

IMA-S Hygienic integrated servo actuator

●ENDURANCE TECHNOLOGY[®]

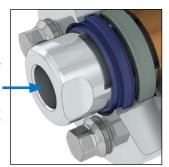
Patented



Designed for the most demanding food & beverage applications

The IMA-S is a hygienically designed integrated servo actuator for the food and beverage processing industry. The IP69K hygienic design features including 316 stainless steel construction, allows for open machine designs and clean-in-place compatibility.

PATENTED SCREW LUBRICATION SYSTEM FOR EXTENDED SERVICE LIFE



*U.S. PATENT NO. 8,196,484

The IMA-S's unique hygienic integrated design

Features:

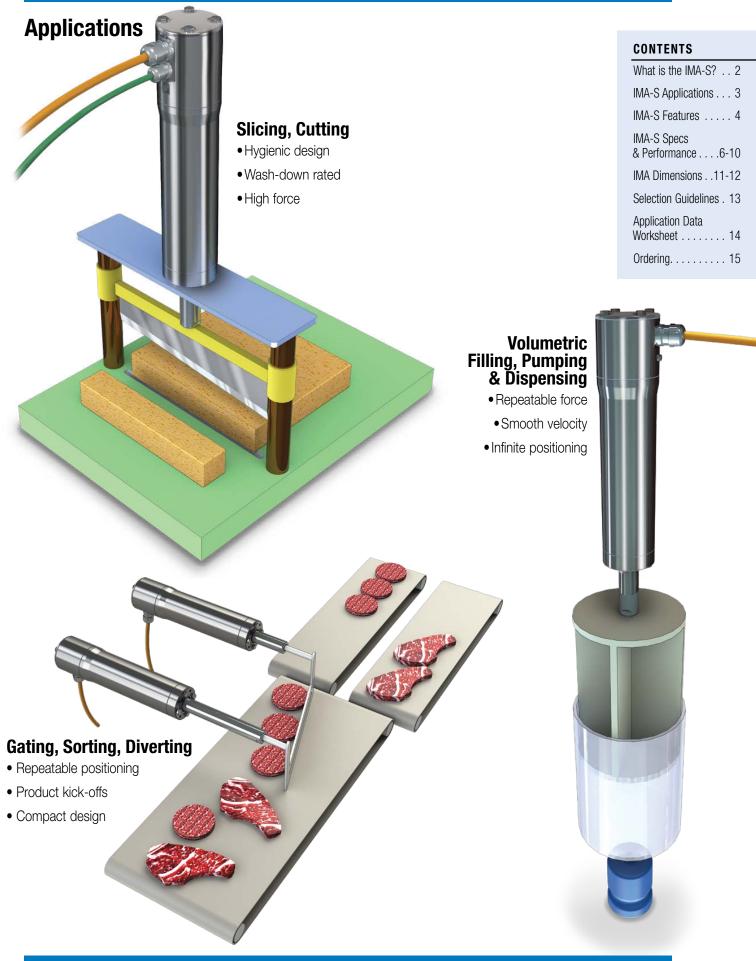
- Prevents bacterial growth
- Resists corrosion
- Provides IP69K wash-down protection
- Improves performance, flexibility, and efficiency

TOLOMATIC'S ELECTRIC ROD-STYLE ACTUATORS

	ERD	RSA	RSX	GSA	IMA
	Rod-Style Actuator	Rod-Style Actuator	Rod-Style Actuator	Guided Rod-Style Actuator	Integrated Servo Actuator
Force up to:	35 kN <i>(7,868 lbf</i>)	58 kN (1 <i>3,039 lbf</i>)	177.9 kN <i>(40,000 lbf)</i>	4.23 kN <i>(950 lbf)</i>	30.6 kN <i>(6,875 lbf)</i>
Speed up to:	1473 mm/sec <i>(58 in/sec)</i>	3,124 mm/sec (123 in/sec)	760 mm/sec (29.9 in/sec)	3,124 mm/sec (123 in/sec)	1,334 mm/sec (52.5 in/sec)
Stroke Length up to:	1000 mm <i>(39.4 in)</i>	1,524 mm <i>(60 in)</i>	1500 mm <i>(59 in)</i>	914 mm <i>(36 in)</i>	457 mm <i>(18 in)</i>
Screw/Nut Type	Solid, Ball & Roller	Solid, Ball & Roller	Roller	Solid & Ball	Ball & Roller
	Fo	r complete informatior	n see www.tolomatic.c	om or literature numb	er:
Literature Number:	2190-4000	3600-4166	2171-4001	3600-4166	2700-4000

(Not all models deliver maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)





IMA-S: HYGIENIC INTEGRATED SERVO ACTUATOR

●ENDURANCE TECHNOLOGY[®]

Endurance Technology features are designed for maximum durability to provide extended service life.

The IMA-S is a hygienically designed integrated servo actuator for the food and beverage processing industry. The hygienic design features all 316 stainless steel construction, IP69K ingress protection, blue seals/o-rings, and hygienic fasteners/cord grips allowing for open machine designs and clean-in-place compatibility. The product line also includes the IMA-SA model which incorporates an internal anti-rotate feature eliminating the need for an external guidance mechanism making it a perfect actuator for applications such as volumetric filling and pumping.





