	FFB1	170	-	-	141	160	55	55	312	FF165	165	130	200	4	45	12	3.5	10
LSES 80 L	FFB1	170	-	-	141	160	55	55	312	FF165	165	130	200	4	45	12	3.5	10
LSES 80 LG	FFB1	190	-	-	151	160	55	55	409	FF165	165	130	200	4	45	12	3.5	10
LS 90 L	FFB2	190	-	-	151	160	55	55	409	FF165	165	130	200	4	45	12	3.5	10
LS 90 SL	FFB1, 2	190	-	-	151	160	55	55	409	FF165	165	130	200	4	45	12	3.5	10
LSES 90 SL	FFB1, 2	190	-	-	151	160	55	55	409	FF165	165	130	200	4	45	12	3.5	10
LSES 90 L	FFB1	190	-	-	151	160	55	55	409	FF165	165	130	200	4	45	12	3.5	10
LSES 90 LU	FFB2	190	-	-	151	160	55	55	409	FF165	165	130	200	4	45	12	3.5	10
LS 100 L	FFB2, 3	200	-	-	156	160	55	55	437	FF215	215	180	250	4	45	12	3.5	10
LSES 100 L	FFB2	200	-	-	156	160	55	55	437	FF215	215	180	250	4	45	14.5	4	12
LSES 100 LR	FFB2	200	-	-	156	160	55	55	437	FF215	215	180	250	4	45	14.5	4	12
LSES 100 LG	FFB2, 3	235	-	-	165	160	55	55	423	FF215	215	180	250	4	45	14.5	4	12
LS 112 M	FFB2	200	-	-	156	160	55	55	437	FF215	215	180	250	4	45	14.5	4	12
LS 112 MG	FFB3	235	-	-	165	160	55	55	448	FF215	215	180	250	4	45	15	4	12
LSES 112 MG	FFB2	235	-	-	165	160	55	55	448	FF215	215	180	250	4	45	15	4	12
LSES 112 MU	FFB3	235	-	-	165	160	55	55	448	FF265	265	230	300	4	45	15	4	14
LS 132 S	FFB3	227	130	45	168	160	55	55	490	FF265	265	230	300	4	45	14.5	4	14
LSES 132 S	FFB3	227	130	45	168	160	55	55	490	FF265	265	230	300	4	45	14.5	4	14
LSES 132 SM	FFB4	272	140	45	186	160	55	55	596	FF265	265	230	300	4	45	14.5	4	14
LS 132 M	FFB4	272	140	45	186	160	55	55	596	FF265	265	230	300	4	45	14.5	4	14
LSES 132 M	FFB4	272	140	45	186	160	55	55	596	FF300	300	250	350	4	45	18.5	5	14
LS 160 MP	FFB4, 5	272	155	45	186	160	55	55	671	FF300	300	250	350	4	45	18.5	5	14
LSES 160 MP	FFB4	272	155	45	186	160	55	55	671	FF300	300	250	350	4	45	18.5	5	14
LS 160 MR	FFB4	272	155	45	186	160	55	55	671	FF300	300	250	350	4	45	18.5	5	14
LSES 160 MR	FFB4	272	155	45	186	160	55	55	671	FF300	300	250	350	4	45	18.5	5	14
LS 160 LR	FFB5	272	155	45	186	160	55	55	671	FF300	300	250	350	4	45	18.5	5	14
LS 160 M	FFB5	312	-	-	235	160	55	55	682	FF300	300	250	350	4	45	18.5	5	14
LSES 160 M	FFB4, 5	312	-	-	235	160	55	55	682	FF300	300	250	350	4	45	18.5	5	14
LS 160 L	FFB4, 5	312	-	-	235	160	55	55	682	FF300	300	250	350	4	45	18.5	5	14
LSES 160 L	FFB4, 5	312	-	-	235	160	55	55	682	FF300	300	250	350	4	45	18.5	5	14
LSES 160 LUR	FFB5	312	-	-	235	160	55	55	677	FF300	300	250	350	4	45	18.5	5	14
LSES 160 MU	FFB5	312	-	-	235	160	55	55	677	FF300	300	250	350	4	45	18.5	5	14
LS 180 MT	FFB5	312	-	-	235	160	55	55	682	FF300	300	250	350	4	45	18.5	5	14
LSES 180 MR	FFB5	312	-	-	235	160	55	55	677	FF300	300	250	350	4	45	18.5	5	14

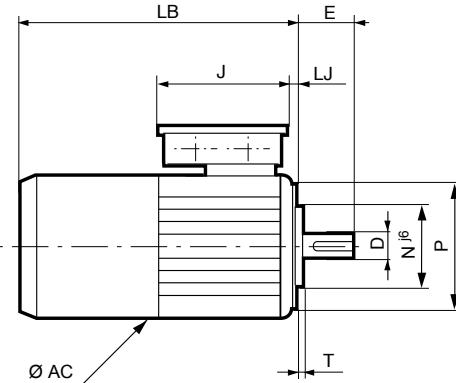
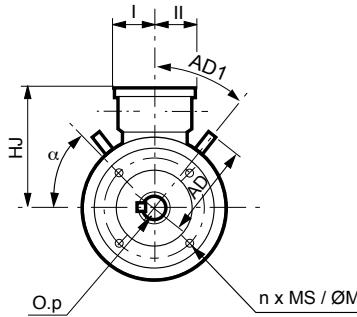
1. Housing diameter without lifting rings

Motor type	Brake type	Output shaft details										
		D	E	F	G	GD	L	LO	rs	ts	ts1	M.OxP
LS 71	FFB1	14j6	30	5	11	5	25	4	-	-	-	M5x12.4
LS(ES) 80	FFB1, 2	19j6	40	6	15.5	6	30	6	0.5	2	20	M6x16
LS(ES) 90	FFB1, 2	24j6	50	8	20	7	40	6	0.5	2	20	M8x19
LS(ES) 100	FFB2, 3	28j6	60	8	24	7	50	6	0.5	2	20	M10x22
LS(ES) 112	FFB2, 3	28j6	60	8	24	7	50	6	0.5	2	20	M10x22
LS(ES) 132	FFB3, 4	38k6	80	10	33	8	63	10	0.5	2	20	M12x28
LS(ES) 160	FFB4, 5	42k6	110	12	37	8	100	6	0.8	1	45	M16x36
LS(ES) 180	FFB5	48k6	110	14	42.5	9	98	12	0.8	1	45	M16x36



**LS(ES) FFB dimensions**

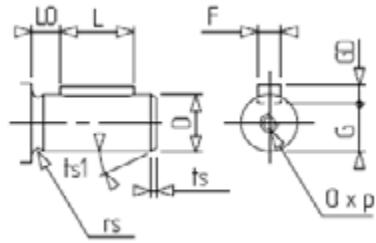
Dimensions in millimeters

**FACE MOUNTED (FT) IM B14 (IM 3601)**

Motor type	Brake type	Main dimensions								IEC symbol	Faceplate (FT) output dimensions						
		AC <sup>1</sup>	AD	AD1	HJ	J	I	II	LB		M	N	P	n	α°	MS	T
LS 71 M	FFB1	140	-	-	130	160	55	55	286	12	85	70	105	4	45	M6	2.5
LS 71 L	FFB1	140	-	-	130	160	55	55	286	12	85	70	105	4	45	M6	2.5
LS 80 L	FFB1	170	-	-	141	160	55	55	312	14.5	100	80	120	4	45	M6	3
LSES 80 L	FFB1	170	-	-	141	160	55	55	312	14.5	100	80	120	4	45	M6	3
LSES 80 LG	FFB1	190	-	-	151	160	55	55	389	13.5	115	95	140	4	45	M8	3
LS 90 L	FFB2	190	-	-	151	160	55	55	389	13.5	115	95	140	4	45	M8	3
LS 90 SL	FFB1, 2	190	-	-	151	160	55	55	389	13.5	115	95	140	4	45	M8	3
LSES 90 SL	FFB1, 2	190	-	-	151	160	55	55	389	13.5	115	95	140	4	45	M8	3
LSES 90 L	FFB1	190	-	-	151	160	55	55	389	13.5	115	95	140	4	45	M8	3
LSES 90 LU	FFB2	190	-	-	151	160	55	55	389	13.5	115	95	140	4	45	M8	3
LS 100 L	FFB2, 3	200	-	-	156	160	55	55	437	14.5	130	110	160	4	45	M8	3.5
LSES 100 L	FFB2	200	-	-	156	160	55	55	437	14.5	130	110	160	4	45	M8	3.5
LSES 100 LR	FFB2	200	-	-	140	160	55	55	437	14.5	130	110	160	4	45	M8	3.5
LSES 100 LG	FFB2, 3	235	-	-	165	160	55	55	423	13.5	130	110	160	4	45	M8	3.5
LS 112 M	FFB2	200	-	-	156	160	55	55	437	14.5	130	110	160	4	45	M8	3.5
LS 112 MG	FFB3	235	-	-	165	160	55	55	448	22.5	130	110	160	4	45	M8	3.5
LSES 112 MG	FFB2	235	-	-	165	160	55	55	448	22.5	130	110	160	4	45	M8	3.5
LSES 112 MU	FFB3	235	-	-	165	160	55	55	448	22.5	130	110	160	4	45	M8	3.5
LS 132 S	FFB3	227	130	45	168	160	55	55	490	40.5	165	130	200	4	45	M10	3.5
LSES 132 S	FFB3	227	130	45	168	160	55	55	490	40.5	165	130	200	4	45	M10	3.5
LSES 132 SM	FFB4	272	140	45	186	160	55	55	596	25	165	130	200	4	45	M10	3.5
LS 132 M	FFB4	272	140	45	186	160	55	55	596	25	165	130	200	4	45	M10	3.5
LSES 132 M	FFB4	272	140	45	186	160	55	55	596	25	165	130	200	4	45	M10	3.5
LSES 132 MU	FFB4	272	140	45	186	160	55	55	596	25	165	130	200	4	45	M10	3.5
LS 160 MP	FFB4, 5	272	155	45	186	160	55	55	671	66.5	165	130	200	4	45	M10	3.5
LSES 160 MP	FFB4	272	155	45	186	160	55	55	671	66.5	165	130	200	4	45	M10	3.5
LS 160 MR	FFB4	272	155	45	186	150	55	55	671	66.5	165	130	200	4	45	M10	3.5
LSES 160 MR	FFB4	272	155	45	186	160	55	55	671	66.5	165	130	200	4	45	M10	3.5

1. Housing diameter without lifting rings

Motor type	Brake type	Output shaft details										
		D	E	F	G	GD	L	LO	rs	ts	ts1	M.OxP
LS 71	FFB1	14j6	30	5	11	5	25	4	-	-	-	M5x12.4
LS(ES) 80	FFB1, 2	19j6	40	6	15.5	6	30	6	0.5	2	20	M6x16
LS(ES) 90	FFB1, 2	24j6	50	8	20	7	40	6	0.5	2	20	M8x19
LS(ES) 100	FFB2, 3	28j6	60	8	24	7	50	6	0.5	2	20	M10x22
LS(ES) 112	FFB2, 3	28j6	60	8	24	7	50	6	0.5	2	20	M10x22
LS(ES) 132	FFB3, 4	38k6	80	10	33	8	63	10	0.5	2	20	M12x28
LS(ES) 160	FFB4, 5	42k6	110	12	37	8	100	6	0.8	1	45	M16x36



