

The ROSA[®] Knee System 2024 Clinical Evidence Summary

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Introduction

A report from the Agency for Healthcare Research and Quality has demonstrated that knee arthroplasty is one of the most frequent procedures in the operating room¹. The success of total knee arthroplasty (TKA) is well-established, and the most recent Australian and UK registry reports demonstrate 10- and 15-year cumulative percent revision (CPR) rates of 4.6% - 6.1% and 3.87% - 5.49%, respectively, for primary total knee arthroplasty associated with osteoarthritis.^{2,3}

Despite its success, TKA continues to experience revisions related to aseptic failures, with loosening and instability the predominant reasons^{4,5}. Technological advances attempt to address this, but the value of these technologies remains controversial. The reasons for controversy are due primarily to the lack of long-term outcomes and survivorship data^{6,7}. Kort et al. noted that benefits of robotic TKA include improved component positioning, but demonstrating improvements in outcomes, satisfaction, and survivorship is lacking⁷. Still, early outcomes are promising and Mullaji and Khalifa recently reported superior early functional outcomes when reviewing contemporary literature on robotic-assisted TKA⁸. Recently, Guo and colleagues analyzed over 17,000 cases from the American College of Surgeons National Surgical Quality Improvement Program (NSQIP) database and reported robotic-assisted patients experienced better early post-operative functional status, fewer complications, and improved modified frailty index scores, suggesting that robotic-assisted TKA leads to better joint function, mobility, and recovery⁹.

A valuable source of real-world data in orthopedics has been the use of well-established registries^{10,11}. Graves noted the value of registries is their unique ability to provide comparative data¹⁰. Additionally, data from registries have been shown to stipulate change in some orthopedic practices. Reviewing the 2024 annual report of the Australian Orthopaedic Association National Joint Replacement Registry (AOANJRR), the data suggests

that robotic knee arthroplasty is reducing the CPR rates of primary TKA at two to four years post-operatively³. The registry reports CPR rates of robotically assisted TKA at 1.9% (95% CI, 1.7%, 2.0%) compared to 2.2% (95% CI, 2.1%, 2.3%) for non-technology-assisted at three-years follow-up. At five-years, the difference in CPT rates between robotic-assisted and non-technology-assisted were 2.3% (95% CI, 2.1%, 2.5%) versus 2.8% (95% CI, 2.8%, 2.9%), respectively (see AOANJRR 2024 Annual Report Table KT60). Although these differences were no longer significant after adjusting for covariates, there were differences in revisions between robotic and non-technology-assisted for aseptic causes of loosening and instability (see AOANJRR 2024 Annual Report Figure KT62)³.

The ROSA[®] Knee System is a semi-autonomous robotic arm that assists in the placement of the cutting jig along with providing ligament laxity assessments throughout the primary TKA workflow. It can be used with image-based or imageless modes¹². The primary purpose of this review was to identify and summarize the literature associated with the ROSA Knee System in relation to accuracy, efficiencies, and outcomes.

Accuracy

There has been a plethora of publications on the ROSA Knee System supporting improved accuracy and precision compared to conventional instrumentation (Tables 1-2)¹³⁻²¹. In vivo studies^{18,20,22-24} have supported the initial findings of cadaveric studies^{16,25}. Wininger et al.²⁶ demonstrated fewer outliers and improved accuracy over manual instrumentation in patients with severe pre-operative valgus deformities. Rossi et al.²⁷ reported reliable and accurate radiographic outcomes in patients with either severe varus or valgus deformities. In addition to the comparative studies, several other publications support the system being accurate and precise (Tables 1-2)^{22,23,28-33} with no discernable learning curve regarding accuracy reported by Bolam et al.³⁴, Petrillo et al.³², and Thongpulsawad et al.³⁵

Table 1. The ROSA Knee System is more accurate and precise in achieving the planned coronal plane alignment (Hip-Knee-Ankle Angle) than conventional TKA.