Tolomatic...MAXIMUM DURABILITY

• HIGH RESOLUTION FEEDBACK

OPTIONS:

•Multi-turn absolute encoder, Hiperface, Hiperface DSL, EnDat 2.2

- Resolver
- Incremental encoder

DRIVE/ROBOT • CONTROLLER TARILITY

Compatible with the following robot & drive/ controller manufacturers:

- Allen Bradley
- Beckhoff
- Bosch Rexroth
- Nidec
- Kollmorgen
- Lenze
- Siemens
- And More

•EHEDG (European Hygienic Engineering and Design Group) cord grip eliminates harborage points



•316 Stainless steel construction

•Superior corrosion resistance



- Chemically inert
- •Wear resistant
- FDA approved

MULTIPLE SCREW TECHNOLOGIES

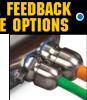
•Ball screws provide efficient motion at an economical price

•Roller screws provide the highest force and longest life



FLEX

 Single (DSL) and dual cable options



MA-SA INTERNAL 0

- Provides hygienic, internal anti-rotate feature, eliminating need for external quidance mechanism
- •Often used in volumetric filling and pumping applications

ADDITIONAL OPTIONS

•Brake

- Food grade grease •Externally threaded rod end Hygienic Fasteners
- Front flange mount
- FDA rod wipers
- Rear clevis mount

Tolomatic

Performance & Mechanical Specifications:

SERIES	STACK¹	NUT/ Screw	SCREW Lead	DYNAMIC Load Rating (1 mil revs)	CONT. Force	PEAK Force	MAX. Velocity	BASE INERTIA²	NERTIA Per UNIT of Stroke	SREAK- Way Orque	BACK DRIVE Force ³
S	S I	zω		kN kN	kN	kN	≥> mm/sec	kg-cm ²	kg-cm² / mm	M-m	N
	1	BN05	mm 5	5.72	0.45	1.45	355	0.6550	0.00017	0.34	217.95
T22	3	BN05	5	5.72	1.15	1.45	355	1.2572	0.00017	0.34	217.95
MA-ST22	1	BN10	10	4.40	0.22	1.36	497	0.6643	0.00021	0.34	111.20
N N	3	BN10	10	4.40	1.15	1.45	497	1.2695	0.00021	0.34	111.20
	1	BN05	5	8.71	1.19	4.45	304	2.2924	0.00040	0.54	346.94
	3	BN05	5	8.71	3.46	4.45	292	4.4048	0.00040	0.54	346.94
	1	BN10	10	5.40	0.60	2.90	497	2.3138	0.00047	0.54	173.47
	3	BN10	10	5.40	1.73	4.00	497	4.4312	0.00047	0.54	173.47
	1	BN20	10	11.39	0.30	1.45	497	2.5132	0.00156	0.54	88.96
MA-ST33	3	BN20	10	11.39	0.87	3.44	497	4.7137	0.00156	0.54	88.96
IA-9	1	RN04	4	41.08	1.30	6.30	243	2.2937	0.00043	0.60	435.90
∣≧	3	RN04	4	41.08	3.77	11.12	233	4.4079	0.00043	0.60	435.90
	1	RN05	5	45.42	1.04	5.04	304	2.2968	0.00044	0.60	346.94
	3	RN05	5	45.42	3.02	11.12	292	4.4116	0.00044	0.60	346.94
	1	RN10	10	45.42	0.52	2.52	497	2.3262	0.00054	0.60	173.47
	3	RN10	10	45.42	1.51	5.99	497	4.4488	0.00054	0.60	173.47
(33	3	RN04	4	45.42	3.77	11.12	233	4.8199	0.00118	0.72	524.86
MA-SA33	3	RN05	5	45.42	3.02	11.12	292	4.8254	0.00119	0.72	418.11
IMA	3	RN10	10	45.42	1.51	5.99	497	4.8991	0.00132	0.72	209.06
			in	lbf	lbf	lbf	in/sec	lb-in ²	lb-in ² /in	in-lb	lbf
2	1	BN05	0.197	1286	100	325	14.0	0.22383	0.00148	3	49
MA-ST22	3	BN05	0.197	1286	258	325	14.0	0.42960	0.00148	3	49
AA-	1	BN10	0.394	989	50	305	19.6	0.22701	0.00182	3	25
≤	3	BN10	0.394	989	258	325	19.6	0.43381	0.00182	3	25
	1	BN05	0.197	1958	269	1000	12.0	0.78337	0.00351	4.8	78
	3	BN05	0.197	1958	779	1000	11.5	1.50519	0.00351	4.8	78
	1	BN10	0.394	1214	134	651	19.6	0.79067	0.00408	4.8	39
	3	BN10	0.394	1214	389	900	19.6	1.51421	0.00408	4.8	39
33	1	BN20	0.394	2560	67	326	19.6	0.85882	0.01355	4.8	20
MA-ST33	3	BN20	0.394	2560	195	773	19.6	1.61076	0.01355	4.8	20
MA	1	RN04	0.157	9236	292	1417	9.6	0.78379	0.00372	5.3	98
-	3	RN04	0.157	9236	847	2500	9.2	1.50624	0.00372	5.3	98
	1	RN05	0.197	10211	234	1134	12.0	0.78485	0.00380	5.3	78
	3	RN05	0.197	10211	678	2500	11.5	1.50753	0.00380	5.3	78
	1	RN10	0.394	10211	117	567	19.6	0.79490	0.00468	5.3	39
	3	RN10	0.394	10211	339	1346	19.6	1.52022	0.00468	5.3	39
MA-SA33	3	RN04	0.157	10211	847	2500	9.2	1.64703	0.01022	6.4	118
A-9	3	RN05	0.197	10211	678	2500	11.5	1.64893	0.01029	6.4	94
	3	RN10	0.394	10211	339	1346	19.6	1.67409	0.01149	6.4	47

¹1 Stack winding MV21 / 41 3 Stack winding MV23 / 43 ²Value given is for a zero stroke actuator + To be determined, visit www.tolomatic.com for up-to-date information ³In vertical applications an unproversed IMA_S will require

³In vertical applications an unpowered IMA-S will require a brake to maintain position if the load on the actuator exceeds this value



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ACTUATOR FOR YOUR APPLICATION REQUIREMENTS AND DUTY CYCLE.