**Designation**

4P	FLSES	80	LG	0.75 kW	IFT/IE3	IM 3001 (IM B5)	230/400V 50 Hz	UG	FFB	1	12 N.m	OPTIONS	
Number of poles, speed: 2, 4, 6	Motor series: <b>FLSES</b>	Frame size: 80 to 160	Length code and manufacturer code: L, <b>LG</b> , LR, LU, LUR M, MG, MP, MR, MU SL, SM	Rated power (kW) (or starting torque N.m on request): 0.75 to 15 kW	Range - Efficiency class: <b>FLSES IFT/IE3</b>	Operating position: - Foot or foot and flange mounted: IM 1001 (IM B3), IM 1051 (IM B6), IM 1061 (IM B7), IM 1071 (IM B8), IM 1011 (IM V5), IM 1031 (IM V6), IM 2001 (IM B35), IM 2011 (IM V15), IM 2031 (IM V36), IM 2101 (IM B34), IM 2111 (IM V58), IM 2131 (IM V69) - Flange mounted: <b>IM 3001 (IM B5)</b> , IM 3011 (IM V1), IM 3031 (IM V3), IM 3601 (IM B14), IM 3611 (IM V18), IM 3631 (IM V19)	Supply voltage(V) and frequency (Hz), connection: <b>230V/380/400/415V 50 Hz - 460V 60 Hz</b>	Application: <b>UG: General applications</b> UL: Hoisting applications	Brake serie: <b>FFB</b>	Brake size: 1 to 5	Braking torque (N.m): 4.5 to 200 N.m	Two-speed on request	<ul style="list-style-type: none"> <li>PTO, PTC (80 to 132), KTY and PT100 sensors</li> <li>Drain holes</li> <li>Separate brake power supply</li> </ul>

## Description of FLSES FFB

### Description of FLSES FFB brake motors

Component	Materials	Comments
Finned housing	Cast iron	<ul style="list-style-type: none"> <li>- with integral feet (4 fixing holes), or without feet</li> <li>- lifting ring for frame size <math>\geq 100</math></li> <li>- ground terminal with an optional jumper screw</li> </ul>
Stator	Insulated low-carbon magnetic steel laminations Electroplated copper	<ul style="list-style-type: none"> <li>- low carbon content guarantees long-term lamination pack stability</li> <li>- semi-enclosed slots</li> <li>- class F insulation</li> </ul>
Rotor	Insulated low-carbon magnetic steel laminations Aluminium	<ul style="list-style-type: none"> <li>- inclined cage bars</li> <li>- rotor cage pressure die-cast in aluminium (or alloy for special applications)</li> <li>- rotor balanced dynamically, 1/2 key</li> </ul>
Shaft	Steel	<ul style="list-style-type: none"> <li>- for all frame sizes <math>\leq 132</math>:           <ul style="list-style-type: none"> <li>• closed keyway</li> <li>• tapped centre hole</li> </ul> </li> <li>- for frame sizes <math>\leq 160</math>:           <ul style="list-style-type: none"> <li>• open keyway</li> <li>• tapped centre hole</li> </ul> </li> </ul>
End shields	Cast iron	<ul style="list-style-type: none"> <li>- DE and NDE, assembled using tie rods</li> </ul>
Bearings		<ul style="list-style-type: none"> <li>- protected ball bearings, permanently greased</li> <li>- bearings preloaded at non drive end</li> </ul>
Lipseals Labyrinth seal	Synthetic rubber	<ul style="list-style-type: none"> <li>- labyrinth seal at drive end for foot mounted motors, frame size <math>\leq 132</math></li> <li>- lipseal at drive end for foot and flange mounted or flange mounted motors, frame size <math>\leq 132</math></li> <li>- DE and NDE lipseal for frame size 160</li> </ul>
Fan	Composite material	<ul style="list-style-type: none"> <li>- bi-directional: straight blades</li> </ul>
Fan cover	Pressed steel	<ul style="list-style-type: none"> <li>- fitted, on request, with a drip cover for operation in vertical position, shaft end facing down</li> </ul>
Terminal box	Cast iron body and cover	<ul style="list-style-type: none"> <li>- IP55</li> <li>- fitted with a terminal block with 6 terminals</li> <li>- terminal box fitted with threaded plugs (brass cable glands as an option)</li> <li>- 1 ground terminal in each terminal box</li> <li>- fixing system consisting of a cover with captive screws</li> </ul>
Brake	Cast iron: yoke, backplate, release handle Anti-corrosion hardened steel: armature, screws, release lever Stainless steel: pressure springs, encoder extension Copper: brake coil	<p>FFB: failsafe brake with factory-set braking torque, already run in</p> <ul style="list-style-type: none"> <li>• 4.5 to 200 N.m of braking torque in accordance with IEC 60034, 60072, EN 50281</li> <li>• built-in power supply (including brake power supply unit); if it is separate (as an option) the power supply is independent of the motor (including brake power supply unit)</li> <li>• electromagnet encased in plastic to ensure it is fully sealed</li> </ul>
External finish		<ul style="list-style-type: none"> <li>- System IIa, shade RAL 6000 (green)</li> <li>- resistance to neutral saline mist: 240 h (in accordance with ISO 9227)</li> </ul>

From 0.75 to 15 kW in accordance with IEC 60034, as standard brake motors are wound as 230/380/400/415V 50Hz, 460V 60Hz with:

- power ratings  $\leq 5.5$  kW:  $\lambda$  connection
- power ratings  $\geq 7.5$  kW:  $\Delta$  connection

They are available in 2, 4 and 6-pole versions.

Adaptation to variable speed applications:

- FLSES IFT/IE3 serie Cabinet-mounted rive (offer on page 3).

Adaptation to particular environments:

- Dust (ATEX certification pending, IP55 in zone 22).

Equipment and options:

- brake release (auto-return hand release (DLRA), release lock off system (DLM) and remote lock off system (DMD))
- indicator lamps (release, wear)
- reduced response time (TRR)
- drain hole (non-standard positions : B3, B5, B14)
- encoder: incremental or absolute, and/or forced ventilation unit
- applications: UG General, UL Hoisting.

## Characteristics Tables

### FLSES FFB IFT/IE3

4 poles - 1500 rpm - IFT/IE3 - AC power supply

FLSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power	Rated torque	Starting torque/Rated torque	Maximum torque/Rated torque	Starting current/Rated current	Moment of inertia	Pull-up torque	Braking torque <sup>1</sup>	400V - 50Hz				Weight IM B3/B5 <sup>2</sup> kg
		P <sub>n</sub> kW	M <sub>n</sub> N.m	M <sub>d</sub> /M <sub>n</sub>	M <sub>m</sub> /M <sub>n</sub>	I <sub>d</sub> /I <sub>n</sub>	J kg.m <sup>2</sup>	M <sub>a</sub> N.m	M <sub>f</sub> N.m	N <sub>n</sub> rpm	I <sub>n</sub> A	η% 4/4	Cos φ 4/4	
FLSES 80 LG	FFB1	0.75	4.95	2.2	3.1	6.6	0.00357	14.1	12	1450	1.65	83.2	0.80	25.0
FLSES 90 SL	FFB2	1.1	7.25	2.4	3.2	7.5	0.00498	16.0	19	1450	2.3	84.8	0.81	30.8
FLSES 90 LU	FFB2	1.5	9.85	2.8	3.6	7.5	0.00604	27.1	19	1454	3.2	85.6	0.79	34.4
FLSES 100 LR	FFB2	2.2	14.5	3.5	3.9	8.3	0.00756	46.4	26	1452	4.6	86.9	0.79	42.6
FLSES 100 LG	FFB3	3	19.6	2.5	3.3	7.2	0.01232	46.1	52	1460	6.05	88.3	0.81	48.8
FLSES 112 MU	FFB3	4	26.2	2.7	3.1	7.1	0.01509	1.9	52	1458	8.1	88.8	0.80	55.5
FLSES 132 SM	FFB4	5.5	35.9	2.9	3.7	8.4	0.02842	98.7	69	1462	10.5	90.1	0.84	85.4
FLSES 132 MR	FFB4	7.5	49.1	2.8	3.4	8.5	0.03869	132.6	110	1460	13.8	90.6	0.86	104
FLSES 160 M	FFB4	9	58.5	2.4	3.1	8.3	0.06566	96.5	110	1468	16.7	91.3	0.85	120
FLSES 160 M	FFB5	11	71.7	2.3	2.9	7.6	0.07676	122	140	1466	20.1	91.7	0.86	132
FLSES 160LUR	FFB5	15	97.4	2.3	3.2	8.0	0.10096	195	180	1470	27.5	92.3	0.85	157

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

### 4 poles - 1500 rpm - IFT/IE3 - DRIVE power supply

FLSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Separate brake power supply - Factory-set braking torque

Motor type	Brake type	Rated power	400V - 50Hz			% Rated torque				
			Rated speed	Rated current	Power factor	M <sub>n</sub> at				
		P <sub>n</sub> kW	N <sub>n</sub> rpm	I <sub>n</sub> A	Cos φ 4/4	10 Hz	17 Hz	25 Hz	50 Hz	87 Hz
FLSES 80 LG	FFB1	0.75	1435	1.8	0.80	90%	100%	100%	100%	57%
FLSES 90 SL	FFB2	1.1	1430	2.6	0.81	90%	100%	100%	100%	57%
FLSES 90 LU	FFB2	1.5	1435	3.5	0.79	90%	100%	100%	100%	57%
FLSES 100 LR	FFB2	2.2	1440	5.0	0.79	90%	100%	100%	100%	57%
FLSES 100 LG	FFB3	3	1445	6.7	0.81	90%	100%	100%	100%	57%
FLSES 112 MU	FFB3	4	1440	8.8	0.80	90%	100%	100%	100%	57%
FLSES 132 SM	FFB4	5.5	1450	11.6	0.84	90%	90%	100%	100%	57%
FLSES 132 MR	FFB4	7.5	1445	15.7	0.86	90%	90%	100%	100%	57%
FLSES 160 M	FFB4	9	1440	19.3	0.83	90%	90%	100%	100%	57%
FLSES 160 M	FFB5	11	1454	22.7	0.86	85%	95%	100%	100%	57%
FLSES 160 LUR	FFB5	15	1458	30.7	0.85	85%	95%	100%	100%	57%

## Characteristics Tables

### FLSES FFB IFT/IE3

4 poles - 1500 rpm - IFT/IE3 - AC power supply

FLSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	Rated power P <sub>n</sub> kW	380V - 50Hz				415V - 50Hz				460V - 60Hz				
			Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4	Rated power P <sub>n</sub> kW	Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Efficiency IEC 60034-2-1 2007	Power factor Cos φ 4/4
FLSES 80 LG	FFB1	0.75	1450	1.65	82.6	0.83	1454	1.60	83.4	0.78	1.31	1758	1.45	85.4	0.76
FLSES 90 SL	FFB2	1.1	1450	2.35	84.1	0.84	1454	2.30	84.9	0.79	1.91	1758	2.05	86.4	0.78
FLSES 90 LU	FFB2	1.5	1454	3.25	85.3	0.82	1458	3.15	85.9	0.77	2.62	1762	2.80	87.3	0.77
FLSES 100 LR	FFB2	2.2	1452	4.70	86.7	0.81	1456	4.65	87.1	0.76	3.83	1762	4.10	88.3	0.76
FLSES 100 LG	FFB3	3	1460	6.20	87.7	0.84	1462	6.05	88.4	0.78	5.22	1766	5.35	90.0	0.79
FLSES 112 MU	FFB3	4	1458	8.30	88.6	0.83	1462	8.05	88.9	0.78	6.96	1764	7.45	85.5	0.79
FLSES 132 SM	FFB4	5.5	1462	10.9	89.6	0.86	1466	10.3	90.2	0.82	9.57	1768	9.25	91.2	0.82
FLSES 132 MR	FFB4	7.5	1460	14.5	90.4	0.87	1464	13.5	91.0	0.85	13.1	1768	12.2	91.7	0.85
FLSES 160 M	FFB4	9	1462	17.9	90.6	0.87	1462	17.9	91.7	0.83	15.7	1772	14.6	92.4	0.84
FLSES 160 M	FFB5	11	1466	21.0	91.4	0.87	1468	19.5	92.2	0.85	19.1	1772	17.5	92.9	0.85
FLSES 160LUR	FFB5	15	1470	28.7	92.1	0.87	1474	26.9	92.6	0.84	26.1	1774	24.1	93.3	0.84