	% outside of Target				Deviation from target, mean \pm SD		
	Target	Robotic	Conventional	P value	Robotic	Conventional	P value
Schrednitzki ¹⁵	$\pm 3^\circ$	0/71 (0%)	75/308 (24.3%)	<0.001	$1.01^\circ \pm 0.08^\circ$	$2.05^\circ \pm 0.11^\circ$	<0.001
Hasegawa ²²	$\pm 3^\circ$	0/36 (0%)	NA	NA	0.6°	NA	NA
Shin ²⁹	$\pm 3^\circ$	4/37 (11%)	NA	NA	NA	NA	NA
Parratte ¹⁴	$\pm 5^\circ$	4 (10%)	8 (20%)	>0.05	NA	NA	NA
Vanlommel ¹⁷	$\pm 3^\circ$	3/58 (5.2%)	19/79 (24.1%)	0.003	NA	NA	NA
Rossi ²³	$\pm 3^\circ$	NA	NA	NA	$1.2^\circ \pm 1.1^\circ$	NA	NA
Batailler ¹³	$\pm 5^\circ$	2/40 (5%)	12/40 (30%)	0.003	NA	NA	NA
Seidenstein ¹⁶	$\pm 3^\circ$	0/14 (0%)	5/20 (25%)	NA	$0.8^\circ \pm 0.6^\circ$	$2.0^\circ \pm 1.6^\circ$	0.004
Parratte ²⁵	$\pm 3^\circ$	0/30 (0%)	NA	NA	$-0.03^\circ \pm 0.87^\circ$	NA	NA
Mancino ³⁶	$\pm 1^\circ$	41/86 (47.4%)	70/86 (81.4%)	<0.05	$1.3^\circ \pm 1.3^\circ$	$1.9^\circ \pm 1.2^\circ$	<0.001
Wininger ²⁶	$\pm 2^\circ$	44/103 (42.7%)	48/103 (46.6%)	>0.05	$2.2^\circ \pm 0.39^\circ$	$2.25^\circ \pm 0.35^\circ$	>0.05
Rajgopal ²⁰	$\pm 3^\circ$	0/135 (0%)	5/135 (3.7%)	0.024	NA	NA	NA
Nogalo ²¹	$\pm 3^\circ$	4/30 (13.3%)	14/67 (20.9%)	>0.05	NA	NA	NA

An important aspect of all robotic systems is the ability to accurately register the landmarks and conduct a dynamic assessment. Charette et al. reported that the ROSA Knee System had excellent inter- and intra-rater reliability for both activities, and the reliability was consistent whether or not image-based planning was used³⁷. In this cadaveric study, they also reported no difference in the ability of a resident, an arthroplasty fellow, or a fellowship-trained arthroplasty surgeon to accurately perform the registration of landmarks and evaluate the soft tissue laxity. The ROSA Knee System also improves the accuracy of low-volume surgeons. Byrne et al.¹⁸ recently reported fewer coronal tibial outliers and cases of notching compared to conventional instrumentation by a non-orthopedic trained, low-volume surgeon.

Three recent studies published in 2024 directly compared the ROSA Knee System to other commercially available robotic-assisted TKA systems. Hasegawa et al.³¹ reported no differences in mean absolute errors (planned vs. post-operative radiographically measured) between Navio™ (Smith & Nephew, Memphis, TN, USA) and ROSA Knee for coronal femoral and tibial angles nor sagittal femoral and tibial angles. Rajgor et al.³⁸ reported no differences between MAKO® total knee robotic arm-assisted surgery (Stryker, Kalamazoo, Michigan, USA) and the ROSA Knee System for restoration of joint line height, tibial slope, patella height, or posterior condylar offset. Similarly, Zhou et al.³⁹ demonstrated no differences in mean absolute error and percentage of outliers (>3°) between MAKO and ROSA Knee for coronal femoral and tibial angles nor sagittal femoral and tibial angles.

Table 2. The ROSA Knee System is accurate and precise in achieving the planned tibial and femoral angles. Absolute Mean Errors from planned angles \pm Standard Deviations (% > $\pm 3^\circ$), unless otherwise indicated.