		IMA-ST22 (1 Stack, MV21/41)	IMA-S122 (3 Stack, MV23/43)	IMA-ST33 (1 Stack, MV21/41)	IMA-ST33 (3 stack, mv23/43)	IMA-SA33
176	тт	64	64	89	89	89
	in	2.52	2.52	3.504	3.504	3.504
VE	тт	76.2 to 304.8	152.4 to 304.8	76.2 to 457.2	152.4 to 457.2	0 to 304.8
	in	3.0 to 12.0	6.0 to 12.0	3.0 to 18.0	6.0 to 18.0	0.0 to 12
чυт	kg	4.8	6.1	10.2	12.5	13.9
	lb	10.5	13.4	22.5	27.5	30.6
NIT	kg/mm	0.0079	0.0079	0.0132	0.0132	0.0173
)KE	lb/in	0.4408	0.4408	0.7390	0.7390	0.9690
BN		<i>mm/300 = 0.051</i>	in/ft = 0.002	(0.004 in/ft for IMA-	-S33BN20)	
RN		mm/300 = 0.010	in/ft = 0.0004			
BN		mm = 0.1	in = 0.004			
RN		mm = 0.051	in = 0.002			
	°C	-20 to 40				
	°F	-4 to 104				
NG		IP69K (Static)				
ITY NG)		5 to 90%				
CK	CK 20 gpeak, half sine, 6ms, 3 axis, IEC 60068-2-27					
ON		2.5 grms, 30-200	0 Hz, 3-axis, 1hr, IE0	C 60068-2-64		
	KE BN RN BN RN GE NG ITY NG) CK	IZE in IKE in IKE ////////////////////////////////////	mm 64 in 2.52 in 3.0 to 12.0 in 3.0 to 12.0 in 3.0 to 12.0 in 10.5 in 0.0079 ike 1b in 0.4408 BN mm/300 = 0.051 RN mm/300 = 0.010 BN mm = 0.1 RN mm = 0.051 ige °C -20 to 40 ige if to 104 if the 104 NG IP69K (Static) if the 104 NG 20 gpeak, half sin	(1 STACK, MV21/41) (3 STACK, MV23/43) IZE mm 64 64 in 2.52 2.52 IKE mm 76.2 to 304.8 152.4 to 304.8 in 3.0 to 12.0 6.0 to 12.0 IKE kg 4.8 6.1 Ib 10.5 13.4 IKE kg/mm 0.0079 0.0079 Ib/in 0.4408 0.4408 BN mm/300 = 0.051 in/ft = 0.002 RN mm/300 = 0.010 in/ft = 0.004 BN mm = 0.1 in = 0.004 RN mm = 0.051 in = 0.002 GE °C -20 to 40 °F -4 to 104 NG IP69K (Static) ITY 5 to 90% CK 20 gpeak, half sine, 6ms, 3 axis, IEC 6	Item Item <t< th=""><th>Item Item <th< th=""></th<></th></t<>	Item Item <th< th=""></th<>

Performance & Mechanical Specifications:

*Value given is for an actuator with minimum stroke, add weight per unit of stroke to calculate weight of entire actuator

Motor Specifica											
		IMA-S22			IMA-S33			IMA-SA33			
WINDING/MOTO	DR VOLTAGE	MV21	MV41	MV23	MV43	MV21	MV41	MV23	MV43	MV23	MV43
TORQUE	N-m/A Peak	0.37	0.75	0.49	0.93	0.61	1.21	0.62	1.21	0.62	1.21
CONSTANT (Kt)	in-lb/A Peak	3.3	6.6	4.3	8.2	5.4	10.7	5.5	10.7	5.5	10.7
VOLTAGE Constant (K _e)	V/Krpm Peak	51	102	61	122	81	160	79.8	154	79.8	154
CONTINUOUS	N-m	0.42	0.42	1.07	1.07	1.12	1.12	3.24	3.24	3.24	3.24
STALL TORQUE	in-lb	3.7	3.7	9.5	9.5	9.9	9.9	28.7	28.7	28.7	28.7
CONTINUOUS Stall Current	A _{RMS}	0.8	0.4	1.55	0.775	1.3	0.65	3.7	1.85	3.7	1.85
PEAK TORQUE	N-m	2.54	2.54	4.51	4.51	5.42	5.42	13.22	12.88	13.22	12.88
FEAK IUNUUE	in-lb	22.5	22.5	39.9	39.9	48	48	117	114	117	114
PEAK CURRENT	A _{RMS}	4.8	2.4	6.6	3.45	6.3	3.3	15	7.5	15	7.5
RESISTANCE	Ohms	18.1	72.4	7.1	28.3	10	40.1	2.07	8.3	2.07	8.3
INDUCTANCE	mH	10.7	42	4.5	18	13.6	54.1	3.8	15	3.8	15
BUS VOLTAGE	V _{RMS}	230	460	230	460	230	460	230	460	230	460
SPEED @ RATED V	RPM		4,2	264		3,6	50	3,5	00	3,5	00
NO. OF POLES						8	3				