4 poles - 1500 rpm - IFT/IE3 - DRIVE power supply

FLSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Separate brake power supply - Factory-set braking torque

Motor type	Brake type	Rated power P <sub>n</sub> kW	400V - 87Hz Δ <sup>1</sup>			Maximum mechanical speed rpm
			Rated speed N <sub>n</sub> rpm	Rated current I <sub>n</sub> A	Power factor Cos φ 4/4	
FLSES 80 LG	FFB1	1.31	2545	3.13	0.80	4500
FLSES 90 SL	FFB2	1.91	2540	4.47	0.81	4500
FLSES 90 LU	FFB2	2.61	2545	6.08	0.79	4500
FLSES 100 LR	FFB2	3.83	2550	8.76	0.79	4500
FLSES 100 LG	FFB3	5.22	2555	11.71	0.81	4500
FLSES 112 MU	FFB3	6.96	2550	15.37	0.80	4500
FLSES 132 SM	FFB4	9.57	2560	20.19	0.84	4500
FLSES 132 MR	FFB4	13.1	2555	27.34	0.86	4500
FLSES 160 M	FFB4	15.7	2572	31.20	0.87	4500
FLSES 160 M	FFB5	19.1	2564	39.49	0.86	4500
FLSES 160 LUR	FFB5	26.1	2568	53.43	0.85	4500

1. Data only applicable to motors: 400V 50Hz Y.

## Characteristics Tables

### IFT/IE3 BRAKE MOTORS

2 poles - 3000 rpm - IFT/IE3 - AC power supply

FLSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

Motor type	Brake type	400V - 50Hz												Weight IM B3/B5 <sup>2</sup>
		Rated power	Rated torque	Starting torque/ Rated torque	Maximum torque/ Rated torque	Starting current/ Rated current	Moment of inertia	Pull-up torque	Braking torque <sup>1</sup>	Rated speed	Rated current	Efficiency IEC 60034-2-1 2007	Power factor	
P <sub>n</sub> kW	M <sub>n</sub> N.m	M <sub>d</sub> /M <sub>n</sub>	M <sub>m</sub> /M <sub>n</sub>	I <sub>d</sub> /I <sub>n</sub>	J kg.m <sup>2</sup>	M <sub>a</sub> N.m	M <sub>f</sub> N.m	N <sub>n</sub> rpm	I <sub>n</sub> A	η% 4/4	Cos φ 4/4	kg		
FLSES 80 L	FFB1	0.75	2.50	2.8	3.6	7.0	0.00121	8.88	4.5	2885	1.60	81.7	0.83	19.2
FLSES 80 LG	FFB1	1.1	3.65	2.4	3.2	6.6	0.00227	9.67	12	2885	2.25	83.7	0.85	25.5
FLSES 90 SL	FFB1	1.5	4.95	2.9	3.0	7.0	0.00249	13.1	12	2890	3	85.0	0.85	27.0
FLSES 90 LU	FFB2	2.2	7.25	3.4	3.2	8.1	0.00376	21.8	19	2895	4.30	86.3	0.86	34.4
FLSES 100 L	FFB2	3	9.90	3.2	3.6	8.1	0.00448	25.7	19	2895	5.75	87.3	0.86	41.4
FLSES 112 MG	FFB2	4	13.1	2.1	3.0	7.2	0.01025	23.6	26	2920	7.50	88.5	0.87	51.0
FLSES 132 SM	FFB4	5.5	17.9	2.0	2.8	6.5	0.01058	34.0	55	2935	10.2	89.6	0.87	70.5
FLSES 132 SM	FFB4	7.5	24.4	2.1	2.9	6.9	0.01690	47.6	55	2940	13.9	90.7	0.86	89.1
FLSES 132 M	FFB4	9	29.2	2.5	3.2	7.6	0.01791	62.8	96	2940	16.8	91.3	0.85	92.7
FLSES 160 M	FFB4	11	35.5	3.4	3.1	8.5	0.07706	97.6	96	2956	19.3	92.2	0.89	135
FLSES 160 M	FFB4	15	48.6	2.9	2.9	7.3	0.06096	112	96	2950	26.7	92.4	0.88	148

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

6 poles - 1000 rpm - IFT/IE3 - AC power supply

FLSES FFB brake - 230Δ/380Y/400Y/415Y-460Y or 400V Δ - IP55 - Built-in power supply - Factory-set braking torque

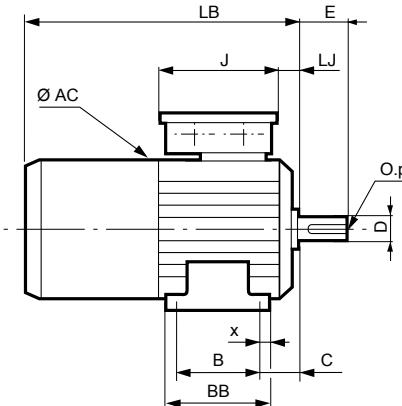
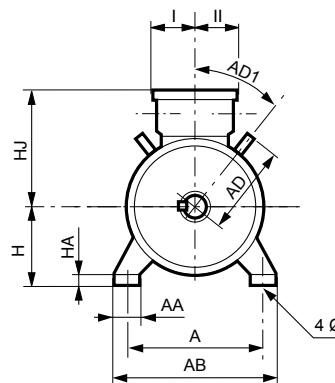
Motor type	Brake type	400V - 50Hz												Weight IM B3/B5 <sup>2</sup>
		Rated power	Rated torque	Starting torque/ Rated torque	Maximum torque/ Rated torque	Starting current/ Rated current	Moment of inertia	Pull-up torque	Braking torque <sup>1</sup>	Rated speed	Rated current	Efficiency IEC 60034-2-1 2007	Power factor	
P <sub>n</sub> kW	M <sub>n</sub> N.m	M <sub>d</sub> /M <sub>n</sub>	M <sub>m</sub> /M <sub>n</sub>	I <sub>d</sub> /I <sub>n</sub>	J kg.m <sup>2</sup>	M <sub>a</sub> N.m	M <sub>f</sub> N.m	N <sub>n</sub> rpm	I <sub>n</sub> A	η% 4/4	Cos φ 4/4	kg		
FLSES 90 SL	FFB2	0.75	7.55	1.9	2.3	4.5	0.00462	13.6	19	950	1.90	79.1	0.72	30.4
FLSES 90 LU	FFB2	1.1	11.0	2.3	2.6	4.8	0.00603	23.1	19	954	2.75	81.7	0.71	35.5
FLSES 100 LG	FFB2	1.5	14.8	2.4	2.8	5.7	0.01607	30.3	26	966	3.60	83.5	0.72	47.5
FLSES 112 MU	FFB3	2.2	21.7	2.3	2.8	0.6	0.01983	47.7	52	968	5.35	84.5	0.70	55.6
FLSES 132 SM	FFB4	3	29.5	2.7	3.1	6.4	0.03116	62.0	55	972	6.85	85.6	0.73	79.5
FLSES 132 M	FFB4	4	39.4	2.4	2.9	6.3	0.03615	82.7	96	970	9.15	87.3	0.72	87.2
FLSES 132 MU	FFB4	5.5	54.4	2.7	2.8	6.3	0.04287	112	96	966	11.9	88.2	0.76	102
FLSES 160 MU	FFB5	7.5	73.2	2.0	3.1	6.5	0.13533	124	140	978	17.4	89.5	0.77	134

1. Values given for information only; for standards-related restrictions, please consult Leroy-Somer.

2. These values are given for information only.

**FLSES FFB dimensions**

Dimensions in millimeters

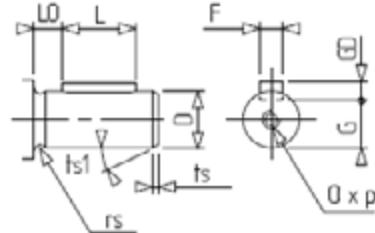
**FOOT MOUNTED IM B3 (IM 1001)**

Motor type	Brake type	Main dimensions																Weight <sup>2</sup> kg			
		A	AA	AB	AC <sup>1</sup>	AD	AD1	B	BB	C	H	HA	HJ	J	I	II	K	LB	LJ	x	
FLSES 80 L	FFB1	125	32	157	170	-	-	100	130	50	80	10	151	187	63.5	63.5	10	312	13.5	13	19.2
FLSES 80 LG	FFB1	125	32	157	185	-	-	100	130	52	80	10	161	187	63.5	63.5	10	389	13.5	13	25
FLSES 90 SL	FFB1, 2	140	26	170	185	135	40	125	162	56	90	10	173	187	63.5	63.5	10	389	13.5	29	30.8
FLSES 90 LU	FFB2	140	26	170	185	-	-	125	162	56	90	10	173	187	63.5	63.5	10	389	13.5	29	34.4
FLSES 100 L	FFB2	160	40	196	204	270	40	140	185	63	100	13	178	187	63.5	63.5	12	437	14.5	29	41.4
FLSES 100 LR	FFB2	160	40	196	204	270	40	140	185	63	100	13	178	187	63.5	63.5	12	437	14.5	29	42.6
FLSES 100 LG	FFB2, 3	160	49	196	230	-	-	140	170	63	100	13	187	187	63.5	63.5	12	448	23.5	11	48.8
FLSES 112 MG	FFB2	190	48	230	233	148	40	140	174	70	112	12	187	187	63.5	63.5	12	448	23.5	32	51
FLSES 112 MU	FFB3	190	48	230	233	148	40	140	174	70	112	12	187	187	63.5	63.5	12	448	23.5	32	55.5
FLSES 132 SM	FFB4	216	63	255	262	165	37.5	178	240	89	132	16	211	187	63.5	63.5	12	596	25	48	85.4
FLSES 132 M	FFB4	216	63	255	262	165	37.5	178	240	89	132	16	211	187	63.5	63.5	12	596	25	48	92.7
FLSES 132 MR	FFB4	216	63	255	262	165	37.5	178	240	89	132	16	211	187	63.5	63.5	12	596	25	48	104
FLSES 160 M	FFB4, 5	254	65	294	312	-	-	210	294	108	160	20	260	187	63.5	63.5	14.5	682	50.8	20	132
FLSES 160 MU	FFB5	254	65	294	312	178	45	210	294	108	160	20	260	187	63.5	63.5	14	677	50.8	20	134
FLSES 160 LUR	FFB5	254	65	294	312	178	45	254	294	108	160	20	260	187	63.5	63.5	14	682	50.8	20	157

1. Housing diameter without lifting rings

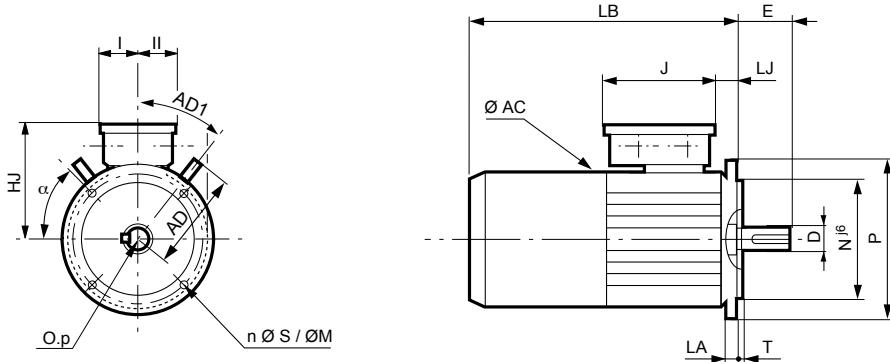
2. These values are given for information only