	Comparison Type	Coronal Angles		Sagittal Angles	
		Femur	Tibia	Femur	Tibia
Hasegawa ²²	Post-Operative CT Scans	$0.80^\circ \pm 0.67^\circ$ (0%)	$1.14^\circ \pm 0.77^\circ$ (0%)	$2.18^\circ \pm 1.19^\circ$ (16%)	$1.05^\circ \pm 0.96^\circ$ (3%)
Hasegawa ²²	Post-Operative Radiographs	$0.46^\circ \pm 0.70^\circ$ (0%)	$0.46^\circ \pm 0.57^\circ$ (0%)	$1.28^\circ \pm 0.81^\circ$ (0%)	$0.83^\circ \pm 0.56^\circ$ (0%)
Shin ²⁹	Post-Operative Radiographs	$0.88^\circ \pm 0.71^\circ$ (0%)	$1.24^\circ \pm 1.06^\circ$ (8%)	$1.93^\circ \pm 1.03^\circ$ (17%)*	$2.04^\circ \pm 1.55^\circ$ (26%)*
Parratte ¹⁴	Post-Operative Radiographs	(2.5%)	(2.5%)	NA	(0%)
Vanlommel ¹⁷	Intra-operative Validation	$0.32^\circ \pm 0.25^\circ$	$0.46^\circ \pm 0.32^\circ$	$0.40^\circ \pm 0.34^\circ$	$0.89^\circ \pm 0.74^\circ$
Rossi ²³	Intra-operative Validation	$0.5^\circ \pm 0.6^\circ$	$0.7^\circ \pm 0.9^\circ$	$0.8^\circ \pm 0.8^\circ$	$0.5^\circ \pm 0.6^\circ$
Rossi ²³	Post-Operative Radiographs	$0.6^\circ \pm 0.5^\circ$	$0.3^\circ \pm 1.8^\circ$	$0.1^\circ \pm 1.2^\circ$	$0.03^\circ \pm 1.9^\circ$

Seidenstein ¹⁶	Intra-operative Validation	0.5° ± 0.4° (0%)	0.6° ± 0.4°	1.3° ± 1.0° (7.1%)	0.6° ± 0.4° (0%)
Parratte ^{25†}	Intra-operative Validation	0.03° ± 0.51° (0%)	-0.6° ± 0.69° (0%)	-0.95° ± 0.9° (3%)	0.2° ± 0.84° (0%)
Mancino ³⁶	Post-Operative Radiographs	1.3° ± 0.9°	0.8° ± 0.5°	0.9° ± 0.8°	0.9° ± 0.7°
Winninger ²⁶	Post-Operative Radiographs	NA	1.78° ± 0.26°	NA	NA
Byrne ¹⁸	Post-Operative Radiographs	NA	(10.1%)	NA	(0%, >5°)
Hasegawa ³¹	Post-Operative Radiographs	0.47° ± 0.65°	0.59° ± 1.35°	1.11° ± 0.75°	0.90° ± 0.59°
Hax ¹⁹	Post-Operative Radiographs	(0%)	(22%)	(2%)	(15%)
Nogalo ²¹	Post-Operative Radiographs	(0%)	(0%)	NA	NA
Thongpulsawad ³⁵	Intra-Operative Validation	0.1° ± 0.6	0.2° ± 0.7°	0.4° ± 2.4°	0.2° ± 0.7°
Zaidi ³⁹	Post-Operative Radiographs	0.61° ± 0.97°	0.61° ± 1.26°	1.87° ± 1.11°	0.75° ± 1.34°
Zaidi ³³	Post-Operative Radiographs	1.62° ± 1.11°	1.44° ± 1.03°	1.39° ± 1.05°	0.99° ± 0.72°
Zhou ³⁹	Post-Operative Radiographs	1.8° ± 1.7° (25%)	1.3° ± 1.1° (5%)	NA	1.4° ± 0.9° (10%)

* Percentages updated per author's response to [Letter to the Editor](#). † reported as actual mean ± Standard deviation

Efficiency

The adoption of robotics in arthroplasty is unique to each surgeon and practice. Some have reported that the decision to incorporate this system came down to their “desire to improve healthcare quality and outcomes and provide value in our practice”⁴⁰. They report reviewing their data with hopes to support or refute this claim. In describing his personal journey through robotics, Lonner reported his decision to adopt the ROSA Knee System was due to the potential for this system to optimize surgical efficiencies, precision, and improve ergonomics⁴¹.