RoHs Compliant Components;

c¶N°us (€"

Performance data was validated using an aluminum face mount plate: IMA22/33 (8.25" x 7.0" x 0.7");

Ambient Temperature = 77°F (25°C); Elevation < 3281' (1,000 m); Drive specifications: Sinusoidal Commutation and PWM Voltage Source

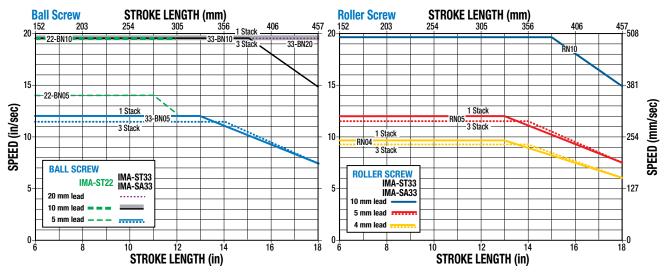
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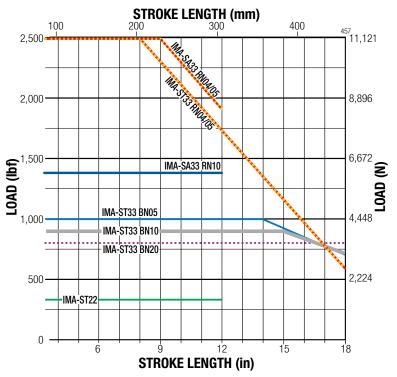
CRITICAL SPEED

sizeit.tolomatic.com for fast, accurate actuator selection ACTUATOR

SIZING



All curves represent properly lubricated and maintained actuators.

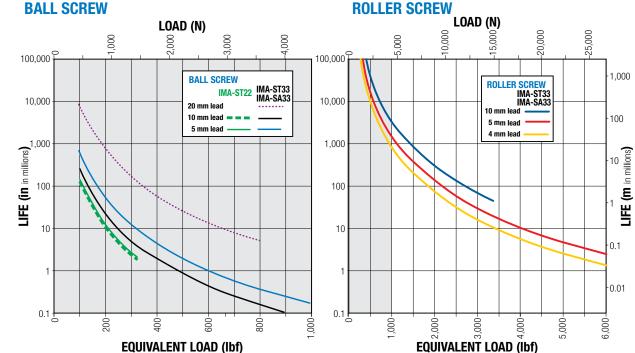


ROLLER SCREW BUCKLING LOAD

All curves represent properly lubricated and maintained actuators.



LIFE



NOTE: The L₁₀ expected life of a ball screw linear actuator is expressed as the linear travel distance that 90% of properly maintained ball screw manufactured are expected to meet or exceed. This is not a guarantee and this graph should be used for estimation purposes only. The underlying formula that defines this value is: $\mathbf{L}_{10} = \left(\frac{\mathbf{C}}{\mathbf{P}}\right)^3 \bullet \mathcal{L} \equiv$

L₁₀Travel life in millions of units (in or mm), where:

- $\mathbf{C} = \text{Dynamic load rating (lbf) or (N)}$
- **P**_e = Equivalent load (lbf) or (*N*) If load is constant across all movements then:
- actual load = equivalent load ℓ = Screw lead (in/rev) (mm/rev)

Use the 'Equivalent Load' calculation below, when the load is not constant throughout the entire stroke. In cases where there is only minor variation in loading, use greatest load for life calculations.

Where:
$$\mathbf{P}_{e} = \sqrt[3]{\frac{L_{1}(\mathbf{P}_{1})^{3} + L_{2}(\mathbf{P}_{2})^{3} + L_{3}(\mathbf{P}_{3})^{3} + L_{n}(\mathbf{P}_{n})^{3}}{1}$$

- $\mathbf{P}_{e} = \text{Equivalent load (lbf) or (N)}$
- \mathbf{P}_{n} = Each increment at different load (lbf) or (N)
- \bm{L} = Total distanced traveled per cycle (extend + retract stroke) [L = L_1 + L_2 + L_3 + L_n]
- L_n = Each increment of stroke at different load (in) or (mm)



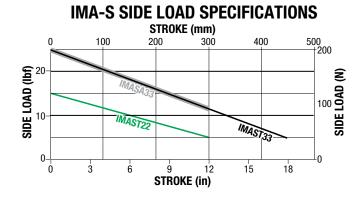
RE-LUBRICATION RECOMMENDATION:

IMA-ST33, IMA-SA33: Lubrication requirements for IMA-S electric actuators depend on the motion cycle (velocity, force, duty cycle), type of application, ambient temperature, environmental surrounding and various other factors. For many general purpose applications, Tolomatic ball screw actuators are typically considered lubricated for life unless otherwise specified, such as those actuator models outfitted with a re-lubrication feature. For roller screw or ball screw actuators outfitted with a re-lubricate the actuator at least once per year or every 1,000,000 cycles, whichever comes first, to maximize service life. For more demanding applications such as pressing, high frequency or other highly stressed applications, the re-lubrication interval for these actuators will vary and will need to be more frequent. In these

SIDE LOAD CONSIDERATIONS

The IMA-S integrated motor actuator is not meant to be used in applications where side loading occurs. Loads must be guided and supported. Loads should be aligned with the line of motion of the thrust rod. Side loading will affect the life of the actuator.







demanding applications, it is recommended to execute at least 5 full stroke moves every 5,000 cycles of operation (or more frequent if possible) to re-distribute the grease within the actuator.