Motor type	Output shaft details												M.OxP
	D	E	F	G	GD	L	LO	rs	ts	ts1	M.OxP		
FLSES 80	19 <sup>6</sup>	40	6	15.5	6	30	6	0.5	2	20	M6x16		
FLSES 90	24 <sup>6</sup>	50	8	20	7	40	6	0.5	2	20	M8x19		
FLSES 100	28 <sup>6</sup>	60	8	24	7	50	6	0.5	2	20	M10x22		
FLSES 112	28 <sup>6</sup>	60	8	24	7	50	6	0.5	2	20	M10x22		
FLSES 132	38 <sup>6</sup>	80	10	33	8	63	10	0.5	2	20	M12x28		
FLSES 160	42 <sup>6</sup>	110	12	37	8	100	6	0.8	1	45	M16x36		



**FLSES FFB dimensions**

Dimensions in millimeters

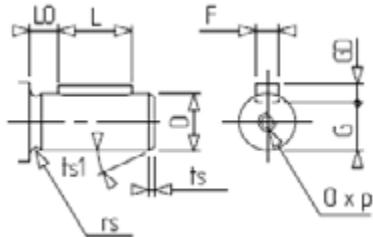
**FLANGE MOUNTED (FF) IM B5 (IM 3001)**

Motor type	Brake type	Main dimensions									IEC symbol	Flange (FF) output dimensions								Weight <sup>2</sup> kg
		AC <sup>1</sup>	AD	AD1	HJ	J	I	II	LB	LJ		M	N	P	n	α°	S	T	LA	
FLSES 80 L	FFB1	170	-	-	151	187	63.5	63.5	312	13.5	FF165	165	130	200	4	45	12	3.5	10	19.2
FLSES 80 LG	FFB1	185	-	-	161	187	63.5	63.5	409	34.5	FF165	165	130	200	4	45	12	3.5	10	25
FLSES 90 SL	FFB1, 2	185	135	40	173	187	63.5	63.5	409	33.5	FF165	165	130	200	4	45	12	3.5	10	30.8
FLSES 90 LU	FFB2	185	-	-	173	187	63.5	63.5	409	33.5	FF165	165	130	200	4	45	12	3.5	10	34.4
FLSES 100 L	FFB2	204	270	40	178	187	63.5	63.5	437	14.5	FF215	215	180	250	4	45	14.5	4	12	41.4
FLSES 100 LR	FFB2	204	270	40	178	187	63.5	63.5	437	14.5	FF215	215	180	250	4	45	15	4	12	42.6
FLSES 100 LG	FFB2, 3	233	-	-	187	187	63.5	63.5	448	23.5	FF215	215	180	250	4	45	14.5	4	12	48.8
FLSES 112 MG	FFB2	233	148	40	187	187	63.5	63.5	448	23.5	FF215	215	180	250	4	45	14.5	4	12	51
FLSES 112 MU	FFB3	233	148	40	187	187	63.5	63.5	448	23.5	FF215	215	180	250	4	45	14.5	4	11	55.5
FLSES 132 SM	FFB4	262	165	37.5	211	187	63.5	63.5	596	25	FF265	265	230	300	4	45	14.5	4	14	85.4
FLSES 132 M	FFB4	262	165	37.5	211	187	63.5	63.5	596	25	FF265	265	230	300	4	45	14.5	4	14	92.7
FLSES 132 MR	FFB4	262	165	37.5	211	187	63.5	63.5	596	25	FF265	265	230	300	4	45	14.5	4	12	104
FLSES 160 M	FFB4, 5	312	-	-	260	187	63.5	63.5	682	50.8	FF300	300	250	350	4	45	18.5	5	14	132
FLSES 160 MU	FFB5	312	178	45	260	187	63.5	63.5	677	50.8	FF300	300	250	350	4	45	18.5	5	14	134
FLSES 160 LUR	FFB5	312	178	45	260	187	63.5	63.5	682	50.8	FF300	300	250	350	4	45	18.5	5	14	157

1. Housing diameter without lifting rings

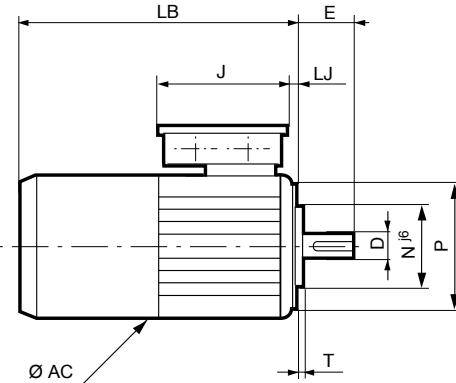
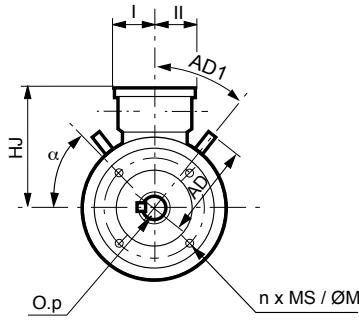
2. These values are given for information only

Motor type	Output shaft details										
	D	E	F	G	GD	L	LO	rs	ts	ts1	M.OxP
FLSES 80	19 <sup>6</sup>	40	6	15.5	6	30	6	0.5	2	20	M6x16
FLSES 90	24 <sup>6</sup>	50	8	20	7	40	6	0.5	2	20	M8x19
FLSES 100	28 <sup>6</sup>	60	8	24	7	50	6	0.5	2	20	M10x22
FLSES 112	28 <sup>6</sup>	60	8	24	7	50	6	0.5	2	20	M10x22
FLSES 132	38 <sup>6</sup>	80	10	33	8	63	10	0.5	2	20	M12x28
FLSES 160	42 <sup>6</sup>	110	12	37	8	100	6	0.8	1	45	M16x36



**FLSES FFB dimensions**

Dimensions in millimeters

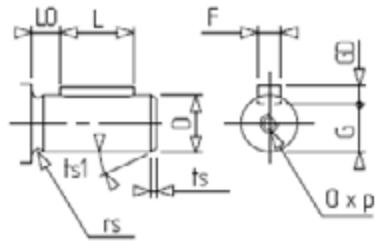
**FACE MOUNTED (FT) IM B14 (IM 3601)**

Motor type	Brake type	Main dimensions								IEC symbol	Faceplate (FT) output dimensions							Weight <sup>2</sup> kg
		AC <sup>1</sup>	AD	AD1	HJ	J	I	II	LB		M	N	P	n	α°	MS	T	
FLSES 80 L	FFB1	170	-	-	151	187	63.5	63.5	312	13.5	100	80	120	4	45	M6	3	19.2
FLSES 80 LG	FFB1	185	-	-	161	187	63.5	63.5	389	13.5	100	80	120	4	45	M6	3	25
FLSES 90 SL	FFB1, 2	185	135	40	173	187	63.5	63.5	389	13.5	115	95	140	4	45	M8	3	30.8
FLSES 90 LU	FFB2	185	-	-	173	187	63.5	63.5	389	13.5	115	95	140	4	45	M8	3	34.4
FLSES 100 L	FFB2	204	270	40	178	187	63.5	63.5	437	14.5	130	110	160	4	45	M8	3.5	41.4
FLSES 100 LR	FFB2	204	270	40	178	187	63.5	63.5	437	14.5	130	110	160	4	45	M8	3.5	42.6
FLSES 100 LG	FFB2, 3	233	-	-	187	187	63.5	63.5	448	23.5	130	110	160	4	45	M8	3.5	48.8
FLSES 112 MG	FFB2	233	148	40	187	187	63.5	63.5	448	23.5	130	110	160	4	45	M8	3.5	51
FLSES 112 MU	FFB3	233	148	40	187	187	63.5	63.5	448	23.5	130	110	160	4	45	M8	3.5	55.5
FLSES 132 SM	FFB4	262	165	37.5	211	187	63.5	63.5	596	25	165	130	200	4	45	M10	3.5	85.4
FLSES 132 M	FFB4	262	165	37.5	211	187	63.5	63.5	596	25	165	130	200	4	45	M10	3.5	92.7
FLSES 132 MR	FFB4	262	165	37.5	211	187	63.5	63.5	596	25	165	130	200	4	45	M10	3.5	104

1. Housing diameter without lifting rings

2. These values are given for information only

Motor type	Output shaft details										
	D	E	F	G	GD	L	LO	rs	ts	ts1	M.OxP
FLSES 80	19 <sup>6</sup>	40	6	15.5	6	30	6	0.5	2	20	M6x16
FLSES 90	24 <sup>6</sup>	50	8	20	7	40	6	0.5	2	20	M8x19
FLSES 100	28 <sup>6</sup>	60	8	24	7	50	6	0.5	2	20	M10x22
FLSES 112	28 <sup>6</sup>	60	8	24	7	50	6	0.5	2	20	M10x22
FLSES 132	38 <sup>6</sup>	80	10	33	8	63	10	0.5	2	20	M12x28



**List and compatibility of options**

	Non-std flange	DLRA	DLM	DMD	Optional Mf	Indicator release	Indicator wear	Cable gland	TRR	Drip cover	Drain holes	FV	Separate power supply	Absolute encoder	Incremental encoder	Sensors
Non-std flange	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Auto-return hand brake release (DLRA)	•	-	-	•	•	•	•	•	•	•	•	•	•	•	•	•
Release lock off system (DLM)	•	-	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Remote lock off system (DMD)	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Optional braking torque	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Release indicator (RD)	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Wear indicator (WI)	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Cable gland	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Reduce response time (TRR)	•	•	•	•	•	•	•	•	•	-	-	-	-	-	-	•
Drip cover (DC)	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Drain holes	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Axial forced ventilation	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Separate brake power supply: 180 VDC coil 400 VAC supply	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Adaptation and AE series absolute encoder	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Adaptation and IE series incremental encoder	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
PTO - PTC protection devices <sup>1</sup> , PT100 - KTY thermal sensors	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•

<sup>1</sup> PTC: as standard for frame size ≥ 160

- |   |               |
|---|---------------|
| • | Compatibility |
| - | Not available |

## Mechanical Options

### OPTIONAL FLANGES FOR LS(ES) SERIES

Motor type	Flange mounted (FF) motors (IM B5)								
	FF 85x70x105	FF 100x80x120	FF 115x95x140	FF 130x110x160	FF 165x130x200	FF 215x180x250	FF 265x230x300	FF 300x250x350	FF 350x300x400
LS 71		■	■	■	●	◆			
LS(ES) 80 L	■	■	■	■	●	◆			
LS(ES) 80 LG / 90	◆	◆	◆	◆	●	◆			
LS(ES) 100 L/LR	■	■	■	■	■	●	●	■	
LS(ES) 100 LG				■	■	●	◆	◆	
LS(ES) 112 M/MR	■	■	■	■	■	●		■	
LS(ES) 112 MG/MU				■	■	●	◆		
LS(ES) 132 S					■	◆	●		
LS(ES) 132 SM/M/MU					■	■	●	◆	
LS(ES) 160 LR/MP					■	◆	■	●	■
LS(ES) 160 M/L/MU/LUR						◆	■	●	◆
LS(ES) 180 MT/MR						◆	●	●	◆

● Standard      ■ Modified bearing location      ◆ Adaptable without shaft modifications

Motor type	Face mounted (FT) motors (IM B14)							
	FT 65x50x80	FT 75x60x90	FT 85x70x105	FT 100x80x120	FT 115x95x140	FT 130x110x160	FT 165x130x200	FT 215x180x250
LS 71	◆	◆	●	◆	◆	◆		
LS(ES) 80 L	◆	◆	●	●	◆	◆	◆	
LS(ES) 80 LG			◆	●	◆	◆	◆	
LS(ES) 90			◆	◆	●	◆	◆	
LS(ES) 100 L/LR			◆	◆	◆	●	◆	◆
LS(ES) 100 LG					◆	●	◆	◆
LS(ES) 112 M/MR		◆	◆	◆	◆	●	◆	◆
LS(ES) 112 MG/MU					◆	●	◆	◆
LS(ES) 132 S/SU					◆	◆	●	◆
LS(ES) 132 SM/M/MU					■	●	■	■
LS(ES) 160 MP, MR						●		●