The surgical workflow has been described in several papers^{12,25,28,42}. Alessi et al. noted the diverse abilities of the system when performing primary TKA and reported that it can be used for either gap balancing or measured resection techniques²⁸. The robotic system is intended to work alongside the surgeon without excessively sacrificing autonomy^{12,42}. Batailler et al. also noted that, along with measured resection or gap balancing, surgical philosophy for alignment is left to surgeon preference^{12,43}.

Upon adoption of the system, Haffar et al. evaluated the ergonomic effects of the system compared to conventional instrumentation⁴⁴. Specifically, they evaluated cardiorespiratory and ergonomic data of the operating surgeon in 20 consecutive robotic cases compared to 20 consecutive conventional cases. Ultimately, they reported less surgeon physiological stress, energy expenditure, and postural strain with the robotic system compared to conventional instrumentation.

The ROSA Knee System has also been reported to have a relatively rapid learning curve for operative times, with similar complication rates as conventional instrumentation^{17,32,34,35}. Polikandriotis and Cafferky described early cases following adoption taking as long as 30 minutes more than conventional⁴⁰. However, they noted that after 10 robotic-assisted cases, surgical times were consistent with conventional cases, requiring approximately 45-60 minutes. When evaluating the learning curves specifically, multiple studies have reported learning curves ranging from 5-15 cases^{17,32,34,35}.

Of interest to the orthopedic surgeon and healthcare administrators is the ability to achieve time neutrality compared to conventional instrumentation when adopting new technologies. Bolem et al. reported no differences in operative times between robotic and conventional TKA³⁴. In contrast, other studies have reported increased operative times with robotic-assisted TKA^{13,17,43}. Kenanidis et al. demonstrated an equilibrium in operative time between robotic-assisted TKA and conventional TKA occurs after approximately 70 cases.⁴⁵ Niera et al.⁴⁶ reported no differences in operative times between robotic-assisted and conventional TKA in experienced surgeons during the proficiency phase. Recently, Ejnisman et al.⁴⁷ reported robotic-assisted operative times were less than conventional TKA after 30 cases in high-volume surgeons. The reduction in operative time appears to be most driven by improved efficiency in surgical planning and joint balancing³⁵. In direct comparison to other

robotic systems, the ROSA Knee System was found to have a significantly shorter operative time compared to MAKO total knee (94.8 ± 23.0 vs. 112.7 ± 12.8 min)³⁹. Further studies are needed to determine if improved efficiency is associated with speed of adoption or related to individual surgeon and center workflows. Additionally, the evaluation of total operating room time between robotic and non-robotic cases is needed.

The ability to use plain radiographs for pre-operative planning, or no imaging at all, removes the patient, administrative, and potentially cost burden, of ordering more advanced imaging. Image-based cases are accomplished with the use of the X-Atlas® 2D to 3D Technology (Zimmer CAS, Montreal, Quebec, CA). Massé and Ghate described this process and evaluated the accuracy of this system, concluding that the imaging technology can accurately reconstruct a three-dimensional bone model from two-dimensional, pre-operative, orthogonal, long-leg radiographs⁴⁸. Using this imaging technology, Klag et al. reported improved accuracy of implant size prediction compared to pre-operative templating on two-dimensional films alone⁴⁹. Additionally, the use of plain film radiographs results in less radiation exposure to the patient compared to CT imaging used in other robotic systems^{50,51}. This amount is not negligible, as CT scans of the knee for pre-operative planning have been shown to provide similar radiation doses as approximately 48 chest X-rays⁵².

Outcomes

Outcome data surrounding this relatively new system is limited, but positive. Kenanidis et al. reported no difference between robotic-assisted TKA and conventional instrumentation in patient-reported outcome measures (PROMs) and overall satisfaction of the knee at the three-month follow-up⁵³. However, at six months, the robotic-assisted TKA group had higher Forgotten Joint and Oxford Knee scores, less pain, and more patients indicated they would undergo the procedure again (Table 3). Parratte et al. demonstrated improvements in the Knee Society Knee and Function scores at six months in the robotic group (Table 3)¹⁴, and Batailler et al. reported improved six-month Knee Society function compared to conventional TKA¹³. Similarly, Wininger et al.²⁶ reported greater three- and six-month National Institutes of Health Patient-Reported Outcomes Measurement Information System (PROMIS) scores in a high volume surgeon performing robotic-assisted compared to a separate high volume surgeon performing only conventional TKA.

