







 ← A105			Type DHSUHH							
			65	75	85	95	110	125	140	
 d Ø max	1	mm	85	95	110	125	140	160	180	
	 Tn 1m Tp	2.1	Nm	6500	10000	14500	20000	26500	36000	55000
 /min.max.		3	tr/min omw/min rpm min <sup>-1</sup>	21000	19000	17000	15000	14000	12000	10000
	 ΔK <sub>w</sub>	12	degré graad degree grad	2x0,25	2x0,25	2x0,25	2x0,25	2x0,25	2x0,25	2x0,25
 ΔK <sub>a</sub>		12	mm: ±	3,6	3,6	3,6	4	4	4	8
	 J <sub>G</sub> (WR <sup>2</sup> ) je	4	kgm <sup>2</sup>	0,090	0,168	0,328	0,509	0,919	1,6	2,8
 P <sub>G</sub> pe		5	kg	21,2	30,2	46,4	57,4	84,5	115	164
	 R <sub>G</sub> Re	Nm/rad Nm/rad <sub>(per m)</sub>	1206700	1986000	2552900	3886100	5002500	6847400	10433600	
274000			496000	742000	1237000	1683000	2680000	4711000		
mm: ±	A	11	mm	340	370	420	470	550	600	650
	B		mm	170	196	222	248	273	307	344
	D		mm	119	133	154	175	196	224	252
	E		mm	60	75	85	95	110	125	140
	G	11	mm	220	220	250	280	330	350	370
	K		mm	94	111	123	142	158	180	202
	L		mm	103	121	134	154	170	193	218

J<sub>G</sub>, P<sub>G</sub> and R<sub>G</sub> are respectively the coupling inertia, weight and torsional stiffness for minimum D.B.S.E. : G.  
For others D.B.S.E.s : J<sub>e</sub>, P<sub>e</sub> and R<sub>e</sub> are additional spacer tube inertia, weight and torsional stiffness per meter.

**If D.B.S.E. > G:**

$$\Rightarrow R_g = \frac{R_{ge} \cdot R_e \cdot 1000}{1 \cdot R_{ge} + R_e \cdot 1000}$$

$$\Rightarrow J = J_g + j_e \cdot \frac{l}{1000}$$

$$\Rightarrow P = P_g + p_e \cdot \frac{l}{1000}$$

with l = DBSE-G (DBSE) = (mm)

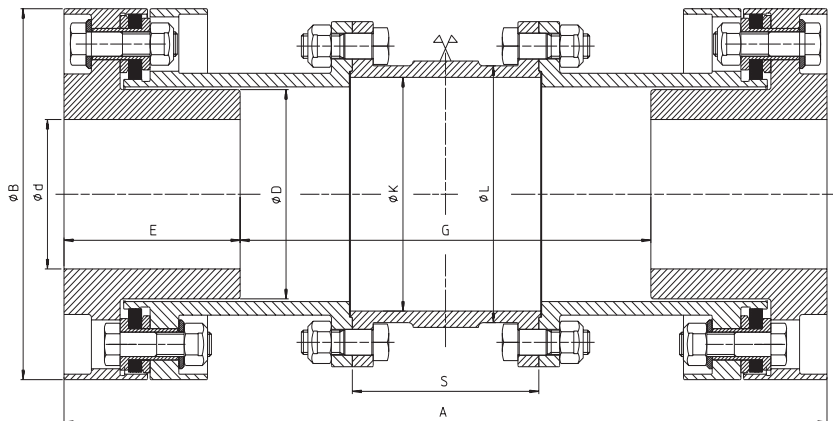
**Example: DHSUHH 95, D.B.S.E. = 350 mm**

$$\Rightarrow l = 70 \text{ mm}$$

$$\Rightarrow R_g = \frac{3886100 \cdot 1237000 \cdot 1000}{70 \cdot 3886100 + 1237000 \cdot 1000} = 3185566 \text{ Nm/rad}$$

$$\Rightarrow J = 0,509 + 0,119 \cdot \frac{70}{1000} = 0,517 \text{ kgm}^2$$

$$\Rightarrow P = 57,4 + 22 \cdot \frac{70}{1000} = 58,9 \text{ kg}$$



← A105			Type DHSURR							
			65	75	85	95	110	125	140	
	1	mm	65	75	85	95	110	125	140	
	2.1	Nm	6500	10000	14500	20000	26500	36000	55000	
			8500	13000	19000	25500	38000	48000	72000	
	3	tr/min omw/min rpm min <sup>-1</sup>	21000	19000	17000	15000	14000	12000	10000	
	12	degré graad degree grad	2x0,25	2x0,25	2x0,25	2x0,25	2x0,25	2x0,25	2x0,25	
	12	mm: ±	3,6	3,6	3,6	4	4	4	8	
	4	kgm <sup>2</sup>	0,075	0,137	0,270	0,418	0,767	1,257	2,133	
		kgm <sup>2</sup> (per m)	0,027	0,051	0,079	0,130	0,190	0,284	0,487	
	5	kg	22	28	43	55	78	102	143	
		kg (per m)	9	12	15	20	23	26	37	
		Nm/rad	848600	1218100	1642800	2250000	3795700	5204800	7315000	
		Nm/rad <sub>(per m)</sub>	455000	871000	1358000	2155000	3180000	4800000	7975000	
mm: ±	A	11	mm	360	470	540	575	585	620	700
	B		mm	170	196	222	248	273	307	344
	D		mm	91	105	119	133	154	175	196
	E		mm	75	100	120	130	135	150	175
	G	11	mm	210	270	300	315	315	320	350
	K		mm	105	124	144	157	179	198	223
	L		mm	112	132	152	167	189	209	236
	S		mm	80	106	128	135	143	160	190

$J_G$ ,  $P_G$  and  $R_{G_0}$  are respectively the coupling inertia, weight and torsional stiffness for minimum D.B.S.E. : G.  
For others D.B.S.E.s :  $J_e$ ,  $P_e$  and  $R_{G_e}$  are additional spacer tube inertia, weight and torsional stiffness per meter.

**If D.B.S.E. > G:**

$$\Rightarrow R_g = \frac{R_{G_0} \cdot R_e \cdot 1000}{1 \cdot R_{G_0} + R_e \cdot 1000}$$

$$\Rightarrow J = J_G + j_e \cdot \frac{l}{1000}$$

$$\Rightarrow P = P_G + p_e \cdot \frac{l}{1000}$$

with  $l = \text{DBSE} - G$  (DBSE) = (mm)

**Example:** DHSURR 95, D.B.S.E. = 385 mm  
 $\Rightarrow l = 70$  mm  
 $\Rightarrow R_g = \frac{2250000 \cdot 2155000 \cdot 1000}{70 \cdot 2250000 + 2155000 \cdot 1000} = 2096757$  Nm/rad  
 $\Rightarrow J = 0,418 + 0,13 \cdot \frac{70}{1000} = 0,427$  kgm<sup>2</sup>  
 $\Rightarrow P = 55 + 20 \cdot \frac{70}{1000} = 56,4$  kg