● Standard      ■ Modified bearing location      ◆ Adaptable without shaft modifications

### OPTIONAL FLANGES FOR FLSES SERIES

Motor type	Flange mounted (FF) motors (IM B5)						
	FF 115x95x140	FF 130x110x160	FF 165x130x200	FF 215x180x250	FF 265x230x300	FF 300x250x350	FF 350x300x400
FLSES 80 L/LG	■	■	●	◆			
FLSES 90 SL/LU	◆	◆	●	◆			
FLSES 100 L/LR/LG	■	■	■	●			
FLSES 112 MG	■	■	■	●			
FLSES 112 MU		■	■	●	◆		
FLSES 132 SMM/MR/MU		■	■	◆	●		
FLSES 160 M/LUR/MU			■	◆	●	●	◆

● Standard      ■ Modified bearing location      ◆ Adaptable without shaft modifications

Motor type	Face mounted (FT) motors (IM B14)						
	FT 85x70x105	FT 100x80x120	FT 115x95x140	FT 130x110x160	FT 165x130x200	FT 215x180x250	FT 265x230x300
FLSES 80 L/LG	◆	●	◆	◆	◆		
FLSES 90 SL/LU		◆	●	◆	■		
FLSES 100 L/LR/LG		◆	●	◆	◆	◆	
FLSES 112 MG/MU		◆	●	◆	◆	◆	
FLSES 132 SMM/MR/MU			●	◆	◆	◆	◆

● Standard      ■ Modified bearing location      ◆ Adaptable without shaft modifications

## Mechanical Options

### RELEASE SYSTEMS

FFB brake motors can be equipped with a manual or electrical brake release system for carrying out maintenance operations such as adjustment and/or manual operation of the system being driven.



**Auto-return hand brake release (DLRA)**

Whenever the brake has been released, make sure that it is engaged once any maintenance operations have been completed.

As standard, the DLRA lever faces upwards like the terminal box; as an option and only on versions with a round frame, it can be mounted on the left, on the bottom, on the right counter-clockwise as seen from the drive end, independently of the terminal box.



**Lock off release system (DLM)**

The DLM lever is added to the DLRA lever which it follows in its operating position.

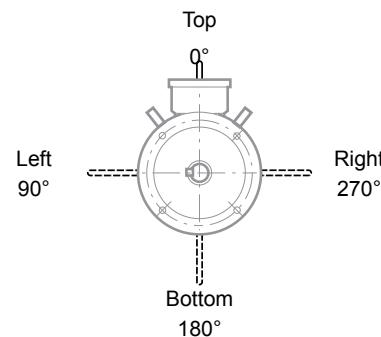


**Remote lock off release system (DMD)**

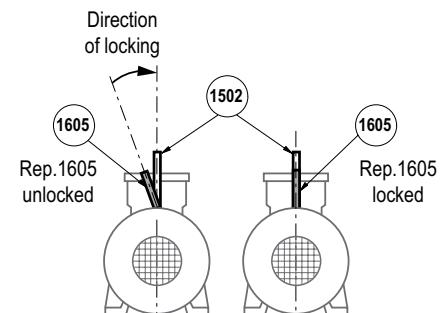
The DMD lever is added to the auto-return hand brake release which it follows in its operation position.

#### Compatibility with Forced Ventilation (FV) option

Direction	Mounting			
	B3	With FV	B5	With FV
0°	•	-	•	-
90 °	-	•	•	•
180°	-	-	•	-
270°	-	•	•	•



#### DLM-DMD lever operating positions



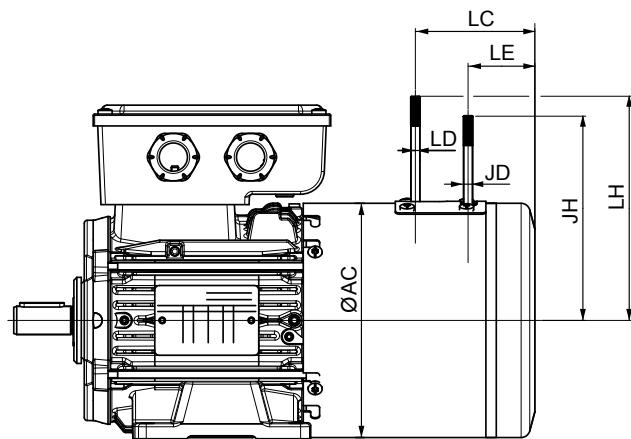
1502: DLRA control rod

1605: DLM-DMD control rod

Release	DLRA	DLM	DMD
Release action	Pull the lever rod towards the non-drive end (NDE)	Pull the lever rod (the one nearest the terminal box) towards the non-drive end (NDE), then swivel the DLM rod to lock	Electrical release: supply the brake coil with power separately from the motor
Keeping the brake released	Requires deliberate action	Permanently without external action	Supply the electromagnet on the lock control board with power. Once the locking contactor is energized, switch off the brake coil power supply and then that of the control board
Return to engaged position	Automatic once traction is eliminated	Automatic when the power is restored or via manual action	Automatic when the power is restored
Areas of use	Safety option: - practical for frequent releases - a safety measure because the brake cannot be left released by mistake.	Safety option: - quick release - saves time when returning to engaged position - a safety measure because it is a way of avoiding leaving the brake in released position	Safety option: - release and maintaining release remotely - setting a crane movement to weathervane mode

## Mechanical Options

Dimensions in millimeters



### LS(ES) FFB series dimensions

Frame size	DLRA				DLM - DMD <sup>1</sup>						
	AC	LC	Ø LD	LH	AC	LC	Ø LD	LH	LE	Ø JD	JH
LS 71	138	78	6	151	138	78	6	151	42	6	< LH
LS(ES) 80 L	158	82	6	151	158	82	6	151	46	6	< LH
LS(ES) 80 LG, 90 SL	184	131	6	151	184	131	6	151	96	6	< LH
LS(ES) 90 L	184	122	8	176	184	122	8	176	80	8	< LH
LS(ES) 90 LU	184	95	8	176	184	95	8	176	52	8	< LH
LS(ES) 100 LR, 112 MR	184	109	8	176	184	109	8	176	66	8	< LH
LS(ES) 100 LG	235	92	8	176	235	92	8	176	50	8	< LH
LS(ES) 112 MG	235	116	8	176	235	116	8	176	75	8	< LH
LS(ES) 100 L, 112 M	184	122	8	176	184	122	8	176	80	8	< LH
LS(ES) 112 MU	235	94	8	176	235	94	8	176	52	8	< LH
LS(ES) 132 S	220	116	8	176	220	116	8	176	75	8	< LH
LS(ES) 132 MU	265	157	13	307	265	157	13	307	99	13	< LH
LS(ES) 132 SM, M	265	180.5	13	307	265	180.5	13	307	122.5	13	< LH
LS(ES) 160 LR, MR	265	144	13	307	265	144	13	307	86	13	< LH
LS(ES) 160 MP	265	175	13	307	265	175	13	307	117	13	< LH
LS(ES) 160 M, L	309	162	13	307	309	162	13	307	106	13	< LH
LSES 160 MU, LU, LUR	309	142	13	307	309	142	13	307	86	13	< LH
LS(ES) 180 MT, LT	309	162	13	307	309	162	13	307	106	13	< LH
LS(ES) 180 MR, LR	309	142	13	307	309	142	13	307	86	13	< LH

1. DMD on FFB2 to FFB5

### FLSES FFB series dimensions

Frame size	DLRA				DLM - DMD <sup>1</sup>						
	AC	LC	Ø LD	LH	AC	LC	Ø LD	LH	LE	Ø JD	JH
FLSES 80 L	158	82	6	151	158	82	6	151	46	6	< LH
FLSES 80 LG	185	131	6	151	185	131	6	151	96	6	< LH
FLSES 90 SL	185	122	8	176	185	122	8	176	80	8	< LH
FLSES 90 LU	185	95	8	176	185	95	8	176	52	8	< LH
FLSES 100 L	204	122	8	176	204	122	8	176	80	8	< LH
FLSES 100 LR	204	109	8	176	204	109	8	176	66	8	< LH
FLSES 100 LG	235	116	8	176	235	116	8	176	75	8	< LH
FLSES 112 MG	235	116	8	176	235	116	8	176	75	8	< LH
FLSES 112 MU	235	94	8	176	235	94	8	176	52	8	< LH
FLSES 132 SM, M	265	180.5	13	307	265	180.5	13	307	122.5	13	< LH
FLSES 132 MR	265	132	13	307	265	132	13	307	74	13	< LH
FLSES 160 MU	309	142	13	307	309	142	13	307	86	13	< LH
FLSES 160 LUR	309	142	13	307	309	142	13	307	86	13	< LH

1. DMD on FFB2 to FFB5

## Mechanical Options

### OPTIONAL BRAKING TORQUE

If the application does not need the braking torque offered as standard on the brake motor (Characteristics Tables section),

as an option, the brake has different torques as shown in the table below.

**Braking torques (N.m) given for information only; for standards-related restrictions, please consult Leroy-Somer.**

	FFB1 <sup>1</sup>		FFB2		FFB3		FFB4		FFB5	
No. of springs	Color	$M_f$ (N.m)	Color	$M_f$ (N.m)	Color	$M_f$ (N.m)	Color	$M_f$ (N.m)	Color	$M_f$ (N.m)
3		4.5		11	-	-		41	-	-
4		6		15	-	-		55	-	-
5	Purple (RAL 4008)	7.5	White (RAL 1013)	19		37	Brown (RAL 8017)	69	-	-
6		9		23		45		83		120
7		10.5		26	Orange (RAL 2000)	52		96		140
8		12		30		59		110	Black (RAL 9005)	160
9	-	-	-	-		67	-	-		180
10	-	-	-	-		74	-	-		200

1.  $M_f$ : 7.5 N.m maximum for frame size 71

### INDICATOR MICROCONTACT (RELEASE/APPLICATION, WEAR)

As an option, the whole range of FFB brake motors can be equipped with a system to monitor the brake condition (release or application) and/or how worn the lining is. They are mounted and adjusted in the factory.

The microcontact wiring is connected in the terminal box on dominos (details in the table).

Indicators	Release indicator (Open/Close)	Wear indicator
Current	6A	6A
Voltage	250V	250V
Mounting	on dominos (3 wires - blue/black/gray) Black/Blue = NO Black/Gray = NC	on dominos (3 wires - blue/black/gray) Black/Blue = NO Black/Gray = NC

NO: normally open; NC: normally closed

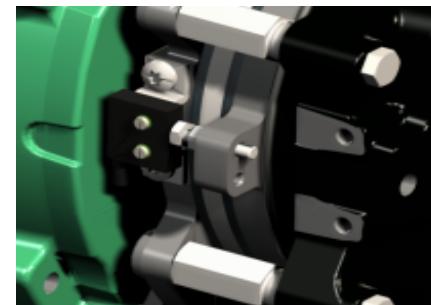
### RELEASE/APPLICATION INDICATOR



For brakes fitted with a release indicator, while the brake is supplied with power the armature actuates a microswitch (discrete) fixed on the yoke indicating brake release.

When the power is switched off, the microswitch changes state in order to confirm that the brake is engaged.

### WEAR INDICATOR



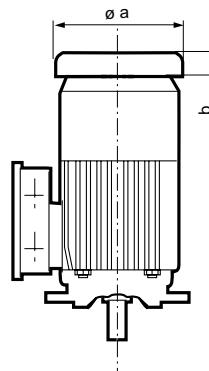
For brakes fitted with a wear indicator, if the brake lining is worn (+ 0.6 mm) the armature actuates the microswitch (discrete) fixed on the backplate and informs the user of the need to adjust the air gap or change the brake lining if it is less than the required minimum.