Recently, Hax et al.¹⁹ reported greater six-month Oxford Knee Scores with robotic-assisted compared to conventional TKA. The authors also demonstrated a trend

toward greater improvements in Core Outcome Measures Index (COMI)-knee scores with robotic assistance, however, the authors reported that the changes were not statistically different between groups. In another recent study, Zhang et al. reported greater Knee Society Function scores and a trend for higher Oxford Knee Scores with robotic-assisted TKA at six-months post-operative when compared to all conventional TKA patients in the cohort. These differences were no longer significant following propensity matching, however, as the authors highlight, the study was underpowered to detect statistical differences. These findings provide additional evidence to support accelerated functional recovery with robotic-assisted TKA, as the ceiling effect for the PROMIS has been reported to be as low as 0.2%⁵⁴ compared to 18-22% for the KOOS JR⁵⁵. At 12-month follow-up, Mancino et al. reported higher post-operative Knee Society Knee and Function Scores in robotic-assisted TKA compared to navigation-assisted TKA without differences in other PROMs evaluated⁴³.

Mancino et al. noted both higher maximum range of motion (ROM) post-operatively and greater changes in ROM in the robotic-assisted group⁴³. The ROM at one-year was reported as least square (LS) means and was 119.4° (95% Confidence interval [CI], $116.54^\circ - 122.35^\circ$) for robotic TKA compared to 107.1° (95% CI, $103.47^\circ - 110.64^\circ$) in the control. This represents a LS mean difference of 12.39° ($7.77-17.01^\circ$, $p < .0001$). This difference is associated with a minimal clinically important difference as reported by Wilson et al.⁵⁶. They also reported a greater improvement in the arc of motion by 11.67° (95% CI $7.36^\circ - 15.7^\circ$, $p < 0.001$). Fary et al. have also reported on improved early ROM in robotic vs conventional with an increase of 5.1° more at one month in the robotic group and a significant odds ratio of 2.17 in the robotic group to achieve at least 90° of flexion by one month post-operative^{57,58}.

Kenanidis et al. reported no complications in either group (Table 4); however, the sample size was likely too small to detect a real difference if any were actually present⁵³. Both Mancino et al. and Parratte et al. reported minimal complications between robotic-assisted and their controls (Table 4)^{14,43}. In their learning curve analysis, Vanlommel et al. also noted minimal complications between robotic-assisted and conventional (Table 4)¹⁷ and Hax et al.¹⁹ also reported no difference in complications between robotic-assisted and conventional TKA. Fary et al. reported fewer wound complications and a non-significant trend ($p=0.08$) for less stiffness in the robotic group⁵⁷. Rajgopal et al. 20 observed 50% less blood loss with robotic-assisted TKA, and attributed this to the need to breach in the intramedullary canal with conventional TKA. Importantly, Woelfle et al.⁶² reported significantly

Table 3. Improved PROMS in ROSA Knee System vs. controls, summarized using mean \pm standard deviation unless otherwise indicated.