Re-lubricate with standard Tolomatic Grease #2744-9099 or optional Food grade grease #2733-1303 into the grease zerk located on the rod end.

		Quantity					
	IMA-ST33	2.5 + [0.010 x L (mm)]	g				
	IMA-SA33	4.8 + [0.010 x L (mm)]	g				
	IMA-ST33	0.09 + [0.009 x L (in)]	0Z				
	IMA-SA33		0Z				
0	L=stroke length (mm or in)						
		_					

NOTE: IMA22ST does not accommodate relubrication

In some applications oil may leak from the grease zerk. In contamination sensitive applications replace grease zerk with plug.

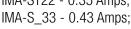
BRAKE CONSIDERATIONS

An un-powered IMA-S will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page IMAS_6.

A brake can be used with the actuator to keep it from

backdriving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when un-powered. See page IMAS_15 for ordering information.

NOTE: The optional Spring-Applied/Electronically-Released Brake requires 24V power. Input current rating: IMA-ST22 - 0.35 Amps;





See "B" dimension, pg. 11

Brake Specifications:

	SERIES	IMA-ST22	IMA-ST33	IMA-SA33
ROTOR	gm-cm ²	19	73	73
INERTIA	oz-in ²	0.052	0.112	0.112
CURRENT	Amp	0.35	0.43	0.43
HOLDING	N-m	1.6	4.0	4.0
TORQUE	in-lb	14	35	35
ENGAGE TIME	mSec	75	40	40
DISENGAGE TIME	mSec	20	50	50
VOLTAGE	Vdc		24	



IMAS 10

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions

Dimensions: All Sizes

DIMENSIONS

CA

SA33

3.75

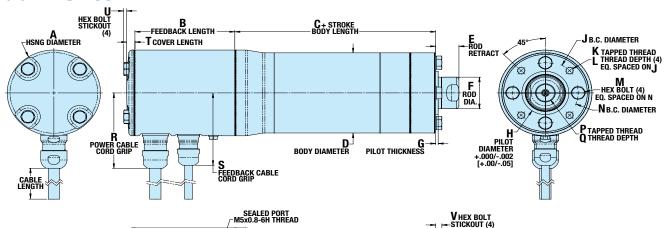
3.15

4.78

4.01

5.51

15.02

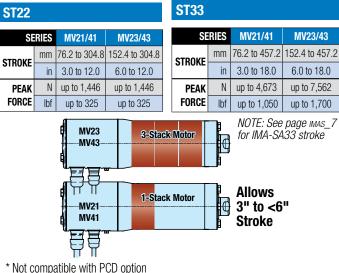


	ST22	ST33	SA33
Α	76.2	95.3	95.3
B1	87.7	80.0	80.0
B2	119.1	121.4	121.4
B3	113.9	102.0	102.0
B4	142.7	140.1	140.1
C1**	123.7	158.8	381.6
C2**	126.2	161.4	384.1
D	64.0	89.0	89.0
E1	18.4	23.7	23.7
E2	15.9	21.2	21.2
F G *	25.38	35.00	35.00
G *	2.54	2.54	2.54
Η*	35.500	48.000	48.000
J*	48.00	70.00	70.00
K *	М6х 1.0-6Н	М8х 1.25-6Н	М8х 1.25-6Н
L*	12.5	13.0	13.0
М	M5	M8	M8
Ν	48.00	67.00	67.00
Р	М12х 1.25-6Н	М20х 1.5-6Н	М20х 1.5-6Н
Q	16.0	25.4	25.4
R†	73.6	83.8	83.8
S †	70.4	80.4	80.4
Т	8.1	8.4	8.4
U1	1.7	3.1	3.1
U2	5.5	9.1	9.1
V1	4.5	6.3	6.3
V2	8.3	12.0	12.0

	SEALED PORT M5x0.8-6H THREAD



KEY FEATURES: 1-STACK & 3-STACK MOTORS



	C2**	in	4.97	6.35	15.12
	D	in	2.52	3.50	3.50
	E1	in	0.72	0.93	0.93
	E2	in	0.62	0.83	0.83
7.2	F	in	0.999	1.378	1.378
	G *	in	0.100	0.100	0.100
)	Η*	in	1.3976	1.8898	1.8898
2 D	J *	in	1.890	2.756	2.756
) 7	K *	mm	М6х 1.0-6Н	М8х 1.25-6Н	М8х 1.25-6Н
	L *	in	0.49	0.51	0.51
	Μ	тт	M5	M8	M8
	Ν	in	1.890	2.638	2.638
	Р	mm	М12х 1.25-6Н	М20х 1.5-6Н	M20x 1.5-6H
	Q	in	0.63	1.00	1.00
	R †	in	2.90	3.30	3.30
	S †	in	2.77	3.16	3.16
	T	in	0.32	0.33	0.33
	U1	in	0.07	0.12	0.12
	U2	in	0.22	0.36	0.36
	V1	in	0.18	0.25	0.25
	V2	in	0.33	0.47	0.47

Jnits

in

Α in

B1 in

B2 in

B3 in

B4 in

C1**

ST22

3.00

3.45

4.69

4.49

5.62

4.87

ST33

3.75

3.15

4.78

4.01

5.51

6.25

Dime	ensions	in	millimeters	
	011010110			

+ Only 1 cord grip required with Sick Hiperface DSL	
(no "S", separate feedback cable);	
22 size (74.9 mm [2.49"]); 33 size (85.4 mm [3.36"]))