### DRIP COVER

For brake motors operating outdoors, with the drive shaft downwards (IM1011 V5, IM3001 V1, IM3611 V18), an optional drip cover is recommended. This is an option and should be specified on the order if required.

Type	Drip cover	
	a	b
LS(ES) 71	138	25
(F)LS(ES) 80	184	25
(F)LS(ES) 90	220	25
(F)LS(ES) 100	220	25
LS(ES) 112 M, MR	220	25
(F)LS(ES) 112 MG, MU	264	25
LS(ES) 132 S, SU	264	25
(F)LS(ES) 132 M, MU, SM, MR	310	25
(F)LS(ES) 160	310	25
LS(ES) 180	310	25

Dimensions in millimeters



## Electrical Options

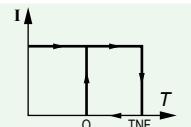
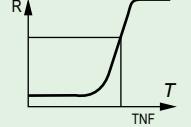
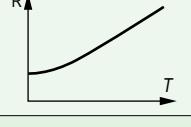
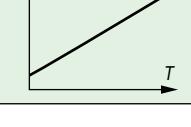
### SENSORS

Motors are protected by a manual or automatic overcurrent relay, placed between the isolating switch and the motor. This relay can in turn be protected by fuses. These protection devices provide total protection of the motor against non-transient overloads.

If a shorter reaction time is required, if you want to detect transient overloads, or if you wish to monitor temperature rises at "hot spots" in the motor or at strategic points in the installation for maintenance purposes, it is advisable to install heat sensors at sensitive points. The various types are shown in the table below, with a description of each.

We offer PTO, PTC, KTY and PT100 heat sensors. It must be emphasized that under no circumstances can these sensors be used to carry out direct regulation of the brake motor operating cycles.

### Built-in indirect thermal protection

Type	Operating principle	Operating curve	Breaking capacity (A)	Protection provided	Mounting Number of devices*
Normally closed thermal protection PTO	Bimetallic strip, indirectly heated, with normally closed (NC) contact		2.5 A at 250 V with cos φ 0.4	general surveillance for non-transient overloads	Mounted in control circuit 3 in series
Positive temperature coefficient thermistor PTC	Non-linear variable resistor, indirectly heated		0	general surveillance for transient overloads	Mounted with associated relay in control circuit 3 in series
Temperature sensor KT Y	Resistance depends on the winding temperature		0	high accuracy continuous surveillance of key hot spots	Mounted in control boards with associated reading equipment (or recorder) 1 per hot spot
Platinum resistance thermometer PT 100	Linear variable resistor, indirectly heated		0	high accuracy continuous surveillance of key hot spots	Mounted in control boards with associated reading equipment (or recorder) 1 per hot spot

- NRT: nominal running temperature

- The NRTs are chosen according to the position of the sensor in the motor and the temperature rise class.

- PTC: as standard on frame size ≥160

- KT Y 84/130 as standard

\* The number of devices relates to the winding protection.

### Fitting thermal protection

- PTO or PTF, in the control circuits
- PTC, with relay, in the control circuits
- PT 100 or thermocouples, with reading equipment or recorder, in the installation control panel for continuous surveillance

### Alarm and early warning

All protective equipment can be backed up by another type of protection (with different NRTs). The first device will then act as an early warning (light or sound signals given without shutting down the power circuits), and the second device will be an alarm (which shuts down the power circuits).

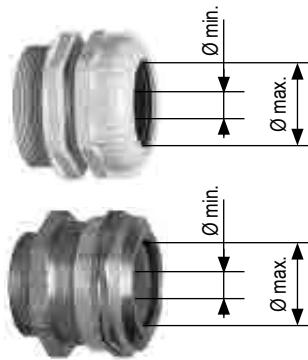
### Built-in direct thermal protection

For low rated currents, bimetallic strip-type protection can be used. The line current passes through the strip, which shuts down or restores the supply circuit as necessary. The design of this type of protection allows for manual or automatic reset.

## Electrical Options

### CABLE GLAND

The standard terminal box of the FFB brake motor has holes on sides 1 and 3 (Frame sizes 71 to 132 S, SU: 4 x ISO M20x1,5; frame sizes 132 SM, M, MU and 160: 2 x ISO M25x1,5 and 2 x ISO M20x1,5). These holes are closed with threaded plugs. An optional cable gland kit is available, otherwise procure the necessary cable glands in accordance with the table opposite:  
**Cable size and tightening of cable glands (Norme EN 50262)**



### LS, LSES FFB series for 400V std supply voltage

Brake motor type	Cable gland type	Standard cable gland (polyamide)		
		Cable size	Ø min. cable (mm)	Ø max. cable (mm)
LS 71 ; accessories	ISO 20a	5	12	2
LS, LSES 80 to 132 S, SU	ISO 20	7	14	2
LS, LSES 132 M to 180	ISO 25	9	18	3

### FLSES FFB series for 400V std supply voltage

Brake motor type	Cable gland type	Standard cable gland (polyamide)		
		Cable size	Ø min. cable (mm)	Ø max. cable (mm)
Accessories	ISO 20a	6	10	4
FLSES 80 to 112 MU	ISO 20	8	12	4
FLSES 132 M to 160 LUR	ISO 25	11.5	18	6

### FORCED VENTILATION

The forced ventilation option is used to:

- operate at zero speed continuously with a torque the same as the motor rated torque at 50 Hz.
- operate in overspeed mode:
  - n > 2600 rpm with 4 and 6 poles
  - n > 4500 rpm with 2 poles
- limit the machine temperature rise for operation with a drive.

### Characteristics

Brake motor frame size	Supply voltage <sup>1</sup>	Consumption		Index of protection <sup>2</sup>
		P (W)	I (A)	
71	Single-phase 230V	22	0.13	IP54
80	Single-phase 230/400V 50Hz	98	0.43/0.25	IP55
90 to 132	Single-phase 230/400V 50Hz	91	0.40/0.23	IP55
160, 180	Three-phase 230/400V 50Hz	150	0.94/0.55	IP55

1. ±10% for voltage, ±2% for frequency

2. Index of protection of the forced ventilation unit installed on the motor

### Dimensions

#### LS(ES) FFB series dimensions

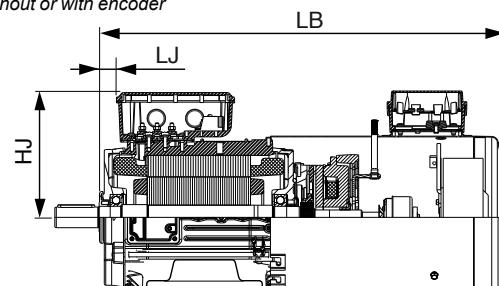
Frame size	Forced ventilation unit on FFB brake motor <sup>1</sup>		
	LB		HJ-LJ
	B3-B14	B5	
LS 71 M	386	386	
LS 71 L	396	396	
LS(ES) 80 L	427	427	
LS(ES) 80 LG	481	501	
LS(ES) 90 L, LU, SL	481	501	
LS(ES) 100 L, LR	529	529	
LS(ES) 100 LG	574	574	
LS(ES) 112 M, MR	529	529	
LS(ES) 112 MG, MU	574	574	
LS(ES) 132 S	615	615	
LS(ES) 132 SM, M, MU	711	711	
LS(ES) 160 LR, MP, MR	786	786	
LS(ES) 160 M, L	840	840	
LS(ES) 160 LUR	835	835	
LS(ES) 180 MR, LR	835	835	

1. FV without or with encoder

#### FLSES FFB series dimensions

Frame size	Forced ventilation unit on FFB brake motor <sup>1</sup>		
	LB		HJ-LJ
	B3-B14	B5	
FLSES 80 L	427	427	
FLSES 80 LG	481	501	
FLSES 90 SL, LU	481	501	
FLSES 100 L, LR	529	529	
FLSES 100 LG	574	574	
FLSES 112 MU, MG	574	574	
FLSES 132 SM, M, MR, MU	711	711	
FLSES 160 M, LUR	840	840	
FLSES 160 MU	835	835	

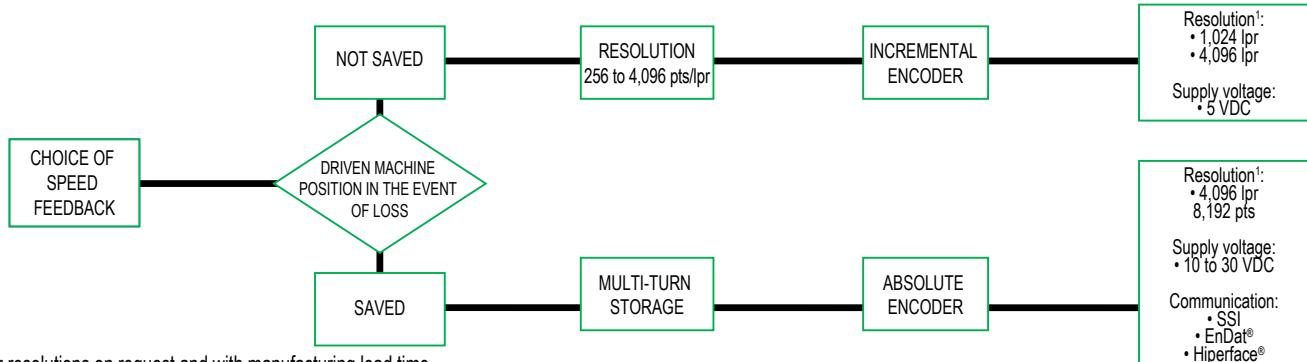
1. FV without or with encoder



## Electrical Options

### CHOICE OF SPEED FEEDBACK

#### Encoder Characteristics



<sup>1</sup>. Other resolutions on request and with manufacturing lead time

#### - Incremental encoder:

This generator supplies a number of pulses on channels A, A/, B, B/, 0 marker, 0/ marker proportional to the speed. A 1,024 lpr or 4096 lpr encoder is sufficient for most applications. However, where stability at very low speed (<10 rpm) is required, use of a higher resolution encoder is recommended. Our std EC-approved encoder is the 5VDC - 1,024 lpr or 4,096 lpr - TTL output - 150 mA - 10,000 rpm - IP64 - Temp. -40°C to +85°C.

#### - Multi-turn absolute encoder:

This saves the position in the revolution and also over several revolutions (max. 4,096), if the power source is disconnected. A reference point is no longer necessary. Data is transmitted via different communication protocols (EnDat2.1®, Hiperface®, SSI, etc.); some protocols are owned by a particular supplier. In certain cases, SinCos or incremental data is also available.

Our std CE, cURus, UL/CSA-approved encoder is the 10/30VDC - 8,192-pt - 4,096 lpr - 1V output - 55 mA - 12,000 rpm - IP64 - Temp. -40°C to +85°C.