	Robotic	Conventional	P value
Kenanidis⁵³			
Forgotten Joint Score (6 months)	71.6 \pm 8.3	61.9 \pm 8.1	<0.001
Oxford Knee Score (3 months)	27.2 \pm 3.0	25.9 \pm 3.3	0.123
Oxford Knee Score (6 months)	37.8 \pm 3.8	34.8 \pm 4.0	0.006
Post-operative VAS (3 months)	3.0 \pm 2.0	3.5 \pm 3.0	0.175
Post-operative VAS* (6 months)	1 \pm 2	2 \pm 2	0.025
Would undergo operation again? [†]	30/30	26/30	0.038
Mancino⁴³			
Knee Society Knee Score (12 months)	84.5 \pm 10.7	70.4 \pm 14	<0.001
Knee Society Functional Score (12 months)	86.4 \pm 12.9	70.5 \pm 16.9	<0.001
Parratte¹⁴			
Knee Society functional score (6 months)	83.7 \pm 15	73.3 \pm 15	0.008
Improvement in Knee Society knee score (6 months)	59.3 \pm 11.9	49.3 \pm 9.7	0.003
Improvement in Knee Society functional score (12 months)	48 \pm 26	29.5 \pm 20	0.004
Batailler¹³			
Knee Society functional score (6 months)	93.3 \pm 7.6	80.7 \pm 8.7	<0.001
Kahn⁵⁹			
KOOS JR (4-6 weeks)	63.1 \pm 16.9	59.0 \pm 15.7	0.035
KOOS JR (6 months)	73.6 \pm 16.6	74.3 \pm 14.8	0.754
KOOS JR (12 months)	77.8 \pm 17.1	74.3 \pm 17.9	0.014
Improvement in KOOS JR (4-6 weeks)	19.9 \pm 18.7	14.0 \pm 16.1	0.020
Improvement in KOOS JR (6 months)	28.7 \pm 18.5	27.8 \pm 17.6	0.650
Improvement in KOOS JR (12 months)	29.8 \pm 19.7	28.2 \pm 21.3	0.385
Fary⁴⁷			
Active Flexion ROM§ (1 month)	106.3 (0.82)	101.2 (0.82)	<0.001
Active Flexion ROM§ (3 months)	119.9 (0.95)	116.0 (0.82)	0.021
KOOS JR (3 months)	68.9 \pm 12.6	70.5 \pm 13.2	0.229
KOOS JR (6 months)	74.0 \pm 14.1	74.6 \pm 13.5	0.673
KOOS JR (12 months)	78.6 \pm 13.6	79.5 \pm 15.7	0.658
Wininger^{€26}			
KOOS JR (3 months)	67.5 \pm 2.5	64.5 \pm 3.5	>0.05
KOOS JR (6 months)	67.5 \pm 2.5	67.5 \pm 2.0	>0.05
PROMIS Physical (3 months)	50 \pm 1.8	46.75 \pm 1.8	0.016
PROMIS Physical (6 months)	52.3 \pm 1.7	47.75 \pm 1.3	0.001
Zhang⁶⁰			
Knee Society Knee Score (6 months, unmatched cohort)	80.9 \pm 12.3	83.3 \pm 13.8	0.122
Knee Society Knee Score (6 months, matched cohort)	80.9 \pm 12.3	85.1 \pm 13.7	0.059
Knee Society Function score (6 months, unmatched cohort)	76.3 \pm 16.3	67.2 \pm 22.9	0.026
Knee Society Function score (6 months, matched cohort)	76.3 \pm 16.3	68.2 \pm 22.4	0.083
Oxford Knee Score (6 months, unmatched cohort)	19.1 \pm 6.7	21.0 \pm 7.0	0.083
Oxford Knee Score (6 months, matched cohort)	19.1 \pm 6.7	20.1 \pm 6.73	0.602
SF36-Physical Component (6 months, unmatched cohort)	46.6 \pm 9.09	44.8 \pm 10.2	0.389
SF36-Physical Component (6 months, unmatched cohort)	46.6 \pm 9.09	46.3 \pm 10.1	0.900

Ratti ⁶¹	Utility Value (based off WOMAC, 1 year)	0.71 ± 0.11	0.78 ± 0.11	0.001
	Utility Value (based off WOMAC, 2 year)	0.78 ± 0.22	0.78 ± 0.19	0.979
Rajgopal ²⁰	Knee Society Knee Score (3 months)	86.7	86.7	>0.05
	Knee Society Knee Score (6 months)	89.9	89.9	>0.05
	Knee Society Knee Score (12 months)	89.9	89.9	>0.05
Ejnisman ⁴⁷	KOOS-PS* (90 days)	61.4 (13.85)	63 (16.4)	0.282
	EQ-5D* (90 day)	0.79 (0.12)	0.79 (0.31)	0.491
	EQ-VAS* (90 day)	80 (15)	80 (20)	0.091

*values given as median and (interquartile range)

‡ values presented as fractions with “yes” as numerator and total sample size for the cohort as the denominator.