** C1 for standard actuator; C2 for actuator with PCD option

Item	Code	Description
CA2 A2N B1 CT2 A2N		Allen Bradley VP Connector, SICK Hiperface DSL
		Tolomatic Standard VP Connector, SICK Hiperface DSL
	FA2 A2N	Allen Bradley Flying Lead, SICK Hiperface DSL
	FT2 A2N	Tolomatic Standard Flying Lead, SICK Hiperface DSL
	CA2 A2B	Allen Bradley VP Connector, SICK Hiperface DSL, Brake
B2	CT2 A2B	Tolomatic Standard VP Connector, SICK Hiperface DSL, Brake
DZ	FA2 A2B	Allen Bradley Flying Lead, SICK Hiperface DSL, Brake
	FT2 A2B	Tolomatic Standard Flying Lead, SICK Hiperface DSL, Brake
	FA1 A1N	Allen Bradley Flying Lead, SICK Hiperface
	FT1 A1N	Tolomatic Standard Flying Lead, SICK Hiperface
B3	FT1 D1N	Tolomatic Standard Flying Lead, Incremental
	FT1 H1N	Tolomatic Standard Flying Lead, Heidenhein Endat 2.2
	FT1 R1N	Tolomatic Standard Flving Lead, Resolver

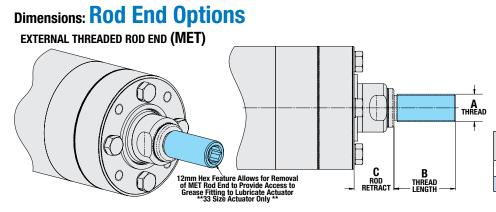
Dimensions in inches (threads are metric)
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ltem	Code	Description
	FA1 A1B	Allen Bradley Flying Lead, SICK HIPERFACE, Brake
	FT1 A1B	Tolomatic Standard Flying Lead, SICK HIPERFACE, Brake
B4	FT1 D1B	Tolomatic Standard Flying Lead, Incremental, Brake
	FT1 H1B	Tolomatic Standard Flying Lead, Heidenhein Endat 2.2, Brake
	FT1 R1B	Tolomatic Standard Flying Lead, Resolver, Brake
C1	—	Standard
C2	PCD	With PCD Option
E1	—	Standard
E2	PCD	With PCD Option
U1	—	Standard
U2	HYG2	With HYG2 Option
V1	_	Standard
V2	HYG2	With HYG2 Option



3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions





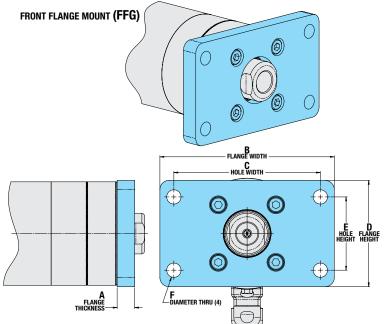
	ST22	ST33	SA33
A	M16x 1.5-6g	M20x 1.5-6g	M20x 1.5-6g
В	37.3	44.5	44.5
С	18.4	28.8	28.8

Dimensions in millimeters

	UNITS	ST22	ST33	SA33
Α	mm	М16х 1.5-6g	M20x 1.5-6g	M20x 1.5-6g
В	in	1.47	1.75	1.75
С	in	0.72	1.13	1.13

Dimensions in inches (threads are metric)

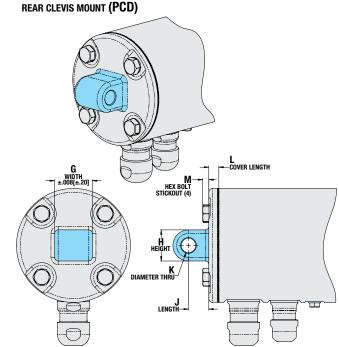
Dimensions: Mounting Options



	ST22	ST33	SA33
Α	11.2	15.0	15.0
В	117.3	150.0	150.0
C	100.0	126.0	126.0
D	67.3	91.4	91.4
Ε	50.0	63.0	63.0
F	8.7	12.3	12.3
Dimensions in millimeters			

	ST22	ST33	SA33
Α	0.44	0.59	0.59
В	4.62	5.91	5.91
C	3.94	4.96	4.96
D	2.65	3.60	3.60
Е	1.97	2.48	2.48
F	0.34	0.48	0.48

Dimensions in inches



	ST22	ST33	SA33
G	25.6	31.6	31.6
Н	22.0	26.0	26.0
J	14.1	17.1	17.1
К	10.036/ 10.000	12.043/ 12.000	12.043/ 12.000
L	8.1	8.4	8.4
M1*	3.6	5.2	5.2
M2*	7.4	10.9	10.9

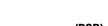
Dimensions in millimeters

	ST22	ST33	SA33
G	1.01	1.24	1.24
Н	0.87	1.02	1.02
J	0.56	0.67	0.67
К	0.3951/ 0.3937	0.4741/ 0.4724	0.4741/ 0.4724
L	0.32	0.33	0.33
M1*	0.14	0.20	0.20
M2*	0.29	0.43	0.43

Dimensions in inches

Tolomatic

*M1 Standard actuator; M2 with HYG2 option



Selection Guidelines

ESTABLISH MOTION PROFILE

Using the application stroke length, desired cycle time and loads establish the motion profile details.