### ENCODER DIMENSIONS

#### LS(ES) FFB series dimensions

Frame size	FFB brake + Encoder			
	HJ-LJ	J	B3-B14	B5
LS 71 M		197	329	329
LS 71 L		197	339	339
LS(ES) 80 L		197	355	355
LS(ES) 80 LG		197	436	456
LS(ES) 90 L, LU, SL		197	435	455
LS(ES) 100 L, LR		197	483	483
LS(ES) 100 LG		197	468	468
LS(ES) 112 M, MR		197	483	483
LS(ES) 112 MG, MU		197	493	493
LS(ES) 132 S, SU		197	534	534
LS(ES) 132 SM, M, MU		197	596	596
LS(ES) 132 MR		197	624	624
LS(ES) 160 MP		197	671	671
LS(ES) 160 LR, MR		197	699	699
LS(ES) 160 M, L		197	711	711
LS(ES) 160 LUR		197	706	706
LS(ES) 180 MR, LR		197	706	706

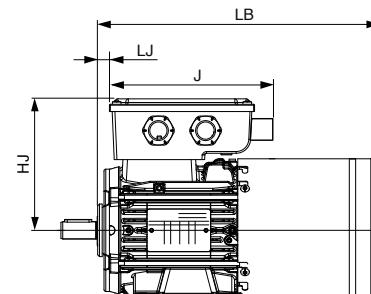
#### LS(ES) FFB series dimensions

Frame size	FFB + Encoder + Forced ventilation			
	HJ-LJ	J	B3-B14	B5
LS 71 M		197	386	386
LS 71 L		197	396	396
LS(ES) 80 L		197	427	427
LS(ES) 80 LG		197	481	501
LS(ES) 90 L, LU, SL		197	481	501
LS(ES) 100 L, LR		197	529	529
LS(ES) 100 LG		197	574	574
LS(ES) 112 M, MR		197	529	529
LS(ES) 112 MG, MU		197	574	574
LS(ES) 132 S, SU		197	615	615
LS(ES) 132 SM, M, MU, MR		197	711	711
LS(ES) 160 MP, LR, MR		197	786	786
LS(ES) 160 M, L, LUR		197	786	786

#### FLSES FFB series dimensions

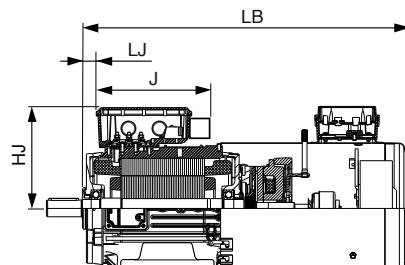
Frame size	FFB brake + Encoder			
	HJ-LJ	J	B3-B14	B5
FLSES 80 L		224	355	355
FLSES 80 LG		224	436	456
FLSES 90 SL, LU		224	436	456
FLSES 100 L, LR		224	483	483
FLSES 100 LG		224	493	493
FLSES 112 MU, MG		224	596	596
FLSES 132 SM, M, MU		224	624	624
FLSES 132 MR		224	711	711
FLSES 160 M, LUR		224	706	706
FLSES 160 MU		224	706	706

Dimensions in millimeters



#### FLSES FFB series dimensions

Frame size	FFB + Encoder + Forced ventilation			
	HJ-LJ	J	B3-B14	B5
FLSES 80 L		224	427	427
FLSES 80 LG		224	481	501
FLSES 90 SL, LU		224	481	501
FLSES 100 L, LR		224	529	529
FLSES 100 LG		224	574	574
FLSES 112 MU, MG		224	574	574
FLSES 132 SM, M, MR, MU		224	711	711
FLSES 160 M, LUR		224	840	840
FLSES 160 MU		224	835	835

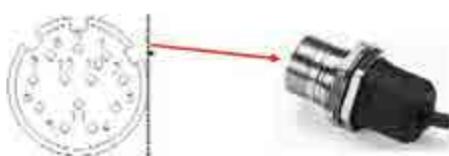


## Electrical Options

### ENCODERS CONNECTION

#### - Incremental encoder:

Terminal No.	
1	0V
2	+VDC
3	A
4	B
5	0
6	A
7	B
8	0
9	NC
10	NC
11	NC
12	NC



View of male connector base at the encoder end

NC: Not Connected (free)

#### - Absolute encoder:

17-pin HEIDENHAIN coupling											
Power supply					Incremental signals					Other signals	
	7	1	10	4	11	15	16	12	13	3	2
	Up	Sensor Up	0V	Sensor 0V	Internal shield	A+	A-	B+	B-	Vacant	Vacant
	—	Blue	White/ Green	White	/	Green/ Black	Yellow/ Black	Blue/ Black	Red/ Black	Red	Black

	Absolute position values						
	14	17	8	9	5	6	
	DATA	DATA	CLOCK	CLOCK	Vacant	Vacant	
	Gray	Pink	Violet	Yellow	Green	Brown	

**Shield** on housing; **Up** = power supply voltage

**Sensor:** The sensor line is connected internally with the corresponding power line.  
Vacant pins or wires must not be used!

## Identification

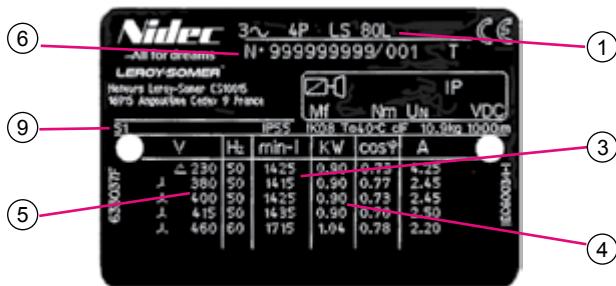
Check that the equipment conforms to the order: mounting arrangement, information on the nameplate.

Information ① to ⑪ should be quoted when ordering spare parts.

*Other logos can optionally be provided: agreement prior to ordering is essential.*

Example: LS 80 L IFT/NIE

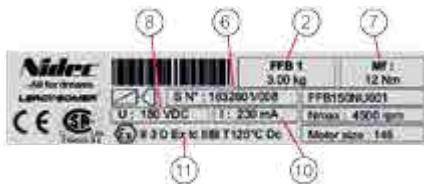
### MOTOR NAMEPLATE



#### Definition of symbols

- T: Impregnation class
- IE2: Efficiency class
- IP--IK--: Ingress protection\*
- Cl.F: Insulation class
- (Ta) 40°C: Ambient operating temperature
- cos P or φ: Power factor
- A: Rated current
- Δ: Delta connection
- λ: Star connection
- A: Vibration level
- H: Balancing mode

### BRAKE NAMEPLATE



Essential information included on the nameplates:

①	Motor series, frame size
②	FFB brake type
③	Speed of rotation (rpm)
④	Rated power (kW)
⑤	Motor voltage (V)
⑥	Motor and brake manufacturing no.
⑦	Mf: Braking torque (N.m)
⑧	U: Brake coil voltage (VDC)
⑨	Duty - Operating factor
⑩	I: Coil current (mA)
⑪	Special marking (ATEX)

Please quote when ordering spare parts

#### Bearings

- DE: Drive end bearing
- NDE: Non-drive end bearing

#### Marking

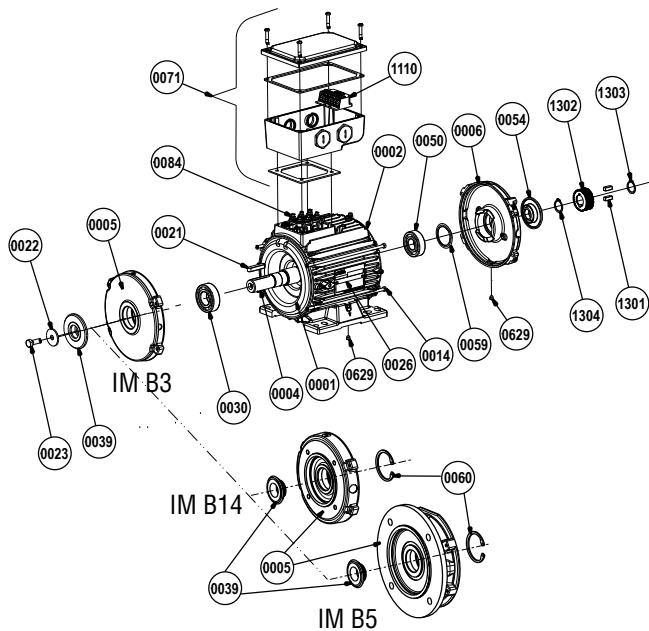
- Definition of symbols used on nameplates
- CE: Legal mark of conformity of product to the requirements of European Directives
- : Product certified CSA, conforming to UL

#### \*IK: Shock resistance

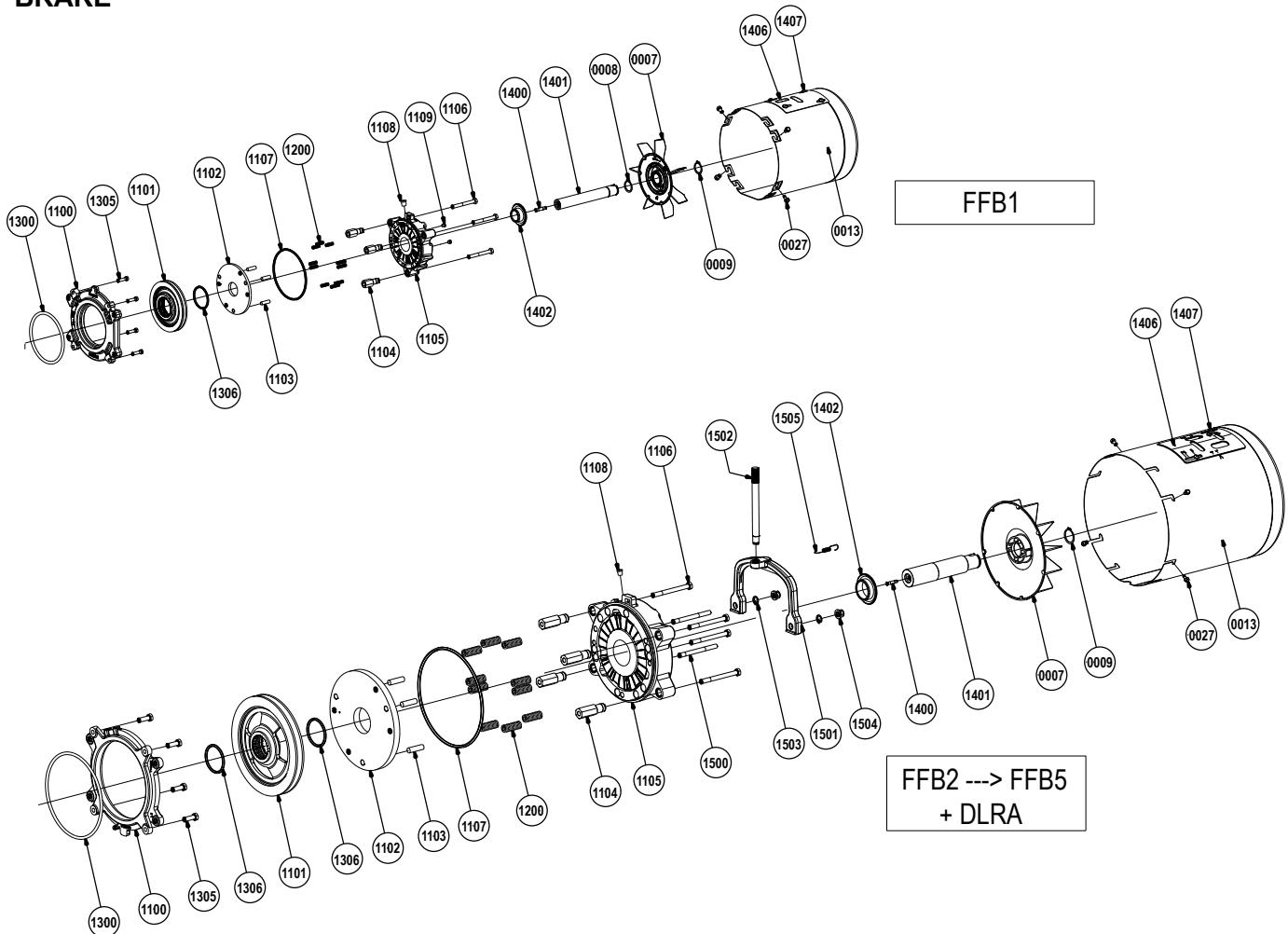
The motor can withstand a weak mechanical shock (IK 08 according to EN 50102). **The user must provide additional protection if there is a risk of significant mechanical shock.**