§ values presented as mean and standard error

€ Values derived from Figure 2

fewer tibial component revisions in cementless robotic-assisted TKA compared to conventional controls.

Conclusion

Multiple studies support the ability of the ROSA Knee System to assist the surgeon accurately and reliably in placing the cutting guide and achieving the planned cut angles and resections^{13-16,20,22-25,29,33,35,36,39}. The system has been shown to be easily incorporated into the surgical

workflow, with a rapid initial learning curve^{17,28,32,34,35,40,47}. The flexibility of the system allows for a variety of surgical techniques,^{12,27,28,42,63-67} and has been shown to reduce surgeon stress compared to conventional instrumentation⁴⁴. Additionally, patient and administrative burdens of obtaining advanced imaging are unnecessary, and radiation exposure is minimized^{41,50,51}. Early studies have demonstrated improved outcomes, including PROMs, ROM, pain and satisfaction, with minimal

Table 4. Complications present post-operatively

	Robotic	Control, n (%)	P value
Kenanidis ⁵³			
Complications and readmissions	0 (0%)	0 (0%)	NA
Mancino ⁴³			
Revision TKA	0 (0%)	2 (4.26%)	0.232
Infection	1 (2%)	2 (4.26%)	>0.99
Aseptic Loosening	0 (0%)	1 (2.13%)	0.485
Reoperations	1 (2%)	3 (6.38%)	0.191
DAIR*	1 (2%)	1 (2.13%)	>0.99
Wound Complication	2 (4%)	4 (8.7%)	0.426
Parratte ¹⁴			
DAIR*	1 (2.5%)	0 (0%)	NA
Traumatic Distal Femoral Fracture	0 (0%)	1 (2.5%)	NA
Vanlommel ¹⁷			
Arthrofibrosis	2 (2.2%)	1 (1.1%)	NA
Surgical site infection	1 (1.1%)	3 (3.3%)	NA
Deep vein thrombosis	1 (1.1%)	0 (0%)	NA
Periprosthetic joint infection	0 (0%)	1 (1.1%)	NA

Fary ⁵⁷			
Deep Knee Infection	2 (0.9%)	2 (0.9%)	NA
Stiffness	13 (6.0%)	23 (10.6%)	0.082
Pain	6 (2.8%)	13 (6.0%)	0.101
Wound Complications	6 (2.8%)	18 (8.3%)	0.023
Other Knee Related AE	15 (6.9%)	13 (6.0%)	0.696
Revision TKA	1 (0.5%)	4 (1.8%)	0.562
Manipulation Under Anesthesia	5 (2.3%)	10 (4.6%)	0.190
Woefle ⁶²			
Aseptic Loosening (tibial implant)	0 (0%)	4 (6.6%)	0.038
Hax ¹⁹			
Infection	1 (1.8%)	0 (0%)	0.999
Vascular, neural, or soft tissue	0 (0%)	1 (1.8%)	0.999
Stiffness	3 (5.5%)	3 (5.5%)	1.000
Rajgopal ²⁰			
Blood loss (ml)	206.7 ± 80.9	413.9 ± 128.4	<0.001

*DAIR: debridement antibiotics and implant retention

complications during the immediate (4-12 weeks) and early (6 - 12 months) post-operative period^{13,14,17,20,26,43,53,57,60,62}. In addition to the current potential values seen in these studies, there is also added value in the data provided by this robotic system. Lonner et al. recently demonstrated the ability to connect the intra-operative data provided by the ROSA Knee System with post-operative step counts and PROMs data in a commercial system⁶⁸. They reported associations with the degree of intra-operative laxity decisions and patient recovery outcomes. This information may be used to guide future care; however, the authors recommend more robust investigations be performed prior to making surgical decisions based on the current data.

This review summarizes the value of the ROSA Knee System and its ability to:

- Improve component positioning
- Improve early patient outcomes
- Decrease radiation exposure

In addition, the intra-operative data collected has the potential to change practice as more data is evaluated and used to better understand the intricacies of intra-operative decisions. The long-term outcomes and survivorship of TKA using the ROSA Knee System are yet to be determined, but the addition of this technology to assist in TKA procedures has been shown to have both patient and surgeon benefits.

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