2 COMPARE OPERATING (PEAK) FORCE AND VELOCITY TO OPERATING REGION

Calculate the application required operating (peak) force and velocity and compare to tables on pages IMAS_6. The calculated force and velocity must fall within the operating region of the actuator.

COMPARE SEVERE DUTY (CONTINUOUS) FORCE AND VELOCITY TO SEVERE DUTY REGION

Calculate the RMS force and velocity required and compare to tables on pages IMAS_6-7. The calculated force and velocity must fall within the severe duty region.

T _ (sum $(\mathbf{T}_{i}^{2} \times \mathbf{t}_{i})$	V – 4	sum $(\mathbf{V}_{i}^{2} \times \mathbf{t}_{i})$
RMS	sum (t _i)	RMS	sum (t _i)

CONSIDER SCREW/NUT CHOICES

Choose roller nuts for its longer life (see Life graph on page IMAS_9) and higher peak loads (see graphs on page IMAS_8). Ball nuts are cost competitive and more efficient (see table on page IMAS_6).

SCREW ACCURACY			
Roller Nut	± 0.0004"/ft.	± 0.0102mm/300mm	
Ball Nut	± 0.002"/ft.	± 0.051mm/300mm	

5 VERIFY CRITICAL SPEED OF THE SCREW Verify that the application's peak linear velocity does not exceed the critical speed value for the size and lead of the screw selected.

GVERIFY AXIAL BUCKLING STRENGTH OF THE SCREW

Verify that the peak force does not exceed the critical buckling force for the size of the screw selected.

MOTOR WINDINGS & VOLTAGES

Choose motor windings optimized for 230 Vac and 460 Vac voltage busses. The 1 stack motor (MV21-230V & MV41-460V), available for the IMA-S22/33, allows strokes of 3" (76.2mm) vs the minimum 6" (152.4mm) stroke required for 3 stack motors, providing the force needed for many applications in a more compact, lighter weight package

O CALCULATE LUBRICATION INTERVAL

See page IMAS_10 for an overview and IMA-S Users Guide (#2700-4016) for complete instructions to calculate lubrication interval.

TEMPERATURE

The IMA-S is intended to operate in an environment with an ambient temperature between -4 to $+104^{\circ}$ F, (-10 to $+40^{\circ}$ C). Performance should be de-rated if the ambient temperature is above 77°F (25°C). Contact the factory if the ambient temperature does not fit within this range. NOTE: Temperature of the actuator's body can approach 180°F (82°C) in aggressive applications. Adequate clearance to ensure actuator's ambient conditions do not rise drastically should be allowed.

1 O BRAKE CONSIDERATIONS An un-powered IMA-S will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page IMAS_8.

A brake can be used with the actuator to keep it from backdriving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when un-powered. See page IMAS_15 for ordering information.

NOTE: The optional Spring-Applied / Electronically Released Brake requires 24V power. Input current rating: IMA22 - 0.35 Amps; IMA33 - 0.43 Amps;

CHOOSE MOTOR CONNECTORS & FEEDBACK DEVICE

Connector choice and wiring emulates popular motor manufacturers for compatibility.

Cable/connector options include:

- Allen Bradley VP series
- Tolomatic standard
- Flying leads
- Cables are available in 3m, 5m and 10m lengths
- Feedback options include:
 - Incremental Encoder
 - Absolute Encoder, Hiperface, Hiperface DSL, EnDat 2.2
 - Resolver

Contact Tolomatic for additional motor connectors, feedback combinations and motor files for third party drives.

2 CONSIDER MOUNTING & ROD END OPTIONS

Examine mounting options dimensional drawings on page IMAS_12. Standard mounting on the IMA-S are 4 tapped holes on the front rod end face of the actuator. Other fixed mounting option is the Front Flange Mount (FFG). Pivoting mount option is the Rear Clevis Mount (PCD).

Rod End Option is: External Threaded Rod End (MET).

NOTE: Regardless of the mounting option chosen, care must be taken to ensure that the load is guided and in-line with the force rod's line of motion. Misalignment of the force rod's line of motion will cause degradation in the actuator's expected life.

CONSIDER ENVIRONMENTAL RATING AND ANTI-ROTATE OPTIONS

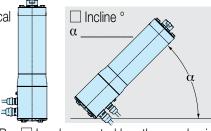
The environmental rating for a standard IMA-S is IP69K for protection against water and dust ingress. Choose the Anti-Rotate Option (IMA-SA) if required. Call Tolomatic at 1-800-328-2174 for help in determining the best actuator for your application.







U Vertical



ACTUATOR SIZING Or Call 1-800-328-2174 for Excellent Customer Service & Technical Support

Load supported by actuator OR Load supported by other mechanism

MOVE PROFILE

Horizontal

텶뤜

EXTEND

Move Distance		
🗌 inch	□ millimeters	
Move Time		sec
Max. Speed		
□ in/sec	□ mm/sec	
Dwell Time Afte	r Move	Sec
DETDACT		

RETRACT

Move Distance _		
🗌 inch	millimeters	
Move Time		sec
Max. Speed		
in/sec	mm/sec	

Dwell Time After Move _____se

NO. OF CYCLES

🗆 per minute 🛛 🗌

per hour

HOLD POSITIO	N?	🗆 Required
		🗆 Not Requi
After Move	D	uring Power Lo

STROKE LENGTH

order in mm ONLY millimeters (SM) (Metric) PRECISION

Repeatability

millimeters

OPERATING ENVIRONMENT

Temperature, Contamination, Water, etc.