## Exploded Views

### MOTOR



### BRAKE



**Parts List**

No.	Name	Qty
1	Wound stator	1
2	Housing (frame)	1
4	Rotor	1
5	DE shield	1
6	Motor NDE shield	2
7	Fan	1
8	Fan washer (no.7)	0 or 1
9	Locking circlips (no.7)	1 or 2
13	Fan cover	1
14	Tie rods	3 or 4
21	Shaft end key (DE)	1
22	Shaft end washer	1
23	Locking screw (no.22)	1
25	Lifting ring (frame size $\geq$ 100)	2
26a	Motor nameplate	1
26b	Brake nameplate	1
27	Fan cover screws (no.13)	4
30	Drive end bearing (DE)	
39	Drive end weatherproof seal (DE)	1
50	Bearing on brake side (NDE)	1
54	Weatherproof seal on brake side (NDE)	1
59	Preloading (wavy) washer	1
60	Internal circlip	1
71	Terminal box	1
84	Terminal plate	1
629	Drain hole plug	1 or 2
1100	Friction backplate	1
1101	Brake disk	1
1102	Armature	1
1103	Pins	3 or 4
1104	Spacer	3 or 4
1105	Yoke	1
1106	Fixing screws (no.1105/1100)	3 or 4
1107	O ring seal	1
1108	Cable entry (no.1105)	1
1109	Pin hole blanking plug	2
1110	Brake power supply unit	1
1200	Compression spring	3 to 10
1300	o ring seal (between no.6 and no.1100)	1
1301	Splined ring key (rep.1302)	2
1302	Splined ring	1
1303	Retaining ring (no.1302)	1
1304	Washer	0 or 1
1305	Backplate fixing screws (no.1100)	3 or 4
1306	O ring seal (no.1101)	2
1400	Extension/shaft linking setscrew (no.1401/4)	1
1401	Extension shaft	1
1402	VLS seal (no.1105)	1
1406	Cover closing hatch	1
1407	Fixing screws (no.1406)	4

1500 to 1505: DLRA option (see section 6.1 of maintenance manual reference 5287)

xx Primary maintenance part

## Installation

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The following information is given for guidance only, and should never be used as a substitute for the current standards, nor does it relieve the installation company of its responsibility.

Depending on the installation, more optional elements can be added to the installation:

### RECEIPT

Check the state of the brake motor; if there is any damage to the motor or even its packaging, contact the carrier.

Check that the brake motor conforms to the order (mounting arrangement, information on the nameplates).

### STORAGE

Store the equipment in a clean, dry location, protected from shocks, vibrations, variations in temperature and in an environment with relative humidity of less than 90%.

Storage for longer than 6 months leads to special conditions, we will be happy to discuss these with you.

After storage for a period of more than 6 months, disconnect the brake power supply unit and check the winding insulation resistance (phase/earth resistance higher than 10 MΩ).

Drain any condensation water.

### COMMISSIONING

The brake motor is designed to operate at the speeds indicated on the nameplate (do not exceed the maximum speed stated on the brake nameplate: Nmax).

Comply with the voltages and frequencies indicated on the nameplate. (Do not deviate by more than 5% from the voltage extremes on the nameplate and by more than 1% from the frequencies).

For hoisting applications, do not use a motor that is not rated S3 (except for variable speed). Do not use a motor with a different duty type from that on the nameplate no.⑨ (see Motor Nameplate section on page 45).

### MECHANICAL INSTALLATION

See manuals ref. 5286 (FFB brake motor installation manual) and ref. 1889 (Recommendations for storing and commissioning AC motors manual).

If the brake motor has been stored at a temperature lower than -10°C, heat it and turn the shaft manually before starting up the machine.

If the brake motor is to be used at a temperature lower than -25°C, it must not be fitted with a sensor. It can be fitted with thermocouples.

**Ensure there is minimum clearance (corresponding to the length of the cover) at the non-drive end of the brake motor so it can be put down (inspections and brake adjustment).**

Install the brake motor in conditions conforming to those on the order (temperature, relative humidity, altitude).

When the brake motor is fitted with lifting rings, these are for lifting the brake motor on its own.

Mount the brake motor in the position specified on the order, on a flat, rigid base in order to prevent distortion and vibration.

Ensure the fixing screws are tightened to the correct tightening torque (class 8.8 minimum according to ISO 898-1), the screw diameter must be the right size for the fixing holes.

Ensure the mechanical shafts are aligned and the coupling and pulley are mounted in accordance with good practice.

**Do not knock** the motor (terminal box, cover), the shaft or the coupling during mounting, do not crush the seal, do not project beyond the shoulder of the shaft.

Ensure correct brake motor cooling, the air intakes and outlets must be kept clear.

Check that the loads applied to the motor shaft (especially the belt tension) are compatible with the values stated in our technical catalogues.

### WIRING

#### Drive power supply cables

These cables do not necessarily need shielding. Their cross-section is recommended in the drive documentation, however, it can be adapted according to the type of cable, installation method, the cable length (voltage drop), etc. See the Sizing power cables section below.

#### Motor power supply cables

These cables must be shielded to ensure EMC conformance of the installation. The cable shielding must be connected over 360° at both ends. At the motor end, special EMC cable glands are available as an option. The cable cross-section is recommended in the motor documentation, however, it can be adapted according to the type of cable, installation method, the cable length (voltage drop), etc. See the Sizing power cables section below.

#### Encoder cables

Shielding the sensor cables is important due to the high voltages and currents present at the drive output. This cable must be laid at least 30 cm away from any power cables. See the Encoders section.

## Installation

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### Sizing power cables

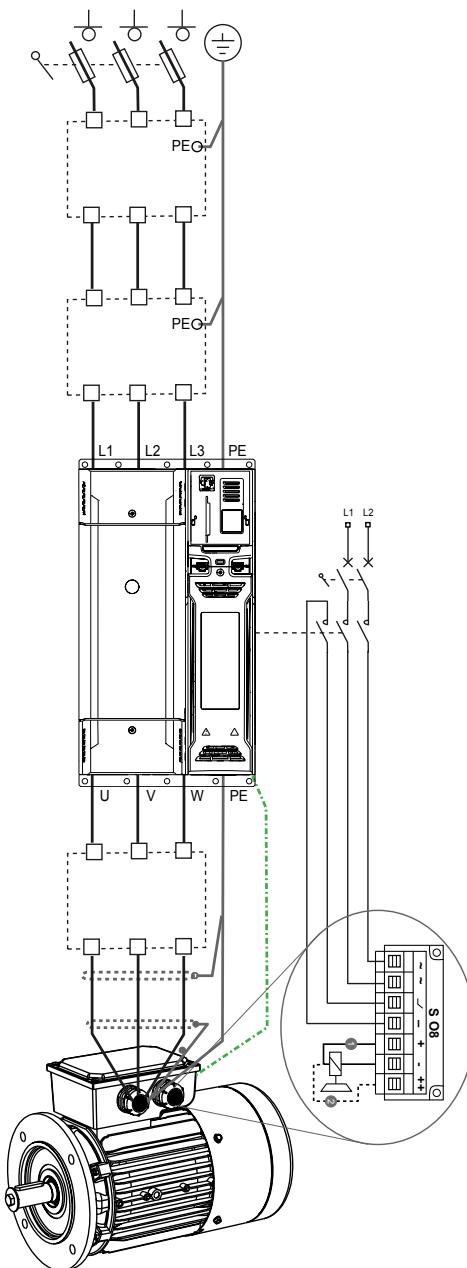
The drive and motor power supply cables must be sized according to the applicable standard, and according to the design current, stated in the drive documentation.

The different factors to be taken into account are:

- The installation method: in a conduit, a cable tray, suspended, etc.
- The type of conductor: copper or aluminum

Once the cable cross-section has been determined, check the voltage drop at the motor terminals. A significant voltage drop results in increased current and additional losses in the motor (temperature rise).

A variable speed drive and transformer system that have been grounded in accordance with good practice will contribute significantly to reducing the voltage on the shaft and the motor casing, resulting in fewer high-frequency leakage currents. Premature breakage of bearings and auxiliary equipment such as encoders should also be avoided wherever possible.



## Packaging Weights and Dimensions

### ROAD TRANSPORT (code 30) or AIR TRANSPORT (code 40)

Ref.	Cardboard boxes <sup>1</sup>	
	Tare kg	Dimensions (L x W x H) <sup>2</sup> mm
P0 000	0.25	245 x 190 x 150
P0 100	0.35	256 x 222 x 165
P0 200	0.40	330 x 288 x 172
R1	0.25	330 x 145 x 200
R2	0.50	420 x 200 x 240
R3	0.65	520 x 220 x 280
R4	1.05	550 x 320 x 360
R5	0.85	580 x 260 x 280
R6	1.30	780 x 300 x 430
R7	0.75	420 x 300 x 260
R8	0.90	500 x 330 x 290
R5 Marine	0.85	580 x 260 x 280

Open pallet box or open-slat crate		
Tare kg	Outer dimensions (L x W x H) <sup>2</sup> mm	Inner dimensions (L x W x H) <sup>2</sup> mm
10	720 x 420 x 550	650 x 350 x 400
26	830 x 520 x 660	760 x 450 x 500
30	990 x 570 x 620	920 x 500 x 550
47	920 x 870 x 700	850 x 800 x 550
48	990 x 870 x 880	920 x 800 x 720
45	1 270 x 870 x 700	1 200 x 800 x 550
47	1 270 x 870 x 880	1 200 x 800 x 720
61	1 270 x 1 070 x 730	1 200 x 1 000 x 550
62	1 270 x 1 070 x 900	1 200 x 1 000 x 720
64	1 270 x 1 070 x 1 050	1 200 x 1 000 x 870

### PACKAGING FOR SEA TRANSPORT (code 10)

Plywood crates		
Tare kg	Outer dimensions (L x W x H) <sup>2</sup> mm	Inner dimensions (L x W x H) <sup>2</sup> mm
20	740 x 480 x 730	680 x 420 x 600
26	840 x 520 x 710	760 x 440 x 530
30	980 x 560 x 720	920 x 500 x 550
58	1 120 x 750 x 850	1 040 x 680 x 670
60	1 100 x 950 x 680	1 020 x 870 x 500
80	1 100 x 950 x 1 180	1 020 x 870 x 1 000

1. Maximum permissible weight: 50 kg

2. These approximate values are given for individual packages. Packages grouped in open slat crates for quantity of machines supplied > 5, in the majority of cases.

## Configurator



The Leroy-Somer configurator can be used to choose the most suitable motor and provides the technical specifications and corresponding drawings.

- Help with product selection
- Print-outs of technical specifications
- Print-outs of 2D and 3D CAD files
- The equivalent of 300 catalogs in 11 languages.

*To register online:*

[http://www.nidecautomation.com/  
fr-FR/leroy-somer-motors-drives/  
Products/Configurator/](http://www.nidecautomation.com/fr-FR/leroy-somer-motors-drives/Products/Configurator/)



## Product Availability

Express Availability - FFB brake motors

IMinfinity® motors and FFB brake IFT/NIE (Not in any efficiency class)  
motors in italics excepted. Not covered by IE Standards - U.G.  
Standard environment - Fixed speed

AVAILABILITY TIMES EX WORKS (FRANCE), IN WORKING DAYS  
Orders received, within the maximum quantity limit, by the factory on day D before 12:00 pm Central European Time, will have the following Availability.  
For products with options, availability will be that of the longest lead-time item for the product or its options.  
If the order is received after 12:00 pm 1 working day on the mentioned availability will be added. See Office.  
The maximum quantity is per line of order. Above this maximum quantity, please consult your Sales Office.

0	D+1	D+2	D+3	D+4	D+5	Please consult
IP55 - Class F - 380VDC Built-on brake power supply - Factory standard torque	400 V ~ 50 Hz + option Forced ventilation VF	400 V ~ 50 Hz + option VF + 50 Hz	400 V ~ 50 Hz + option VF + 50 Hz	400 V ~ 50 Hz + option VF + 50 Hz	400 V ~ 50 Hz + option VF + 50 Hz	
230 / 400 V Y						
4 poles						
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All for dreams

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