EXTEND		RETRACT		
LOAD		LOAD		
U.S. Standard)	Metric)	U.S. Standard)	(Metric)	
FORCE		FORCE		
🗌 lbf	\Box N	🗌 lbf	\Box N	

NOTE: If load or force changes during cycle

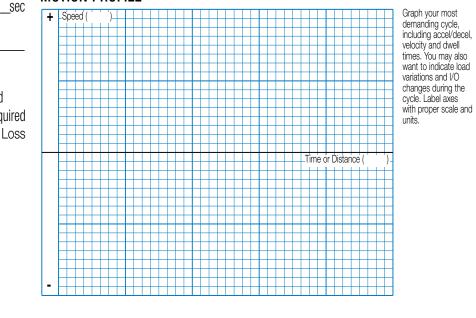
Ause the highest numbers for calculations

U.S. Standard) (Metric)

MOTION PROFILE

(Metric)

(U.S. Standard)



CONTACT INFORMATION Name, Phone, Email

Co. Name, Etc.

USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT www.tolomatic.com OR... CALL TOLOMATIC AT 1-800-328-2174. We will provide any

assistance needed to determine the proper actuator for the job.

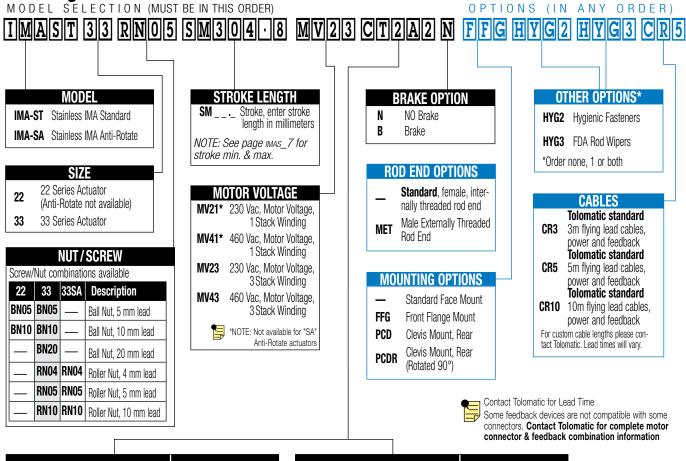
FAX 1-763-478-8080

EMAIL help@tolomatic.com

IMAS_14

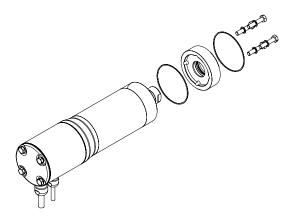


Ordering



MOTOR SERIES CONNECTORS		FEEDBACK DEVICE		
Cable + Allen Bradley VP Connector	CA2	A2	SICK Hiperface DSL	
Allen Bradley Flying Lead	FA1	A1	SICK Hiperface	
Allen Bradley Flying Lead	FA2	A2	SICK Hiperface DSL	
Cable + Tolomatic Std. VP Connector	CT2	A2	SICK Hiperface DSL	
Tolomatic Std. Flying Lead	FT1	D1	Incremental	

MOTOR SERIES CONNE	CTORS	FEE	DBACK DEVICE
Tolomatic Std. Flying Lea	ad FT1	A1	SICK Hiperface
Tolomatic Std. Flying Lea	ad FT1	H1	Heidenhein Endat 2.2
Tolomatic Std. Flying Lea	ad FT1	R1	Resolver
Tolomatic Std. Flying Lea	ad FT2	A2	SICK Hiperface DSL



REPLACEABLE SEAL CARTRIDGE				
Description	IMA-ST22	IMA-ST33	IMA-SA33	
Standard	2622-9070	2633-9070	2633-9070	
Standard with Rear Clevis Mount (PCD_)	2622-9071	2633-9071	2633-9071	
FDA Rod Wipers (HYG3)	2622-9072	2633-9072	2633-9072	
FDA Rod Wipers (HYG3	2622-9073	2633-9073	2633-9073	
with Rear Clevis Mount (PCD_)	2022-9013	2000-9070	2000-9070	



The Tolomatic Difference Expect More From the Industry Leader:



Unique linear actuator solutions with Endurance TechnologySM to solve your challenging application requirements.



The fastest delivery of catalog products... Built-to-order with configurable stroke lengths and flexible mounting options.



Online sizing that is easy to use, accurate and always up-to-date. Find a Tolomatic electric actuator to meet your requirements.



Match your motor with compatible mounting plates that ship with any Tolomatic electric actuator.



Easy to access CAD files available in the most popular formats to place directly into your assembly.



Extensive motion control knowledge: Expect prompt, courteous replies to any application and product questions from Tolomatic's industry experts.

Also Consider These Other Tolomatic Products:

Electric Products

Rod & Guided Rod Style Actuators, High Force Actuators, Screw & Belt Drive Rodless Actuators, Motors, Drives and Controllers

"Foldout" Brochure #9900-9074





Pneumatic Products

Rodless Cylinders: Band Cylinders, Cable Cylinders, Magnetically Coupled Cylinders/Slides; Guided Rod Cylinder Slides

"Foldout" Brochure #9900-9075



Power Transmission Products Gearboxes: Float-A-Shaft[®], Slide-Rite[®]; Disc Cone Clutch; Caliper Disc Brakes

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